

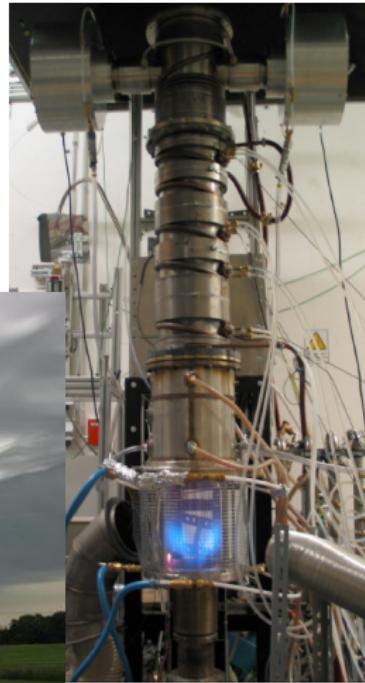
Towards a Semi-Implicit All Froude Number Godunov-type Method for Shallow Water Flows

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12th Int. Conference on Hyperbolic Problems
June, 12th 2008

Motivation



Outline

1 Geophysical Flows

- Governing Equations
- Numerical Difficulties

2 Projection Method for Incompressible Flows

- General Idea
- Spatial Discretization
- Stability of the Projection Step

3 Weakly Compressible Flows

- Formulation of the Scheme
- Numerical Results

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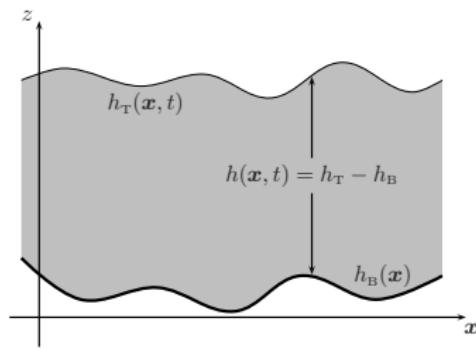
The Shallow Water Equations

Non-dimensional form:

$$h_t + \nabla \cdot (h\mathbf{v}) = 0$$

$$(h\mathbf{v})_t + \nabla \cdot (h\mathbf{v} \circ \mathbf{v}) + \frac{1}{Fr^2} \nabla p = -\frac{1}{Fr^2} h \nabla h_B$$

$$p = \frac{h^2}{2}$$



- $Fr = \frac{v'_{ref}}{\sqrt{g' h'_{ref}}}$
- hyperbolic system of conservation laws
- similar to Euler equations, no energy equation

Zero Froude Number (“Incompressible”) Limit

Limit Equations:

$$\begin{aligned} h_t + \nabla \cdot (h\mathbf{v}) &= 0 \\ (h\mathbf{v})_t + \nabla \cdot (h\mathbf{v} \circ \mathbf{v}) + h\nabla h^{(2)} &= \mathbf{0} \end{aligned}$$

- $h = h_0(t)$ given through boundary conditions
- **divergence constraint** for velocity field:

$$\int_{\partial V} h\mathbf{v} \cdot \mathbf{n} \, d\sigma = -|V| \frac{dh_0}{dt} \quad \text{for } V \subset \Omega$$

- $h^{(2)}$: Lagrange multiplier; ensures compliance with divergence constraint

Computing Low Froude Number Shallow Water Flows

Arising difficulties:

- spatial height (pressure) variations vanish as $\text{Fr} \rightarrow 0$,
but they do affect the velocity field at leading order
- spatial homogeneity of leading order pressure implies
an elliptic divergence constraint for the mass flux
- eigenvalues of the Jacobian flux matrix $\mathbf{v} \cdot \mathbf{n}$ and $\mathbf{v} \cdot \mathbf{n} \pm \sqrt{h/\text{Fr}}$
become singular
- explicit methods suffer from a Courant-Friedrichs-Lowy time step
restriction with $\delta t \leq \mathcal{O}(\text{Fr})$

Conservative Low Froude Number Numerics

Task: Construct a scheme, which ...

- ... allows time steps **independent of the Froude number**
- ... **conserves** mass, momentum, total energy:

$$\mathbf{U}_V^{n+1} = \mathbf{U}_V^n - \frac{\delta t}{|V|} \sum_{I \in \mathcal{I}_{\partial V}} |I| \mathbf{F}_I$$

- ... is **second order accurate** in time and space
- ... uses machinery of **Godunov-type methods**
- ... requires the solution of at most linear, scalar equations
- ... ensures, that for $\text{Fr} = 0$, advection velocities **and** final momentum satisfy divergence constraint

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Construction of the Projection Method

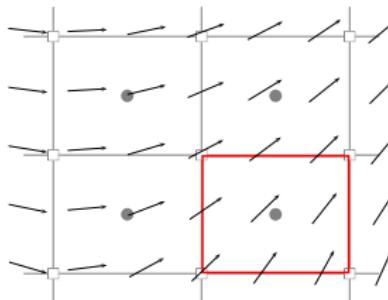
method in conservation form:

$$\mathbf{U}_V^{n+1} = \mathbf{U}_V^n - \frac{\delta t}{|V|} \sum_{I \in \mathcal{I}_{\partial V}} |I| \, \mathbf{F}_I$$

$$\mathbf{F}_I := \mathbf{F}_I^* + \mathbf{F}_I^{\text{MAC}} + \mathbf{F}_I^{\text{P2}}$$

- advective fluxes \mathbf{F}_I^* from second order Godunov-type method (applied to auxiliary system)
- $\mathbf{F}_I^{\text{MAC}}$ from (MAC) projection, which corrects advection velocity divergence
- \mathbf{F}_I^{P2} from second projection, which adjusts new time level divergence of cell-centered velocities

Correction of the Fluxes

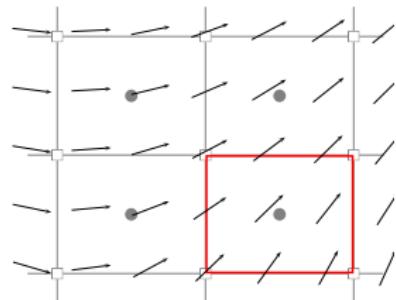


1. (MAC) Projection:

$$(h\mathbf{v})_I = (h\mathbf{v})_I^* - \frac{\delta t}{2} h_0 (\nabla h^{(2)})_I$$

corrects **advective fluxes** on boundary of control volume

Correction of the Fluxes



1. (MAC) Projection:

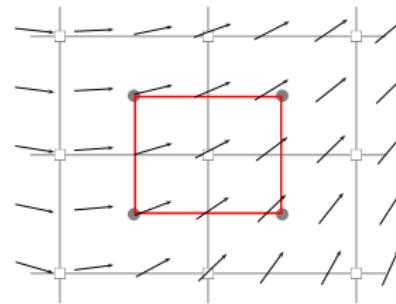
$$(h\mathbf{v})_I = (h\mathbf{v})_I^* - \frac{\delta t}{2} h_0 (\nabla h^{(2)})_I$$

corrects **advective fluxes** on boundary of control volume

2. Projection:

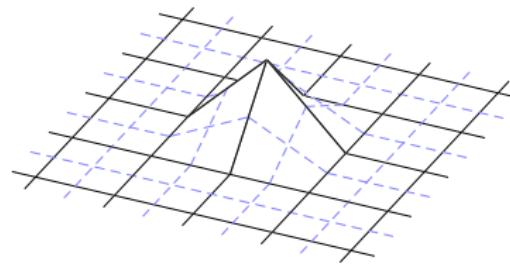
$$(h\mathbf{v})^{n+1} = (h\mathbf{v})^{**} - \delta t (h_0 \nabla h^{(2)})^{n+1/2}$$

adjusts momentum to obtain correct divergence for **new velocity field**



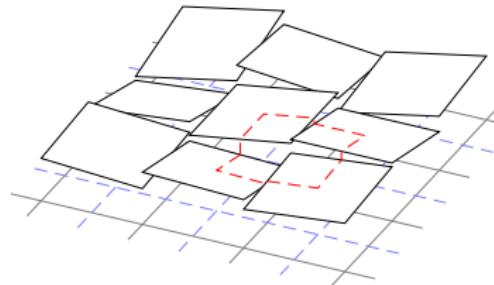
Discretization of the Poisson-Type Problems

Petrov-Galerkin FE discretization [SÜLI, 1991]:



- discrete divergence can be **exactly calculated**
- Laplacian has **compact stencil**
- $L = D(G) \rightsquigarrow$ **exact** projection method

- bilinear trial functions for the unknown $h^{(2)}$
- piecewise constant test functions on the dual discretization



Exact Projection Method

Local updates within each cell V_{ij} :

$$(h\mathbf{v})^{n+1}(x, y) = (h\mathbf{v})^{**}(x, y) - \delta t h_0 \nabla h^{(2)}{}^{n+1/2}(x, y)$$

where

$$\nabla h^{(2)}{}^{n+1/2}(x, y)|_{ij} = \begin{pmatrix} \partial_x h^{(2)} \\ \partial_y h^{(2)} \end{pmatrix}_{ij} + \begin{pmatrix} y - y_j \\ x - x_i \end{pmatrix} \partial_{xy}^2 h_{ij}^{(2)}$$

~ second projection modifies piecewise linear reconstruction:

$$\partial_x(h\mathbf{v})_{ij}^{n+1} = \partial_x(h\mathbf{v})_{ij}^{**} - \delta t h_0 \begin{pmatrix} 0 \\ \partial_{xy}^2 h_{ij}^{(2)} \end{pmatrix}$$

$$\partial_y(h\mathbf{v})_{ij}^{n+1} = \partial_y(h\mathbf{v})_{ij}^{**} - \delta t h_0 \begin{pmatrix} \partial_{xy}^2 h_{ij}^{(2)} \\ 0 \end{pmatrix}$$

Stability of the Projection Step

Derive saddle point problem . . .

$$(h\mathbf{v})^{n+1} = (h\mathbf{v})^{**} - \nabla_h(\delta t h_0 h^{(2)})$$

$$\frac{1}{2} \nabla_h \cdot \left[(h\mathbf{v})^{n+1} + (h\mathbf{v})^n \right] = -\frac{dh_0}{dt}$$

. . . and employ theory of mixed finite elements (Nicolaïdes, 1982):

Theorem (V. & Klein 2007)

The generalized mixed formulation has a unique and stable solution $((h\mathbf{v})^{n+1}, \delta t h_0 h^{(2)})$.

- we obtain approximations, in which the solution of the Poisson problem $h^{(2)}$ and the momentum update $(h\mathbf{v})^{n+1}$ **cannot decouple!**

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Weakly Compressible Flows

mimic Zero Froude Number results by decomposing pressure into two components:

$$p(t, \mathbf{x}; \text{Fr}) = p_0(t) + \text{Fr}^2 p'(t, \mathbf{x})$$

$$h_t + \nabla \cdot (h\mathbf{v}) = 0$$

$$(h\mathbf{v})_t + \nabla \cdot (h\mathbf{v} \circ \mathbf{v}) + \nabla p' = 0$$

$$p = p_0(t) + \text{Fr}^2 p'(t, \mathbf{x}) = \frac{h^2}{2}$$

$$p_t + h\nabla \cdot (h\mathbf{v}) = 0$$

Extension of (zero Froude number) projection method by inclusion of **local time derivatives** of p' into projection steps

Explicit Predictor for Advection

Auxiliar system:

$$h_t + \nabla \cdot (h\mathbf{v}) = 0$$

$$(h\mathbf{v})_t + \nabla \cdot (h\mathbf{v} \circ \mathbf{v}) + \nabla p = -(1 - \text{Fr}^2) \nabla p'^{\text{old}}$$

$$p = \frac{h^2}{2}$$

yields **first order** accurate prediction:

$$(h\mathbf{v})^{n+1/2} = (h\mathbf{v})^{*,n+1/2} + \mathcal{O}(\delta t^2)$$

$$= (h\mathbf{v})^{*,n+1/2} - \frac{\delta t}{2} (1 - \text{Fr}^2) \nabla \delta p' + \mathcal{O}(\delta t^2)$$

$$\delta p' := p'^{n+1} - p'^n$$

First Correction – Advection Fluxes

Pressure equation:

$$\left(\frac{dp_0}{dt} \right)^{n+1/2} + \text{Fr}^2 \left(\frac{\partial p'}{\partial t} \right)^{n+1/2} = -h \nabla \cdot \left((h\mathbf{v})^* - \frac{\delta t}{2} (1 - \text{Fr}^2) \nabla \delta p' \right)$$

Since:

$$\left(\frac{\partial p'}{\partial t} \right)^{n+1/2} = \frac{\delta p'}{\delta t} + \mathcal{O}(\delta t^2)$$

this yields **Helmholtz equation** for $\delta p'$:

$$-\frac{\text{Fr}^2}{\delta t} \delta p' + h^* \frac{\delta t}{2} (1 - \text{Fr}^2) \Delta \delta p' = \left(\frac{dp_0}{dt} \right)^{n+1/2} - \left(\frac{dp^*}{dt} \right)^{n+1/2}$$

Second Correction – Pressure Term

intermediate momentum update:

$$(h\mathbf{v})^{**} := (h\mathbf{v})^n - \delta t \nabla \cdot (h\mathbf{v} \circ \mathbf{v})^{n+1/2}$$

momentum at the new time level:

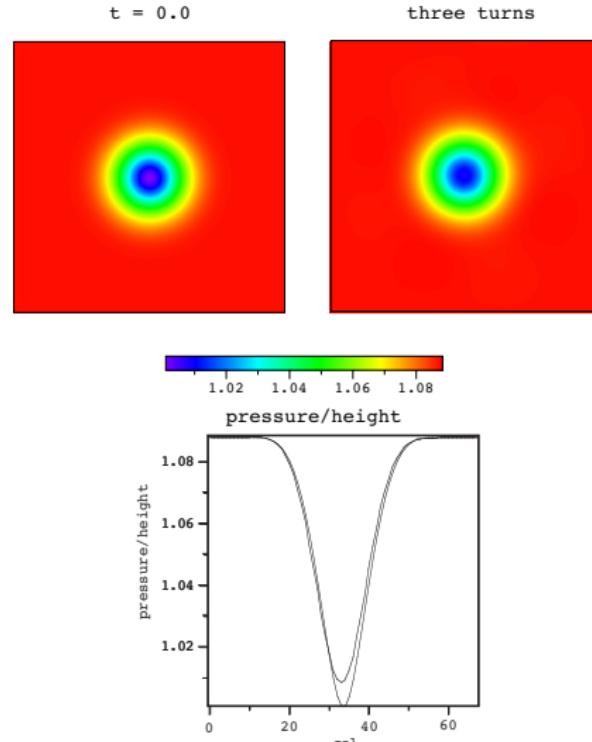
$$(h\mathbf{v})^{n+1} = (h\mathbf{v})^{**} - \delta t \nabla p'^{n+1/2} + \mathcal{O}(\delta t^2)$$

since pressure update already known, obtain **Poisson-type equation**:

$$\begin{aligned} \left(\frac{\partial p}{\partial t} \right)^{n+1/2} &= -\frac{1}{2} \left[h^n \nabla \cdot (h\mathbf{v})^n + h^{n+1} \nabla \cdot (h\mathbf{v})^{n+1} \right] \\ &= -\frac{1}{2} \left[h^n \nabla \cdot (h\mathbf{v})^n + h^{n+1} \nabla \cdot ((h\mathbf{v})^{**} - \delta t \nabla p') \right] \end{aligned}$$

Advection of a vortex

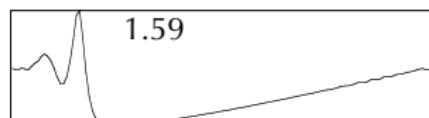
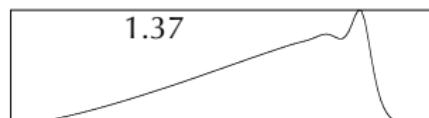
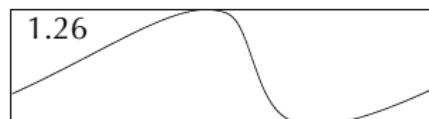
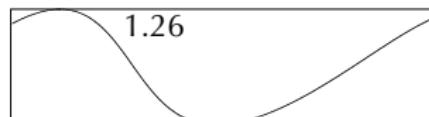
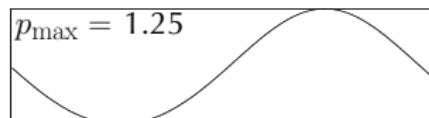
quasi stationary, smooth solution, periodic b.c., $\text{Fr} \sim 0.1$



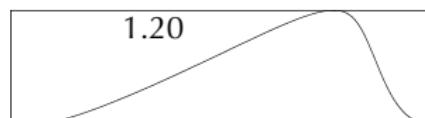
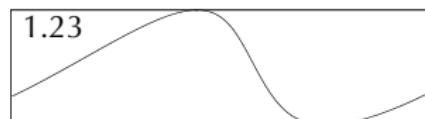
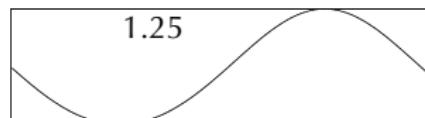
Barotropic Gravity Wave

$\text{Fr} \sim 0.1$, 128 cells, $\text{CFL} = 0.9$

1st "projection" only



1st + 2nd "projection"



Summary

A Cartesian grid semi-implicit method has been presented.

- **conservative** method with two flux corrections motivated by zero Froude number projection method
- incorporates **Godunov-type** method in predictor step
- solution of **one Helmholtz** and **one Poisson-type** problem in correction step
- Outlook
 - ▶ arbitrary Froude number
 - ▶ better representation of gravity waves (incorporation of results from multiscale asymptotic analysis, see Klein (1995))
 - ▶ inclusion of source terms (bottom topography)

For Further Information/Reading



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