

## Discrete Geometry II

### Homework # 9— due June 12th

**Exercise 1.** Consider the following five unit vectors in  $\mathbb{R}^3$ :

$$a_1 = \frac{1}{\sqrt{3}}(1, 1, 1), \quad a_2 = \frac{1}{\sqrt{3}}(1, -1, 1), \quad a_3 = \frac{1}{\sqrt{3}}(-1, -1, 1),$$

$$a_4 = \frac{1}{\sqrt{3}}(-1, 1, 1), \quad a_5 = (0, 0, -1)$$

- i) Describe the cone  $\mathcal{C} := \mathcal{B}_A \cap \{b \in \mathbb{R}^5 \mid b_3 = b_4 = b_5 = 0\}$ .
- ii) Express the volume  $\text{vol}(P_A(b))$  as a piecewise polynomial function of the variables  $b_1$  and  $b_2$  on  $\mathcal{C}$ .

**(10 points)**

**Exercise 2.** i) Give an example of two polytopes  $P_A(b')$  and  $P_A(b'')$  such that

$$P_A(b') + P_A(b'') \neq P_A(b' + b'')$$

ii) Consider the following five unit vectors in  $\mathbb{R}^3$ :

$$a_1 = (-1, 0, 0), \quad a_2 = (0, -1, 0), \quad a_3 = (0, 0, -1),$$

$$a_4 = \frac{1}{\sqrt{3}}(1, 1, 1), \quad a_5 = (a, b, c) \in \mathbb{R}_{<0}^3$$

Find the system of linear inequalities on  $b_4$  and  $b_5$  that describes the cone  $\mathcal{B}_A \cap \{b \in \mathbb{R}^5 \mid b_1 = b_2 = b_3 = 0\}$ .

**(10 points)**

**Exercise 3.** Let  $a_1, \dots, a_n \in \mathbb{R}_{>0}^d$  have strictly positive coordinates. For  $b \in \mathbb{R}_{\geq 0}^n$  define the *orthant-shaped* polyhedron

$$Q(b) := \{x \in \mathbb{R}^d : x \geq 0, a_i^t x \geq b_i \text{ for all } i = 1, 2, \dots, n\}.$$

For  $\alpha \in \mathbb{R}_{>0}^n$  define

$$\mathcal{Q} := \{b \in \mathbb{R}_{\geq 0}^n : \text{vol}_{d-1} Q(b)^{a_i} \leq \alpha_i \text{ for all } i = 1, \dots, n\}$$

i) For  $i \in [n]$  and  $\epsilon > 0$  define  $\bar{b} = b + \epsilon e_i$  and show that

$$\text{vol}_{d-1}(Q(b)^{a_i}) \leq \text{vol}_{d-1}(Q(\bar{b})^{a_i})$$

- ii) Show that there is an  $M$  such that  $b_i \leq M$  for all  $b \in \mathcal{Q}$ .
- iii) Deduce that there is a  $U > 0$  such that

$$P(b) := Q(b) \cap \{x : x_1 + x_2 + \dots + x_d \leq U\}$$

is a polytope such that  $P(b)^{a_i} = Q(b)^{a_i}$  for all  $i$ .

iv) (Bonus) Show that  $\mathcal{Q}$  is convex.

**(10+3 points)**

## Supplementary problems

**Exercise 4.** For  $d+1$  positively dependent vectors  $a_0, a_1, \dots, a_d \in \mathbb{R}^d$  and a vector  $b \in \mathbb{R}^{d+1}$  compute the volume of the simplex  $P_A(b)$ .

**Exercise 5.** Let  $A = (a_1, \dots, a_n)$  be a configuration of unit vectors in  $\mathbb{R}^d$ . Define the *contraction*  $c_i(A)$  as the following configuration of  $n-1$  vectors in  $a_i^\perp$ :

$$c_i(a_j) = a_j - (a_i^\top a_j)a_i \text{ for all } j \neq i$$

i) Show that the face  $F_i(b)$  of the polyhedron  $P_A(b)$  is congruent to the polyhedron  $P_{c_i(A)}(d_i(b)) \cap a_i^\perp$ , where  $d_i(b) = (b_1, \dots, \hat{b}_i, \dots, b_n) \in \mathbb{R}^{n-1}$ .

ii) Prove the formulas

$$\frac{\partial \text{vol}_{d-1}(F_i(b))}{\partial b_j} = \frac{\text{vol}_{d-2}(F_{ij}(b))}{\sin \phi_{ij}}$$

$$\frac{\partial \text{vol}_{d-1}(F_i(b))}{\partial b_i} = - \sum_{j \neq i} \text{vol}_{d-2}(F_{ij}(b)) \cot \phi_{ij}$$

where  $F_{ij}(b) = F_i(b) \cap F_j(b)$ , and  $\phi_{ij}$  is the angle between  $a_i$  and  $a_j$ .

iii) (Bonus) Show that the volume is twice continuously differentiable on a subset of  $\mathcal{B}_A$  consisting of all  $b$  such that the system  $Ax \leq b$  is irredundant. Give an example showing that the volume is not thrice differentiable.