



Dynamic Planar Voronoi Diagrams for General Distance Functions

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Berlin, Germany

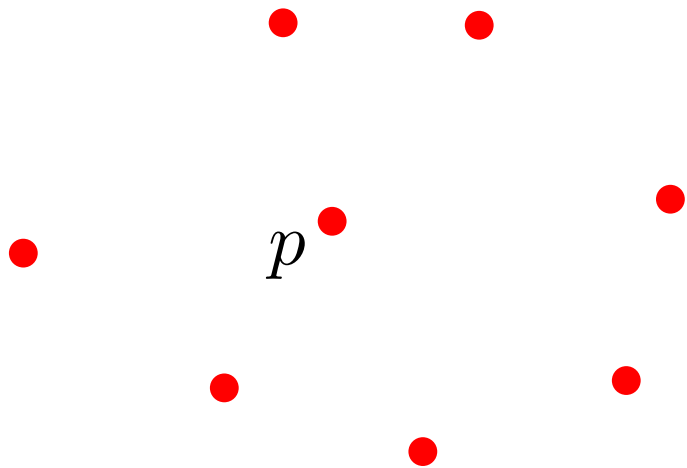
Micha Sharir

Tel Aviv University
Tel Aviv, Israel

Dynamic Nearest Neighbor Search

sites P in \mathbb{R}^2 +

distance functions $\delta_p : \mathbb{R}^2 \rightarrow \mathbb{R}$ for all $p \in P$

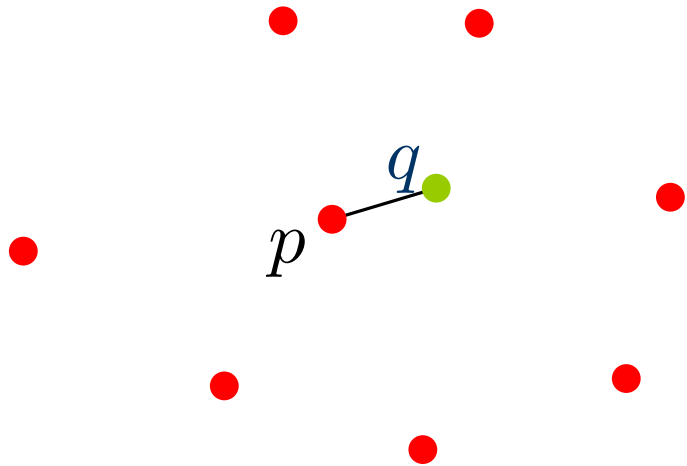


Euclidean

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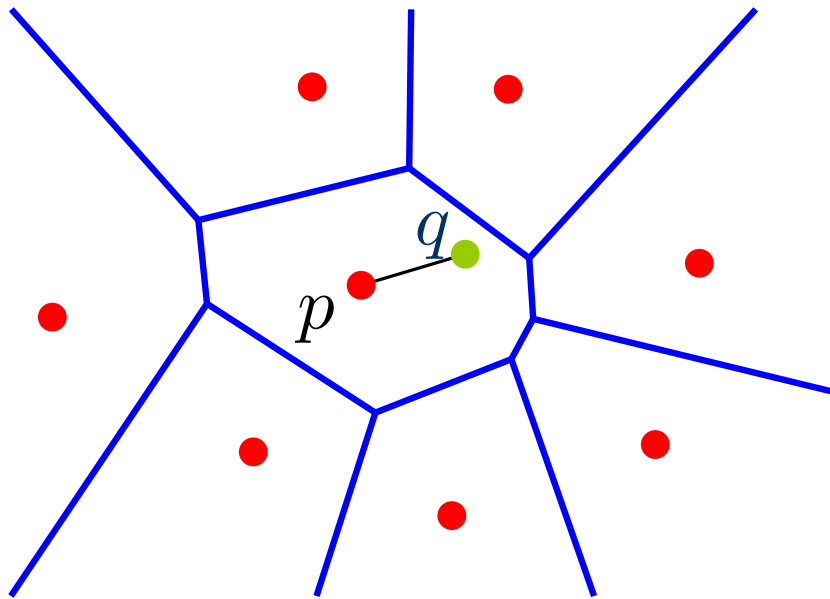


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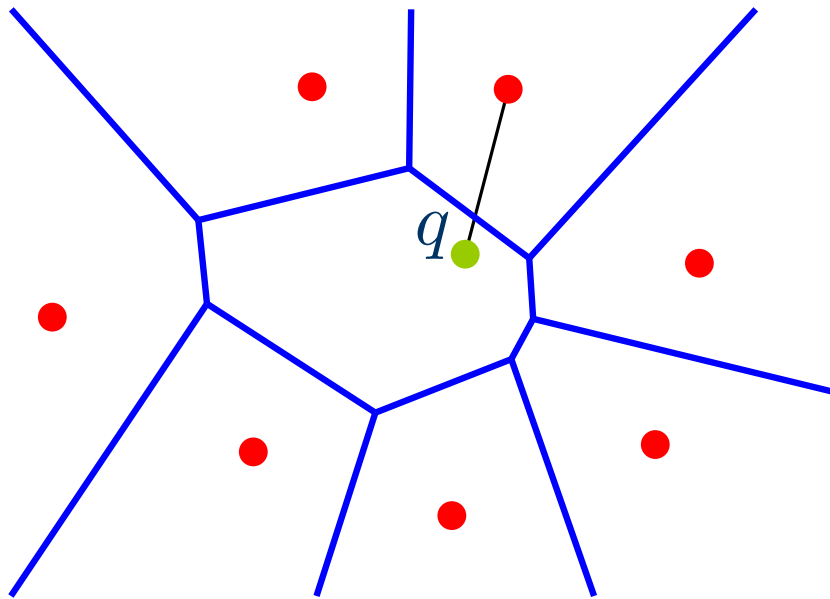


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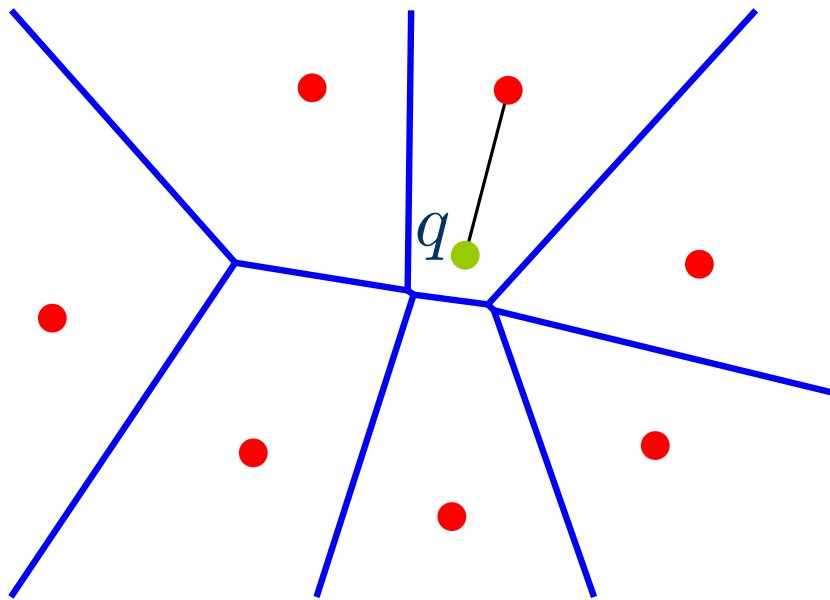


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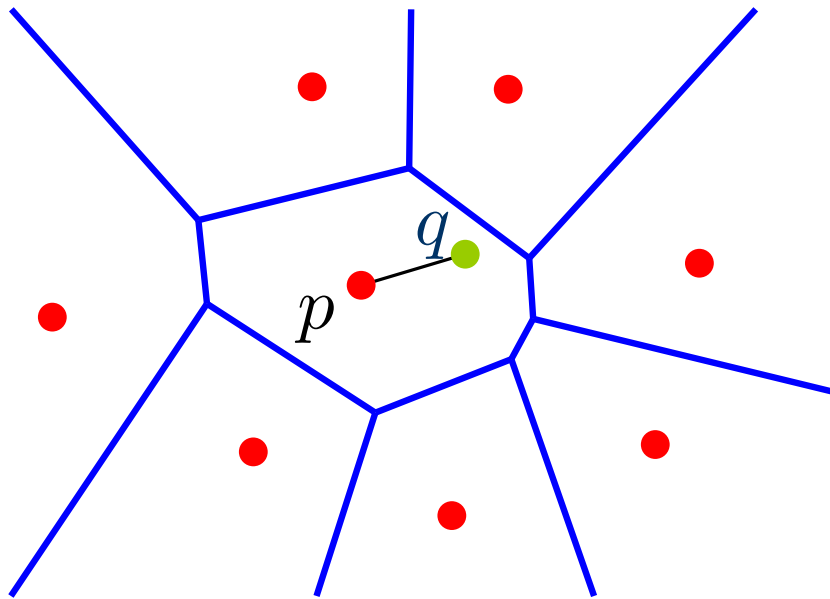


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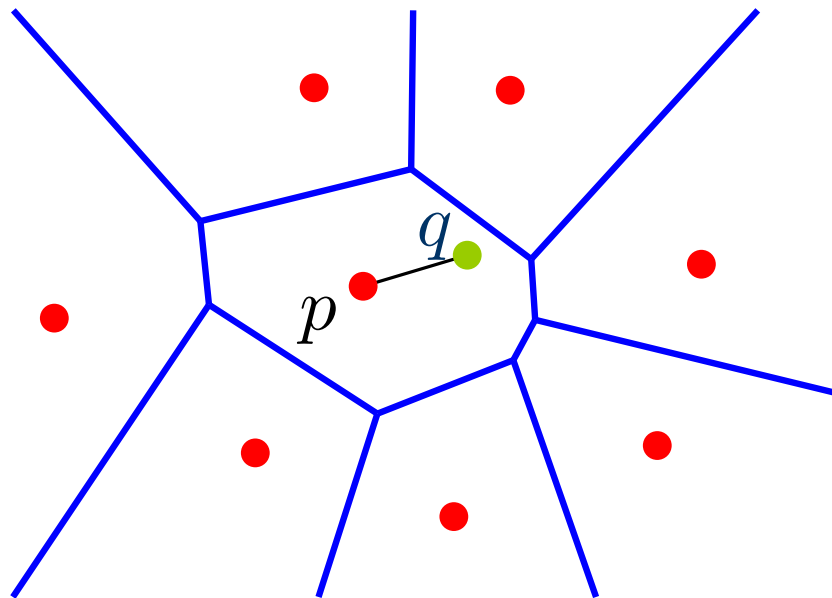


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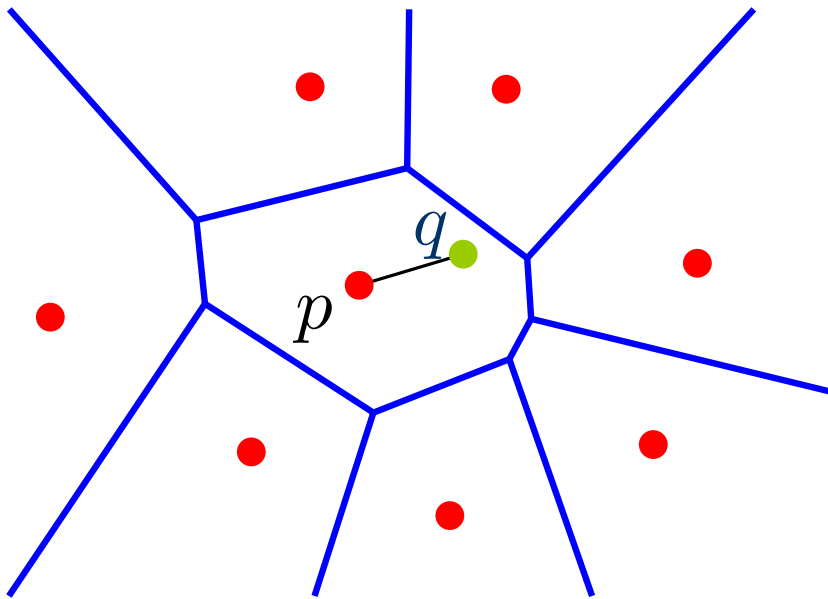
Euclidean

	updates	queries
[AM95]	n^ϵ	$\log n$
[Cha06]	$\log^6 n$	$\log^2 n$

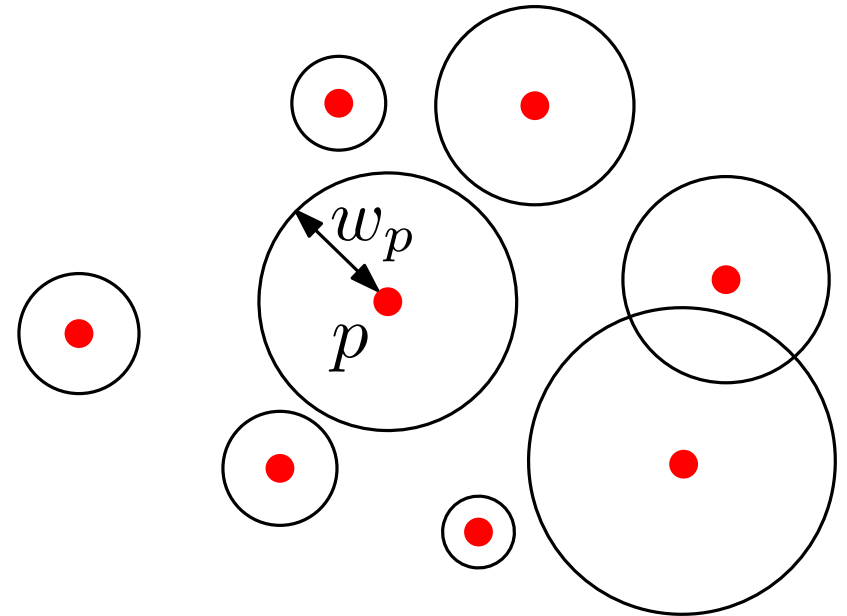
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gen. metric

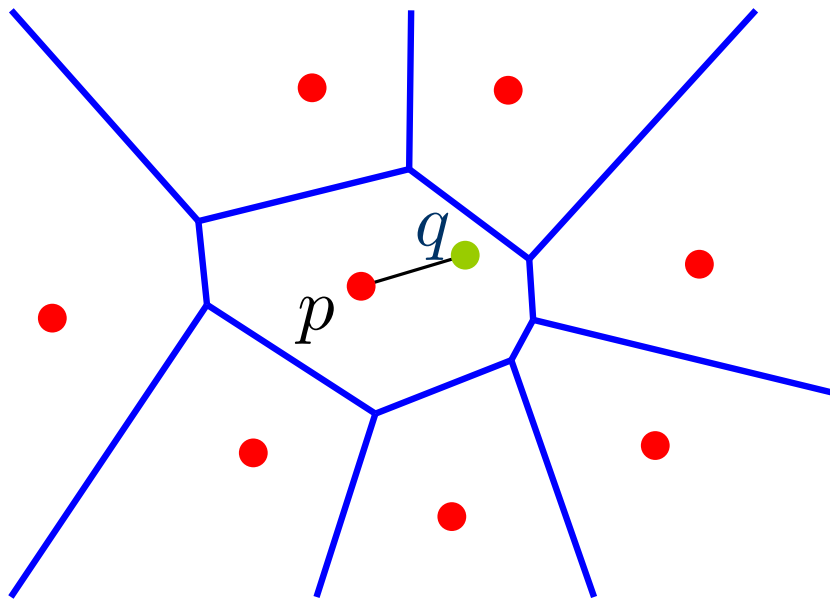
(e.g., add. weighted or any ℓ_p -norm)

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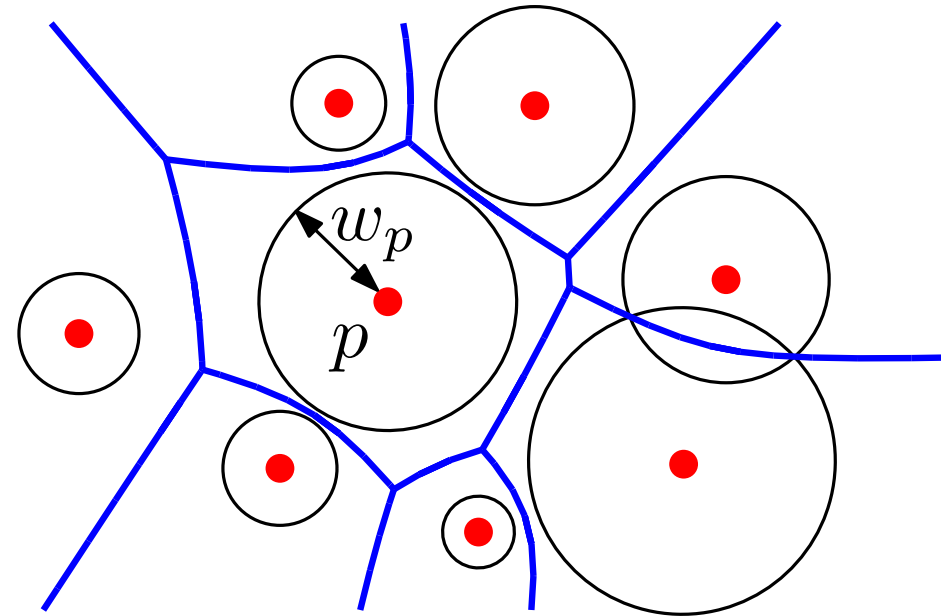
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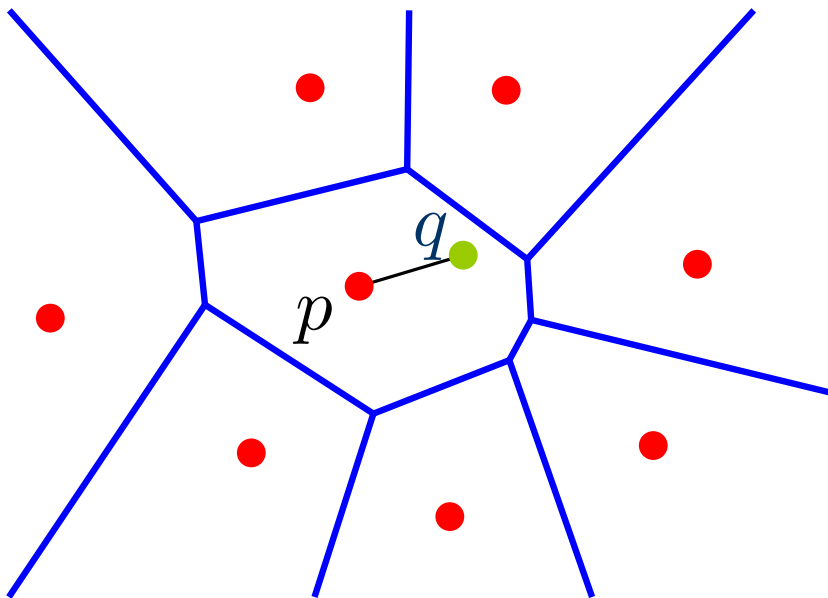
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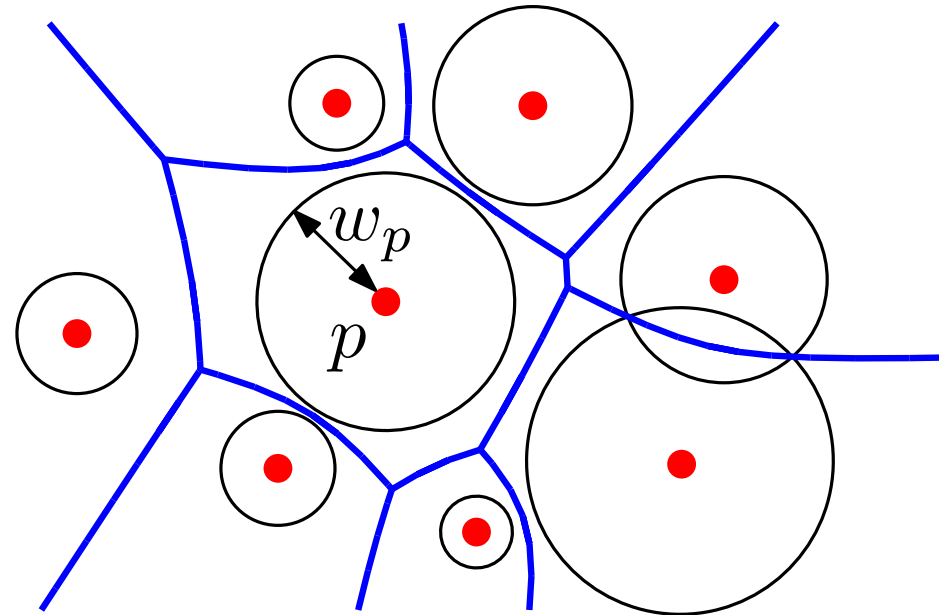
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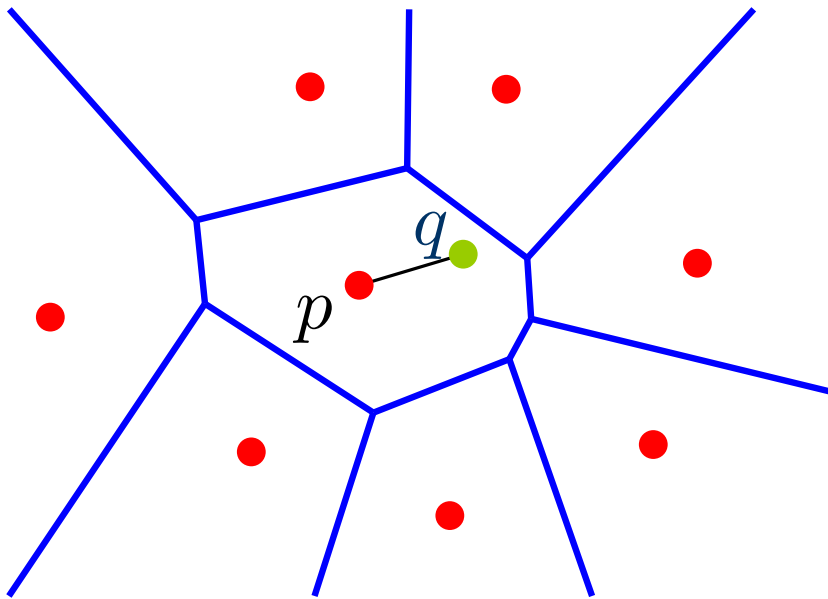
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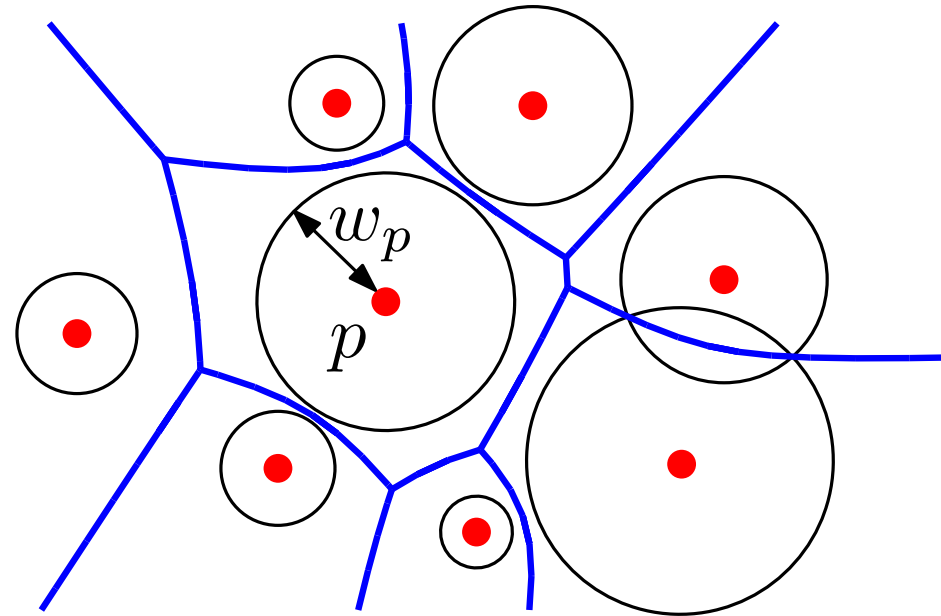
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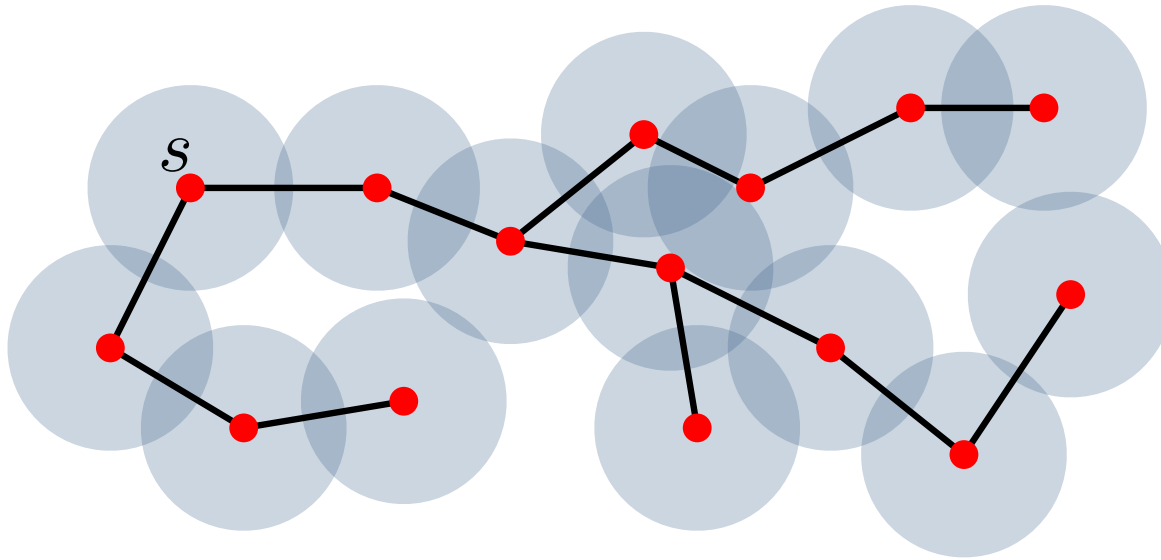
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[AES99]	n^ε	$\log n$
Now:	$\text{polylog}(n)$	$\log^2 n$

Applications

Single source shortest path in unit disk graphs

Old Bound: $n^{1+\varepsilon}$ [CJ15]

New Bound: $n \text{polylog}(n)$ exp.

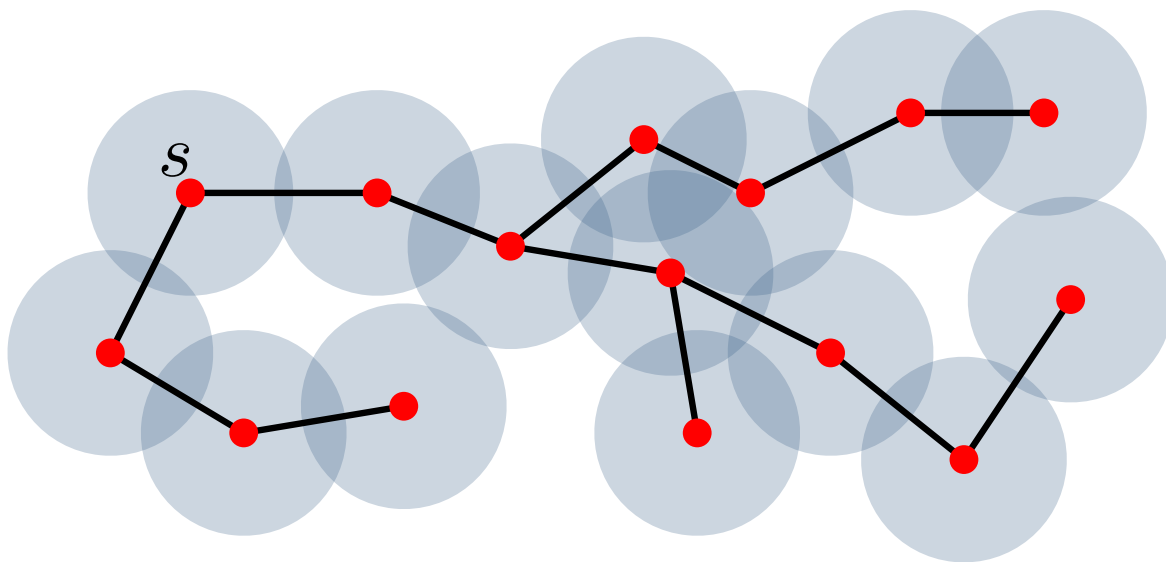


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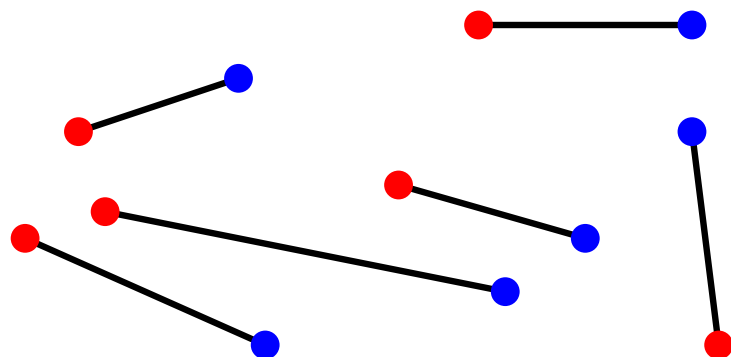
New Bound: $n \text{polylog}(n)$ exp.



Minimum Euclidean planar bichromatic matching

Old Bound: $n^{2+\varepsilon}$ [AES99]

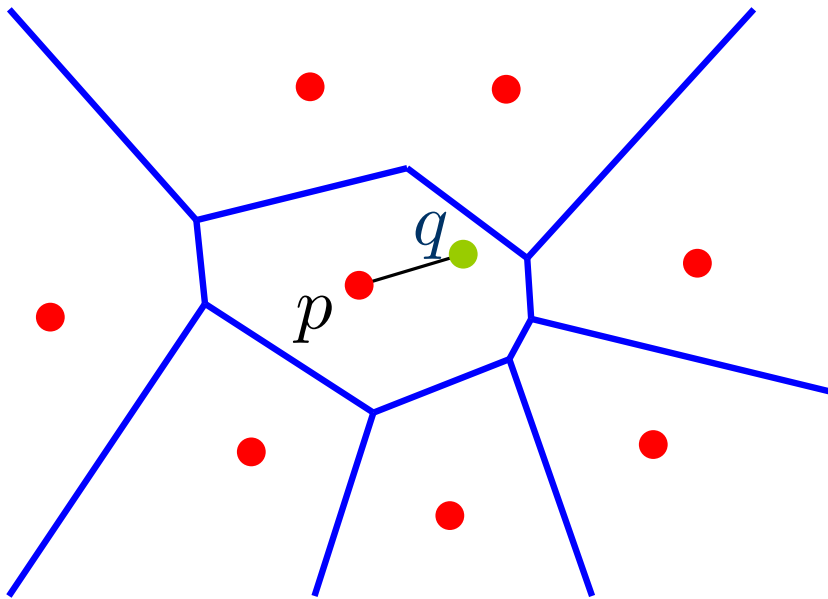
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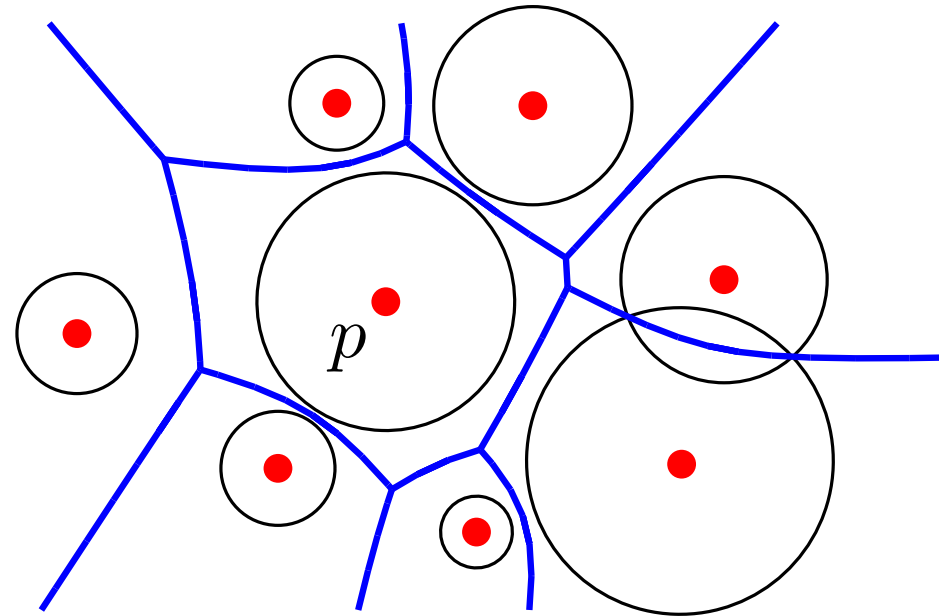
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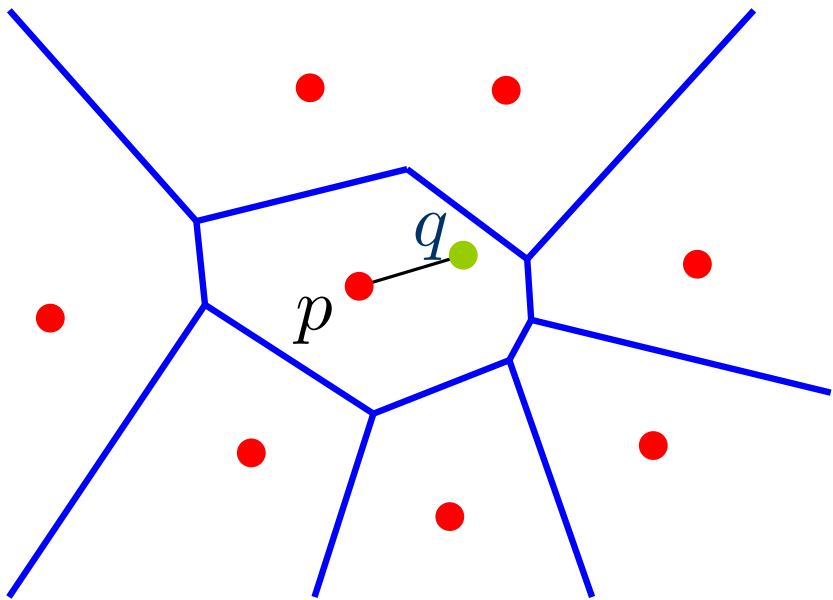
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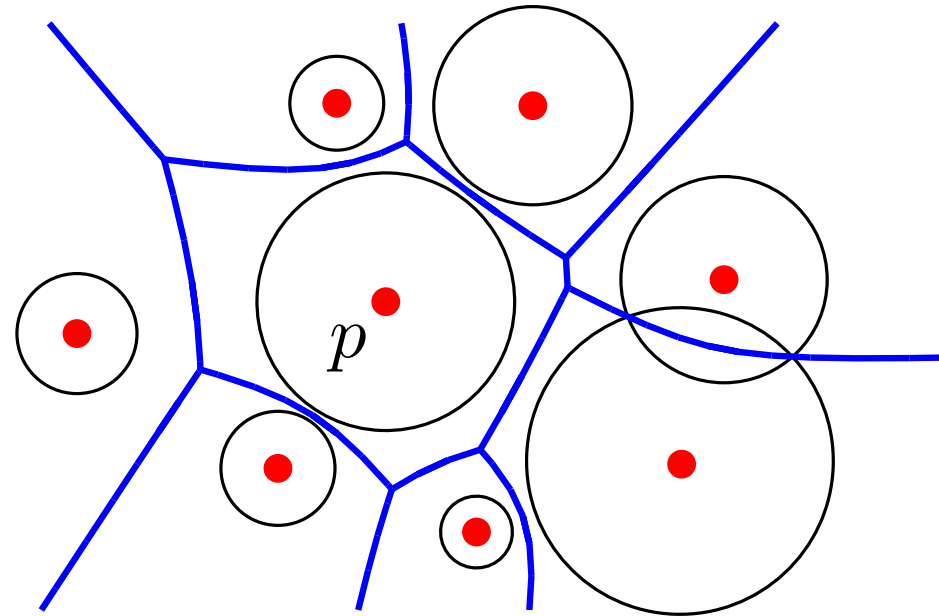
gen. metric

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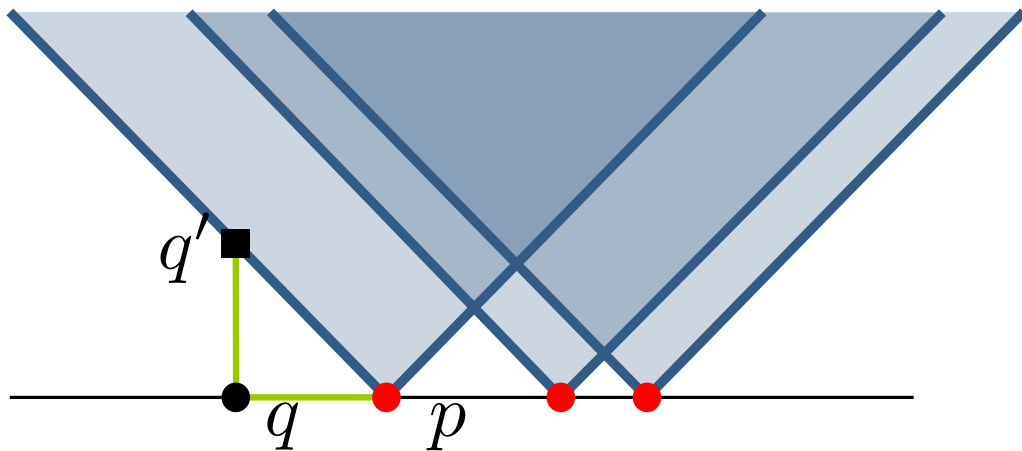
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Euclidean

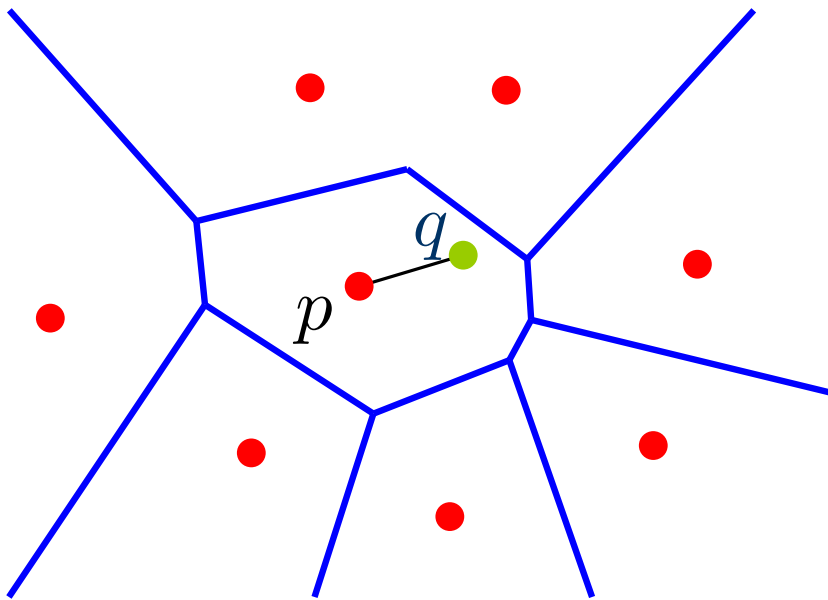


gen. metric

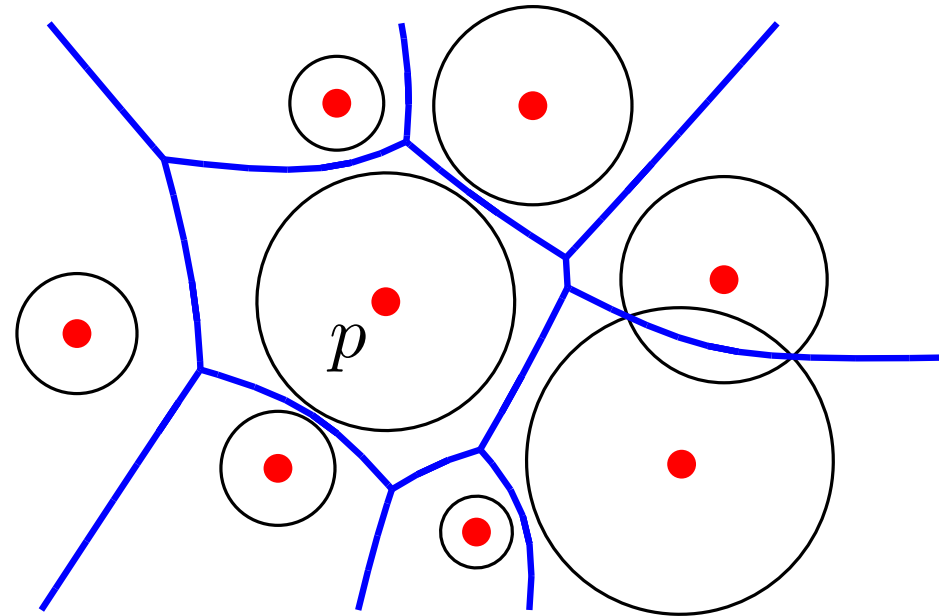


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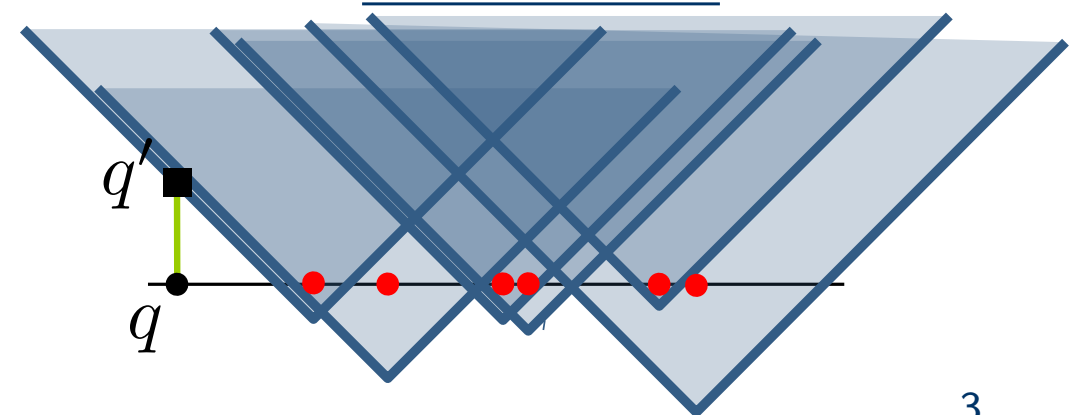
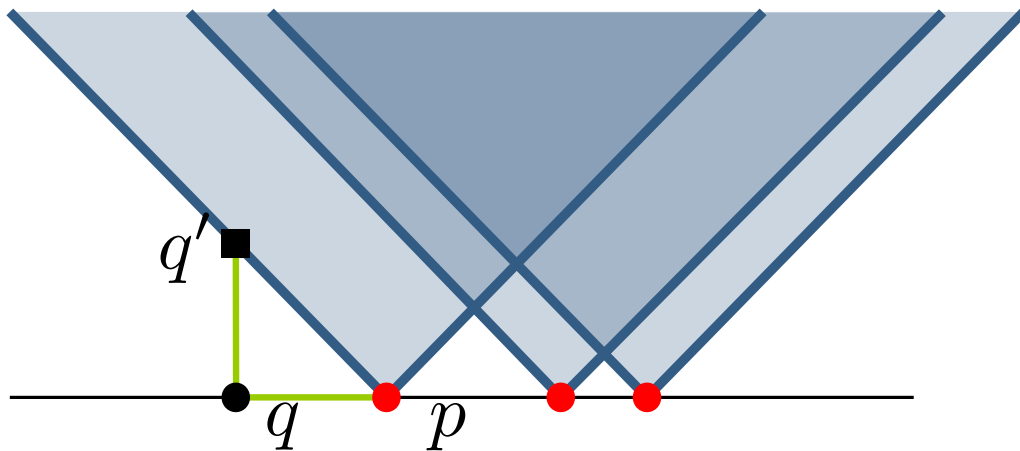
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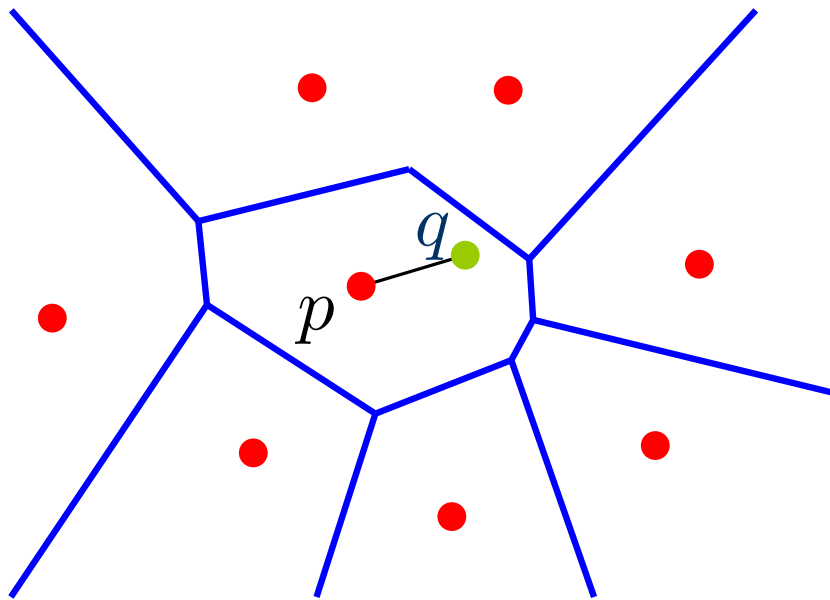


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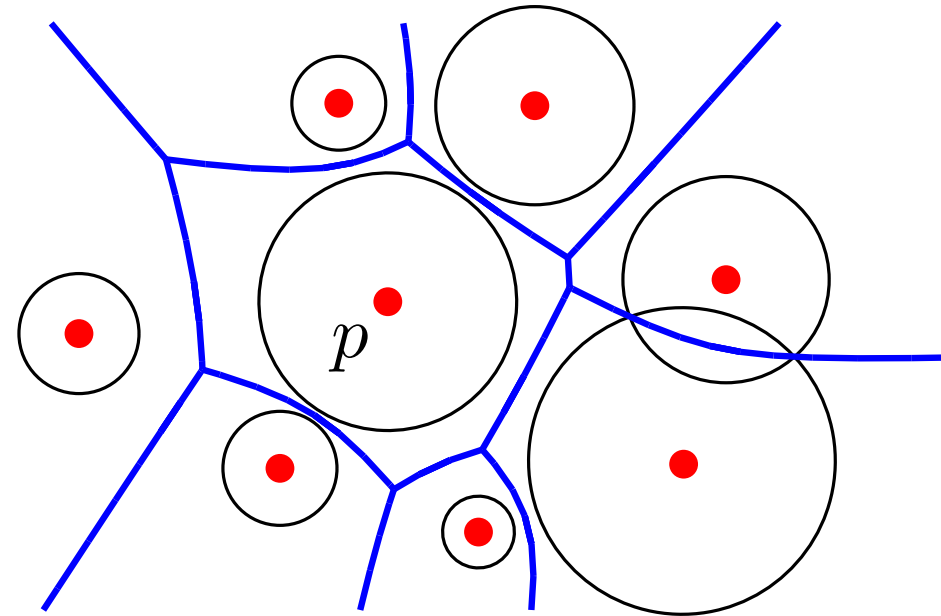


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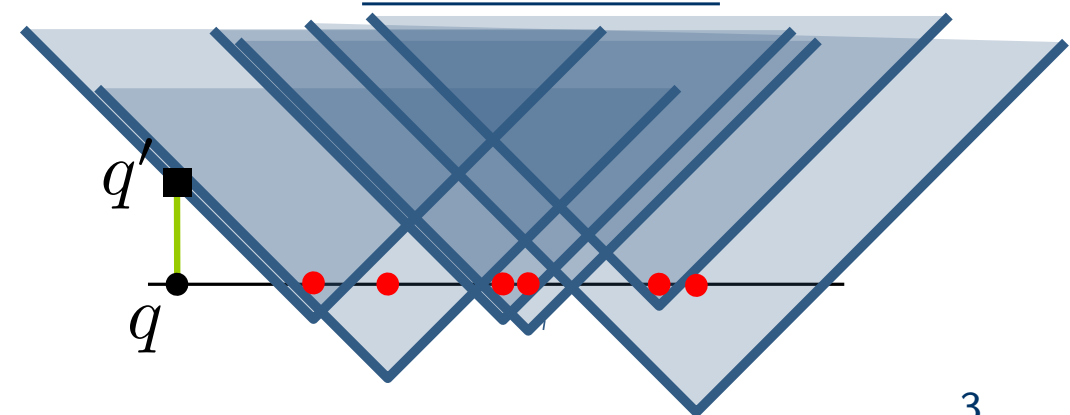
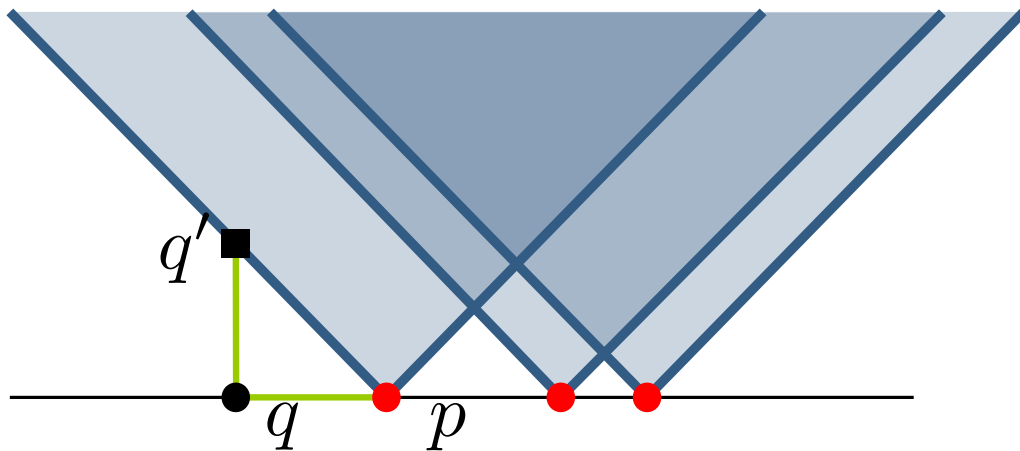
sites P in \mathbb{R}^2 +
distance functions $\delta_p : \mathbb{R}^2 \rightarrow \mathbb{R}$ } surfaces S in \mathbb{R}^3



Euclidean

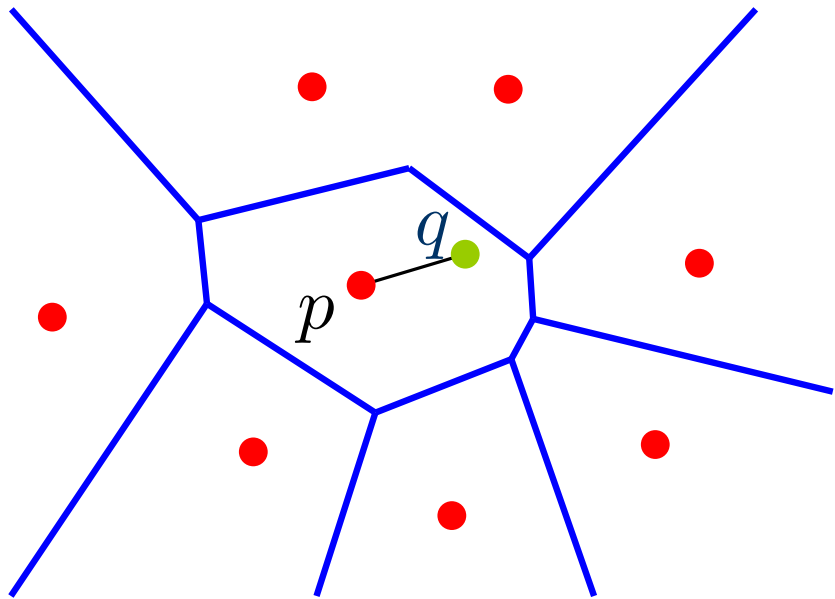


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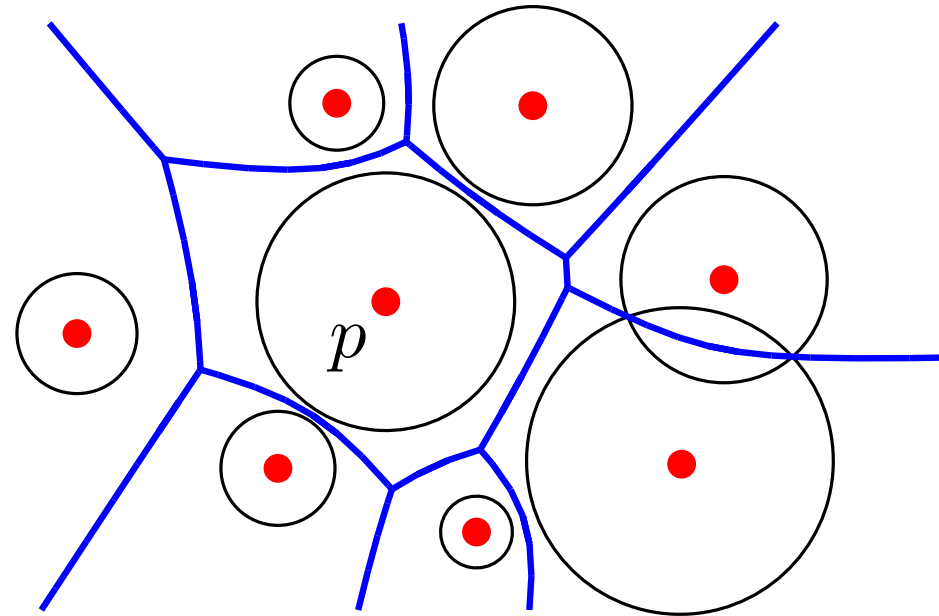


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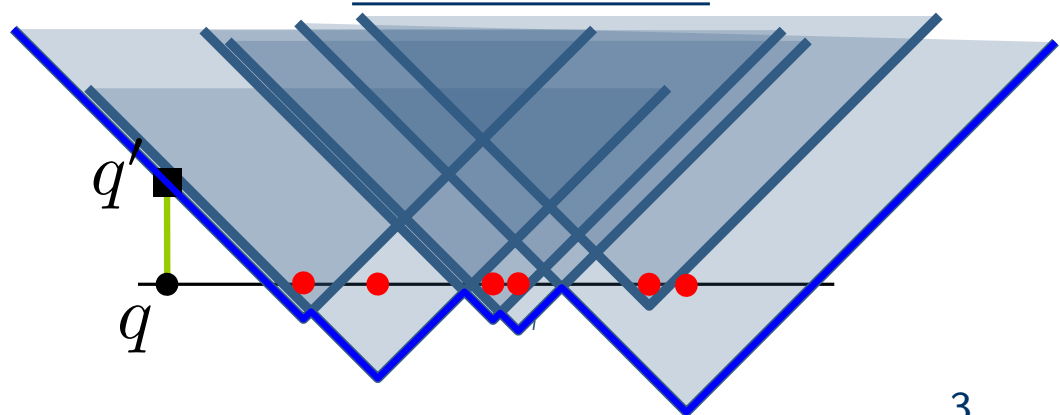
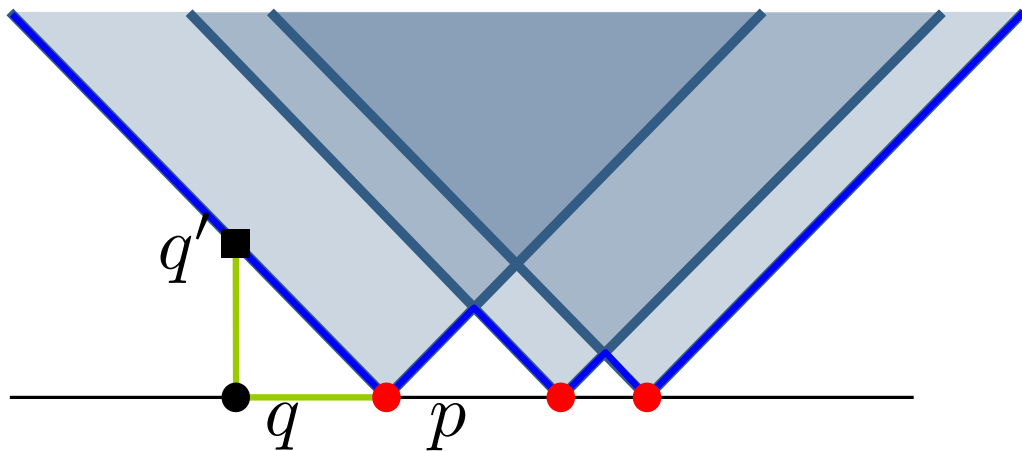
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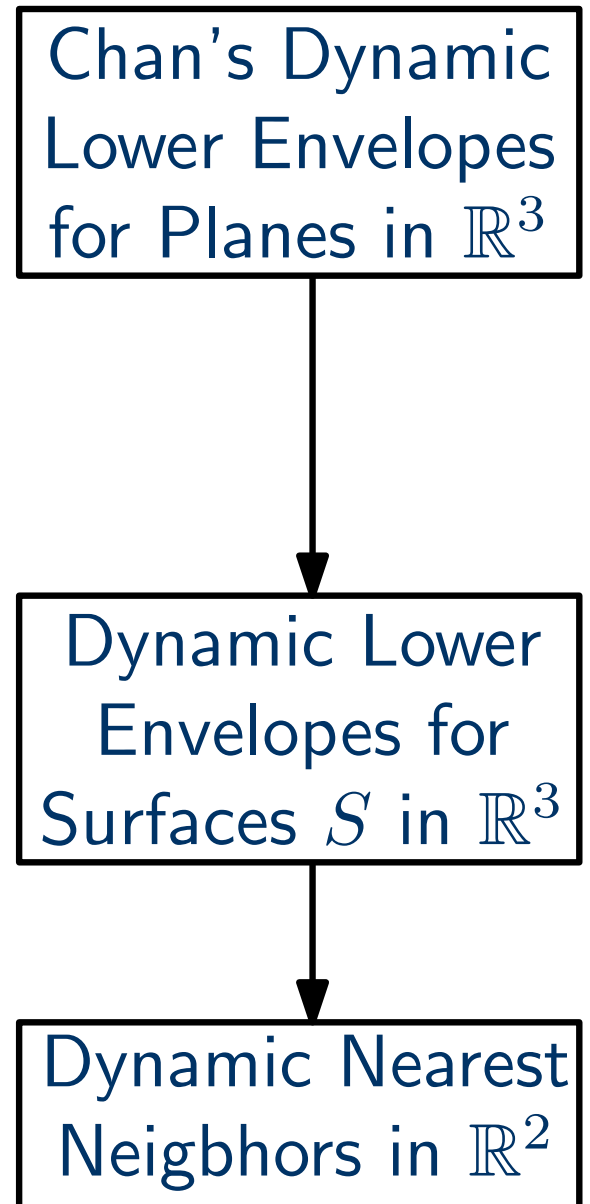
Overview

Dynamic Lower
Envelopes for
Surfaces S in \mathbb{R}^3

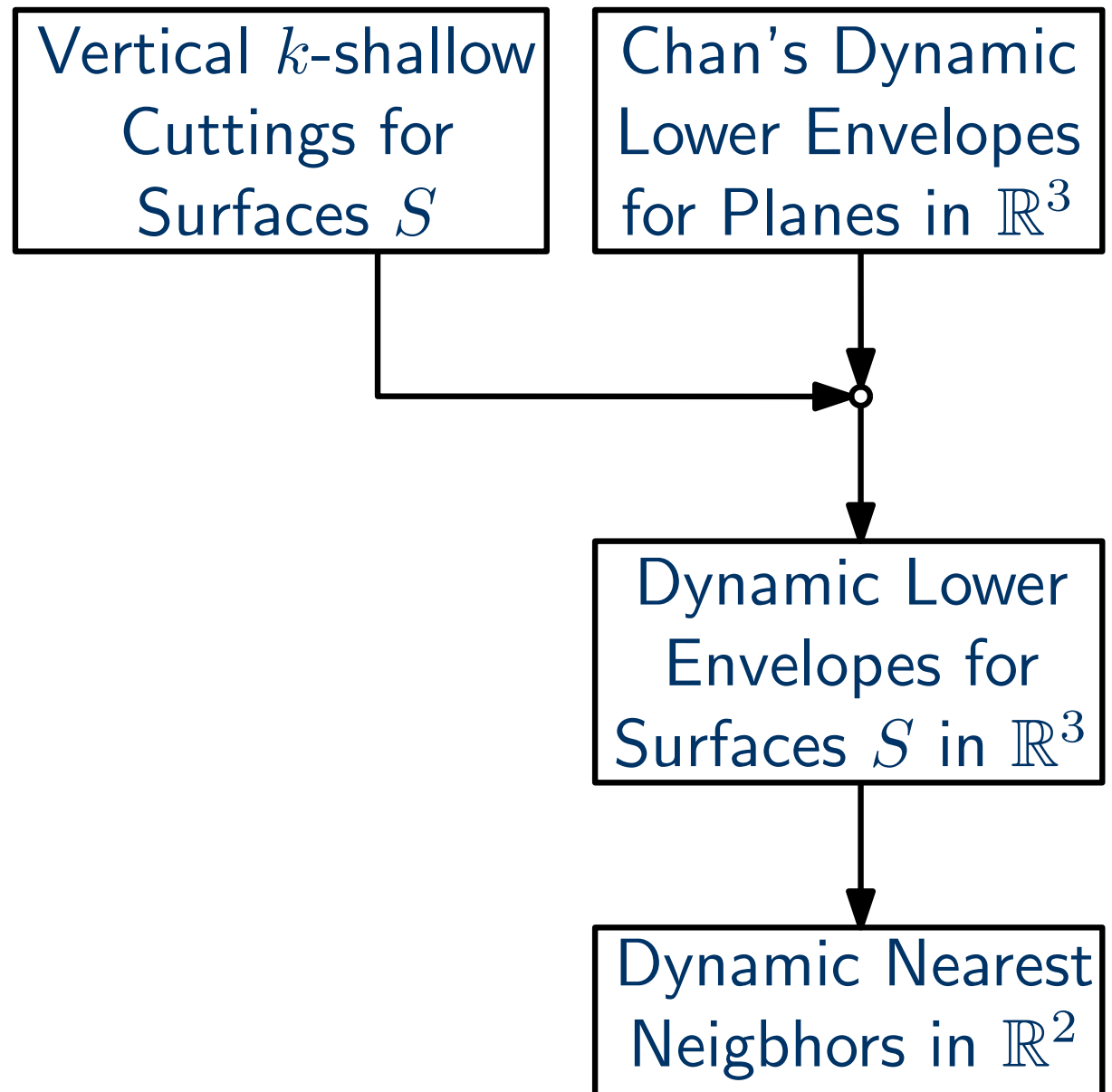


Dynamic Nearest
Neighbors in \mathbb{R}^2

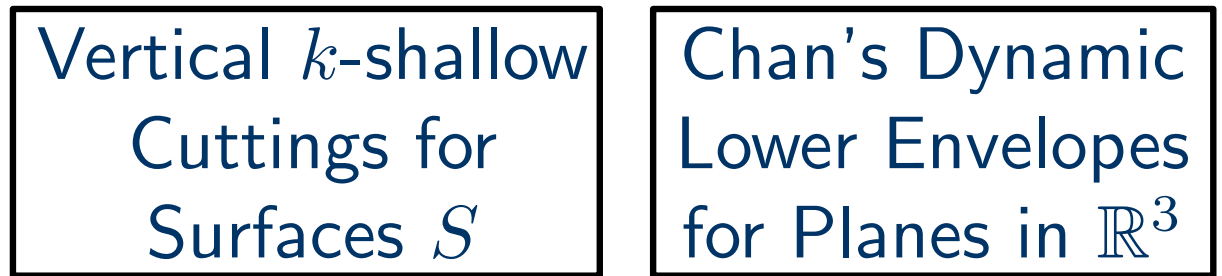
Overview



Overview



Overview



vertical k -shallow cuttings for S with

- size $O((n/k)\text{polylog}n)$
- in time $O(n\text{polylog}(n))$

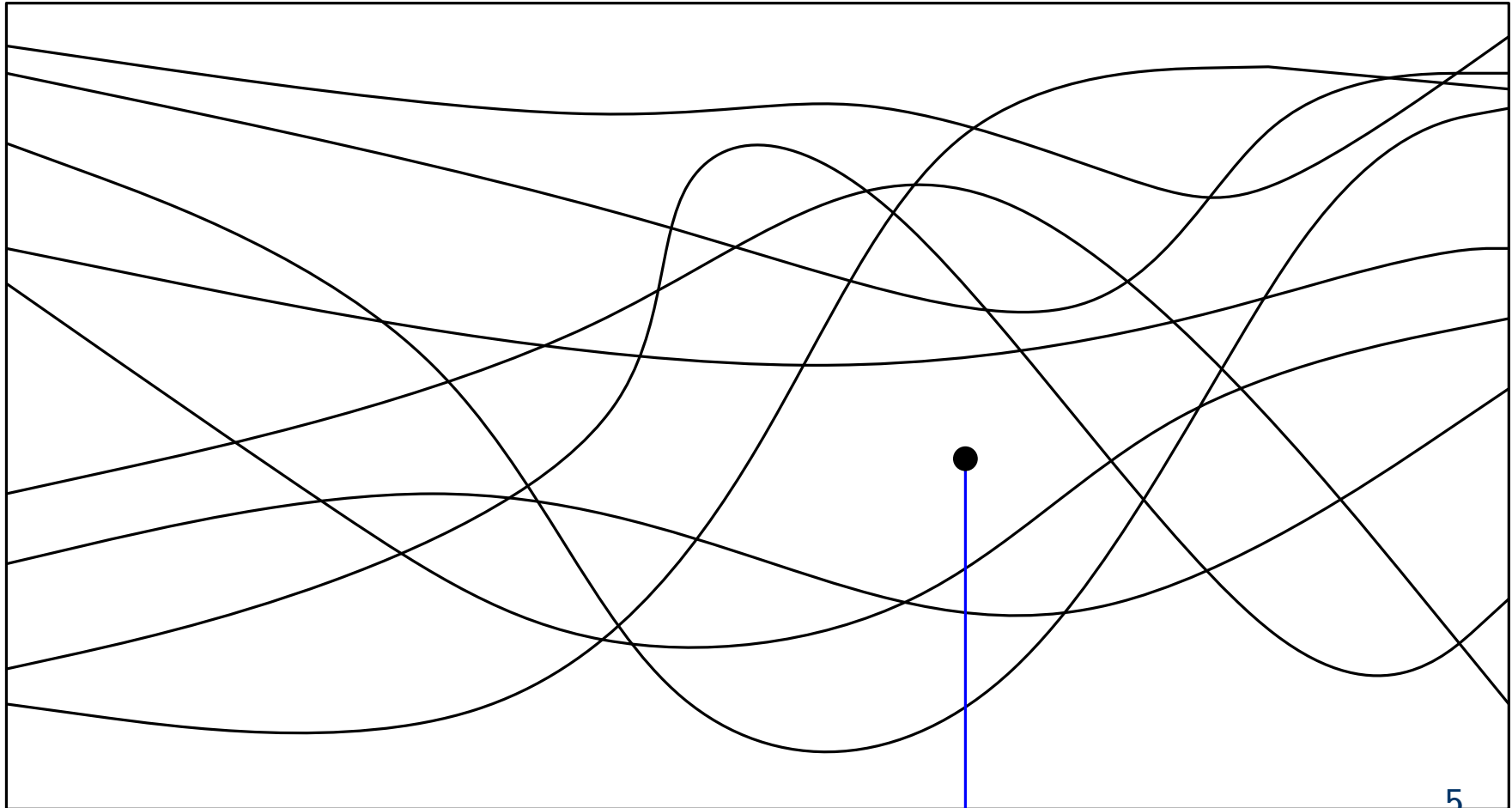


dynamic lower envelopes for S with

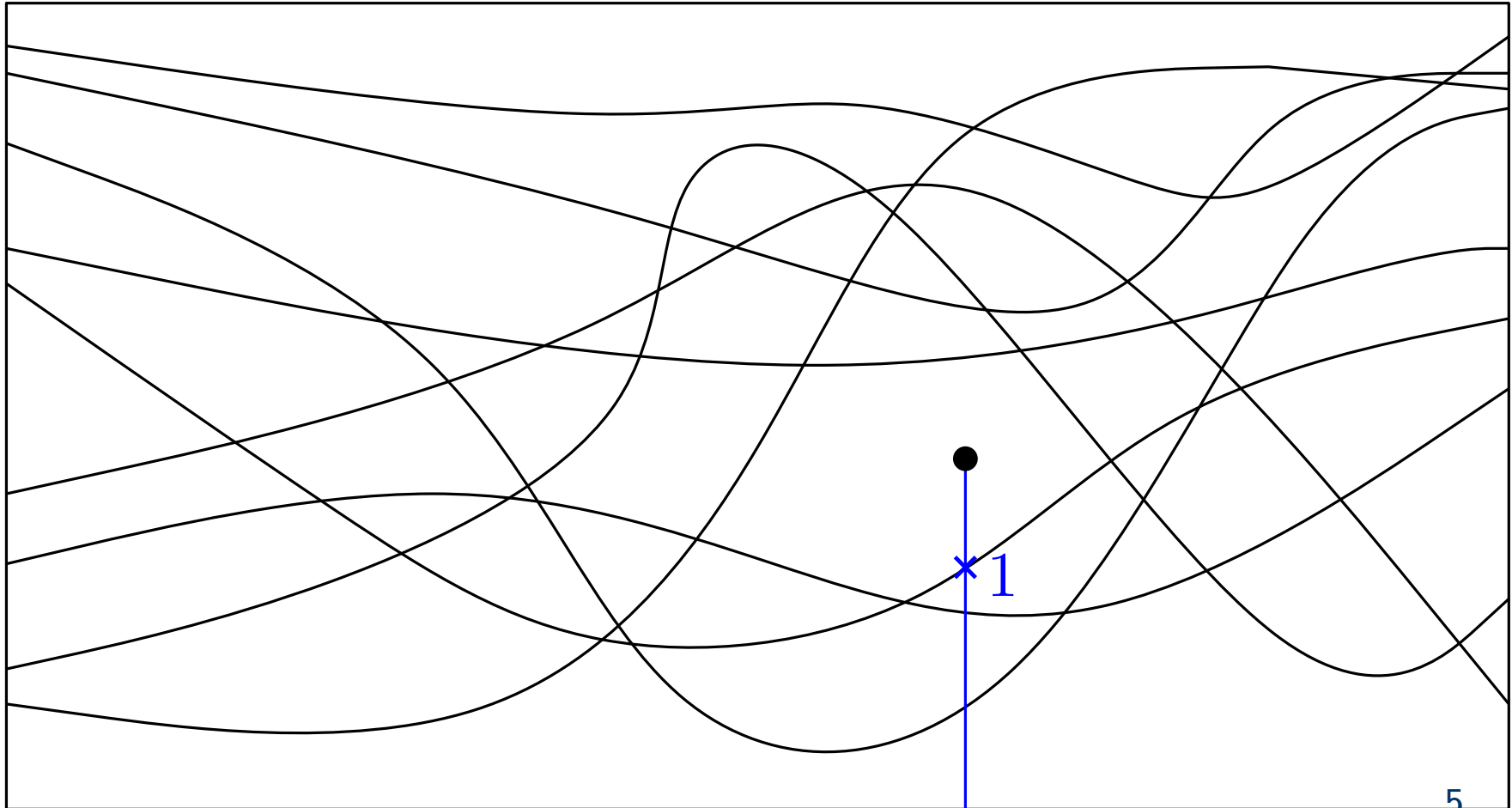
- update time $O(\text{polylog}(n))$
- query time $O(\log^2 n)$



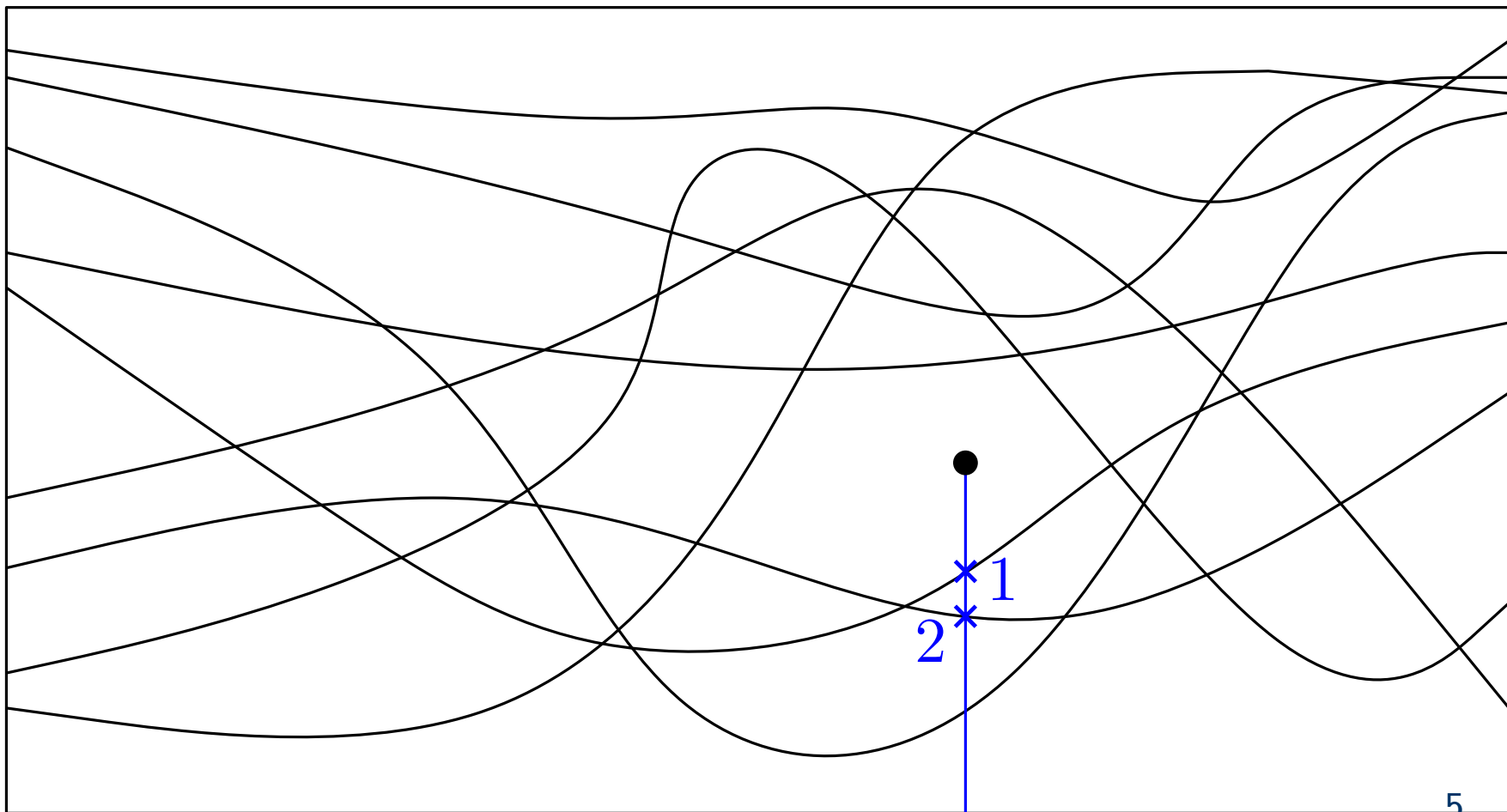
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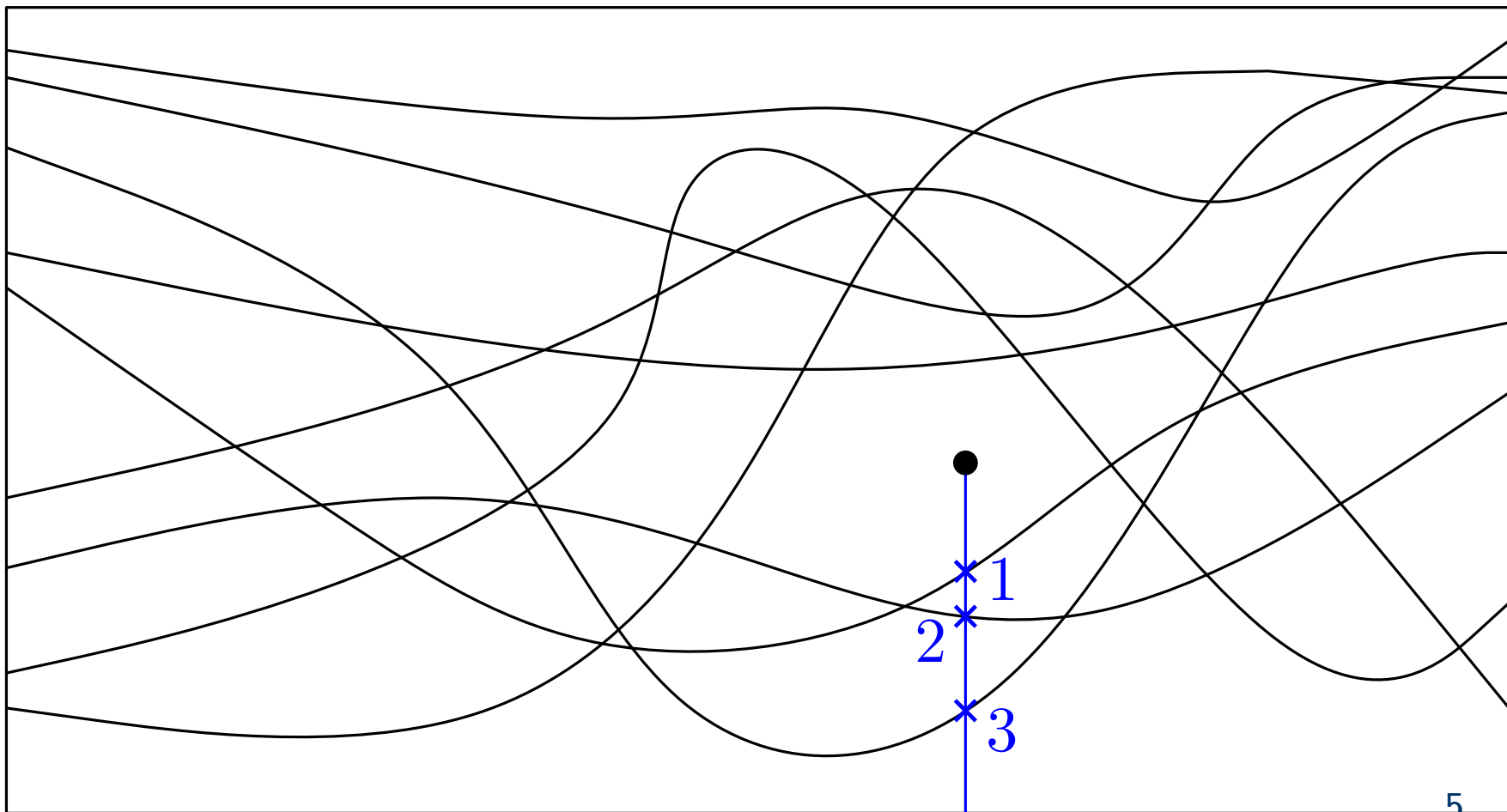
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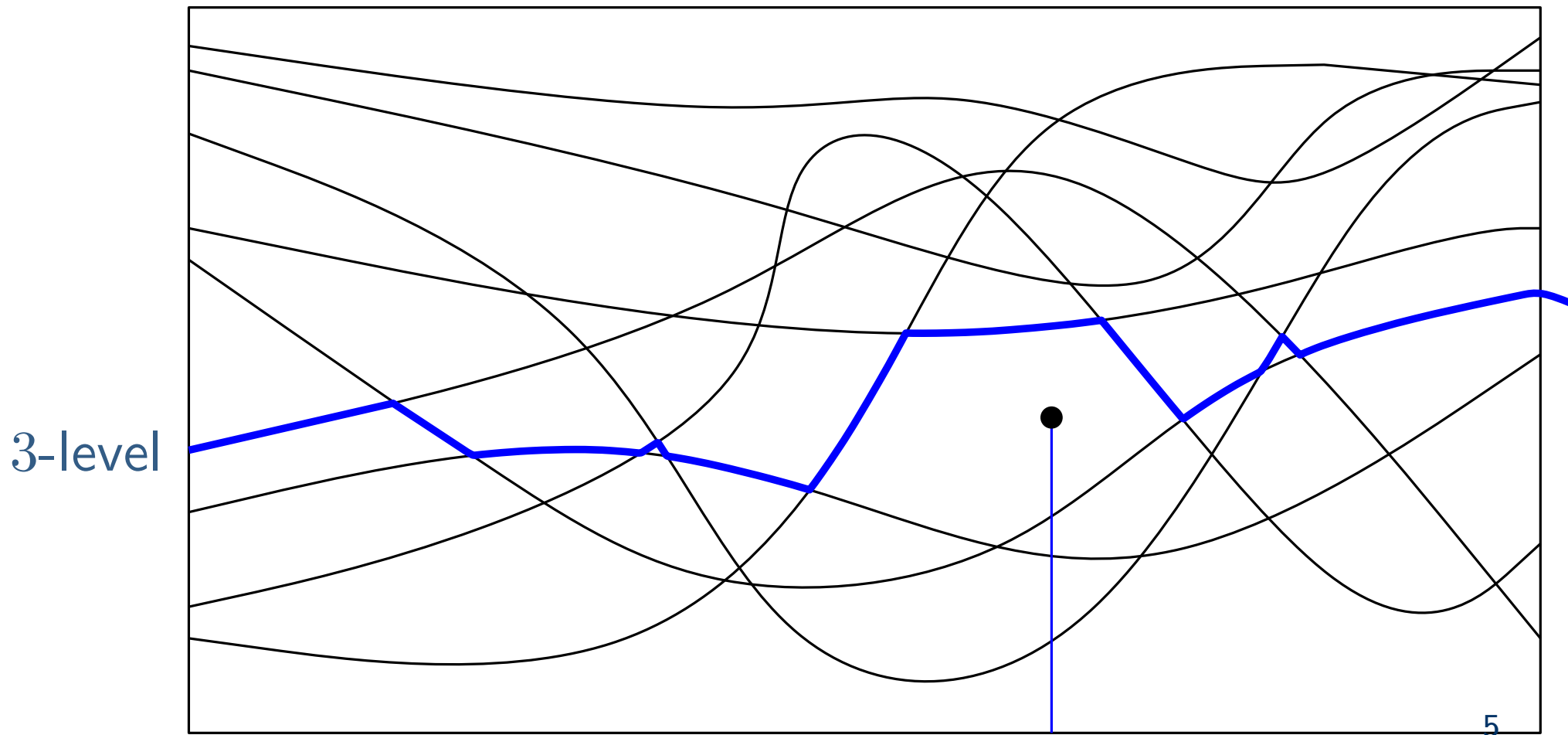
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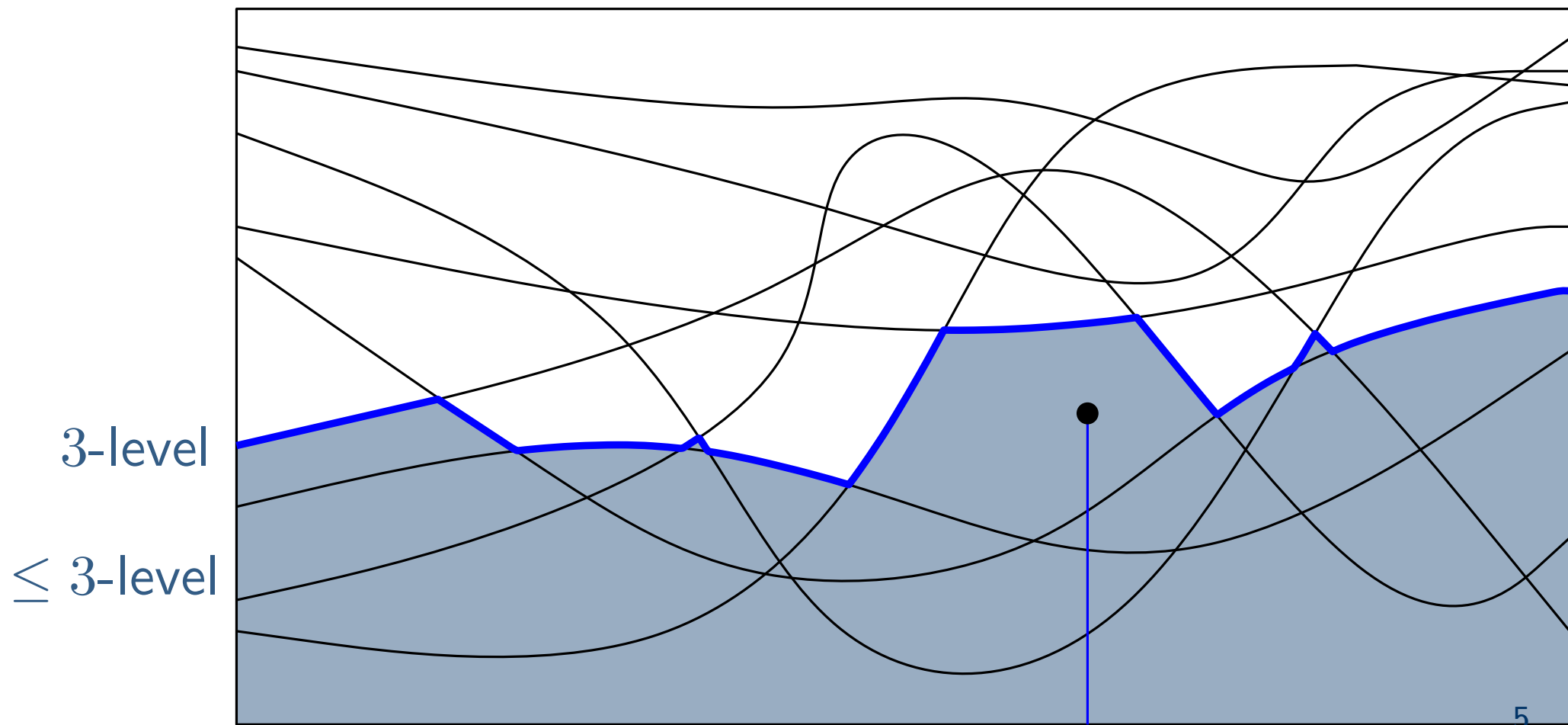
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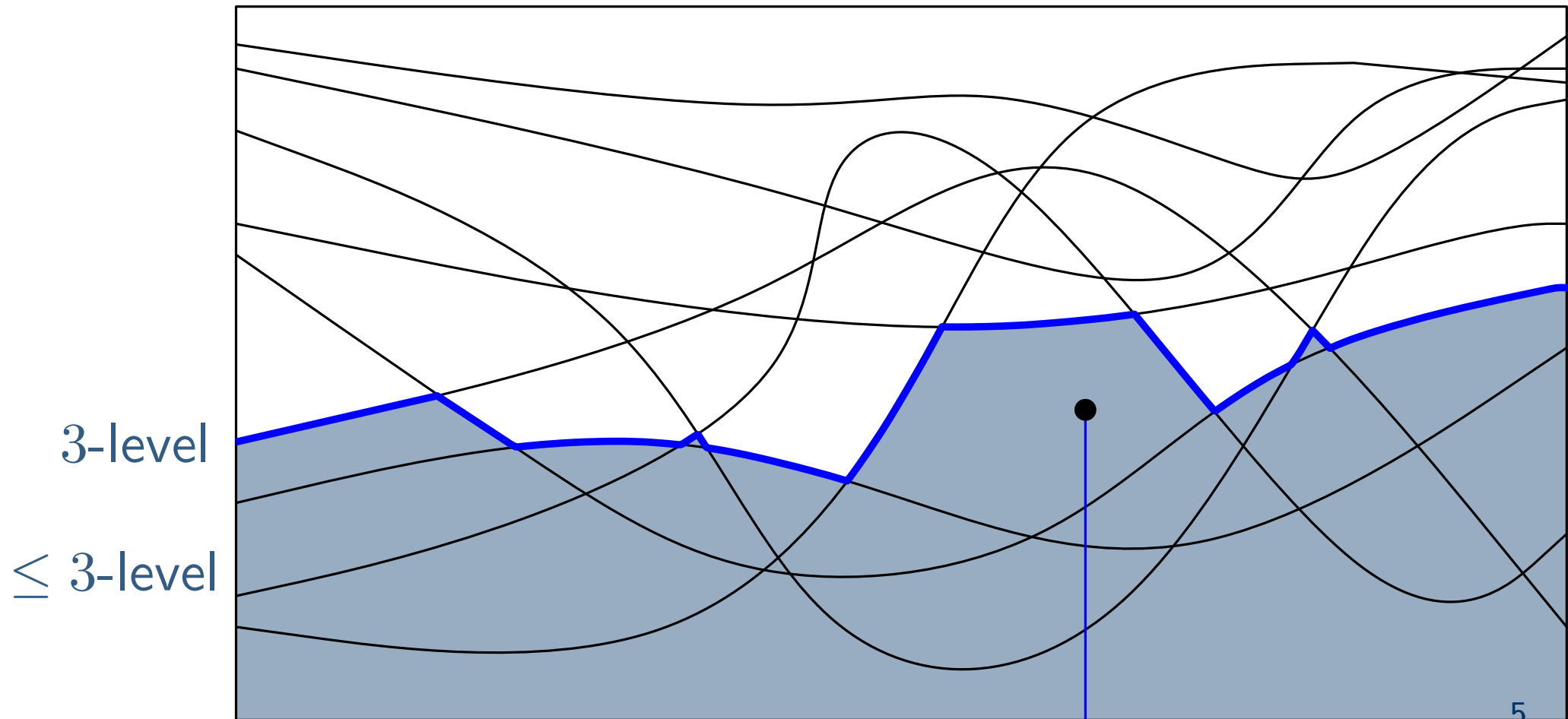


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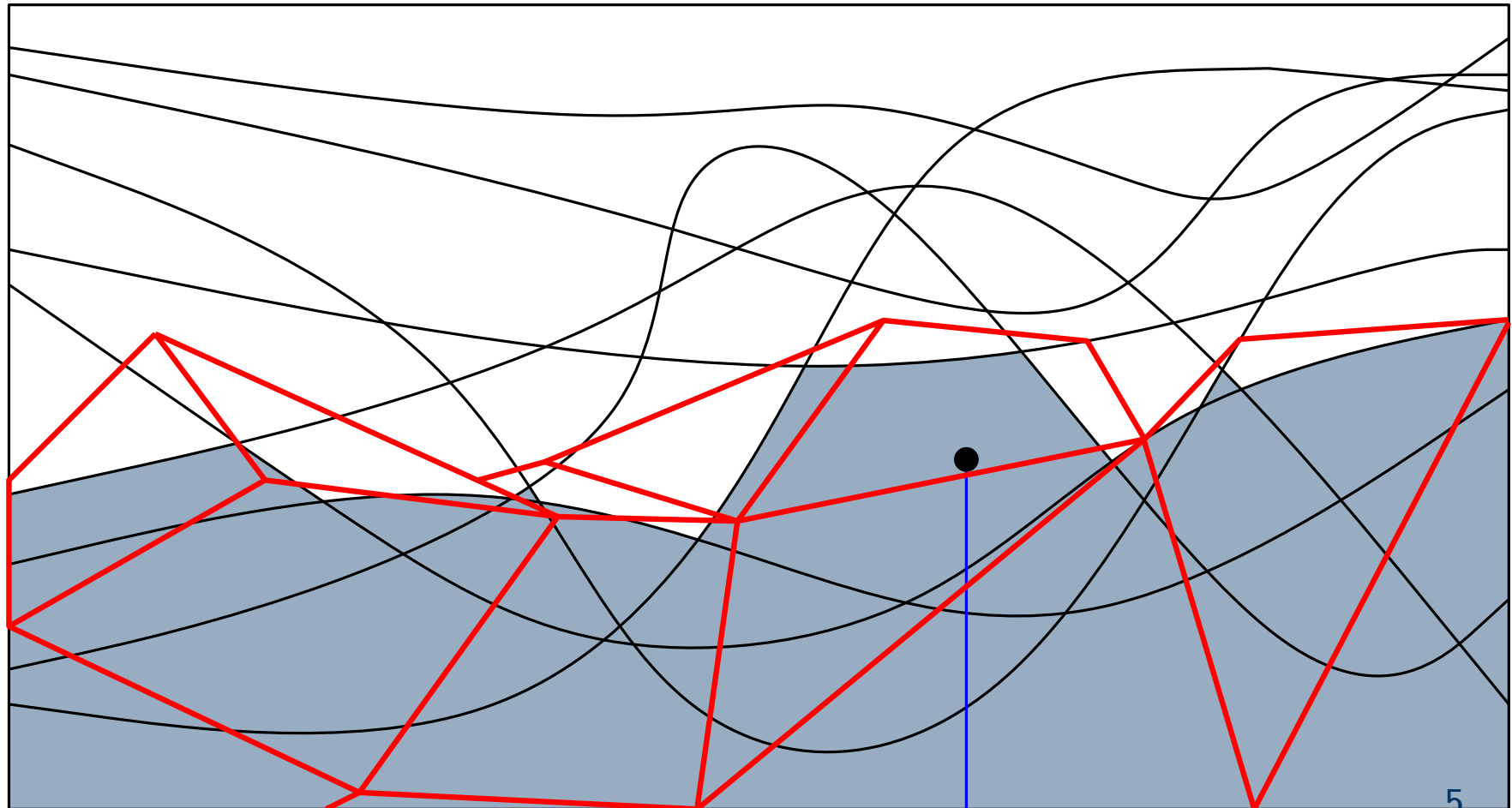
Vertical k -shallow cuttings

k -shallow cutting: covering of $\leq k$ -level with "few" cells s.t. each cell intersects $O(k)$ surfaces



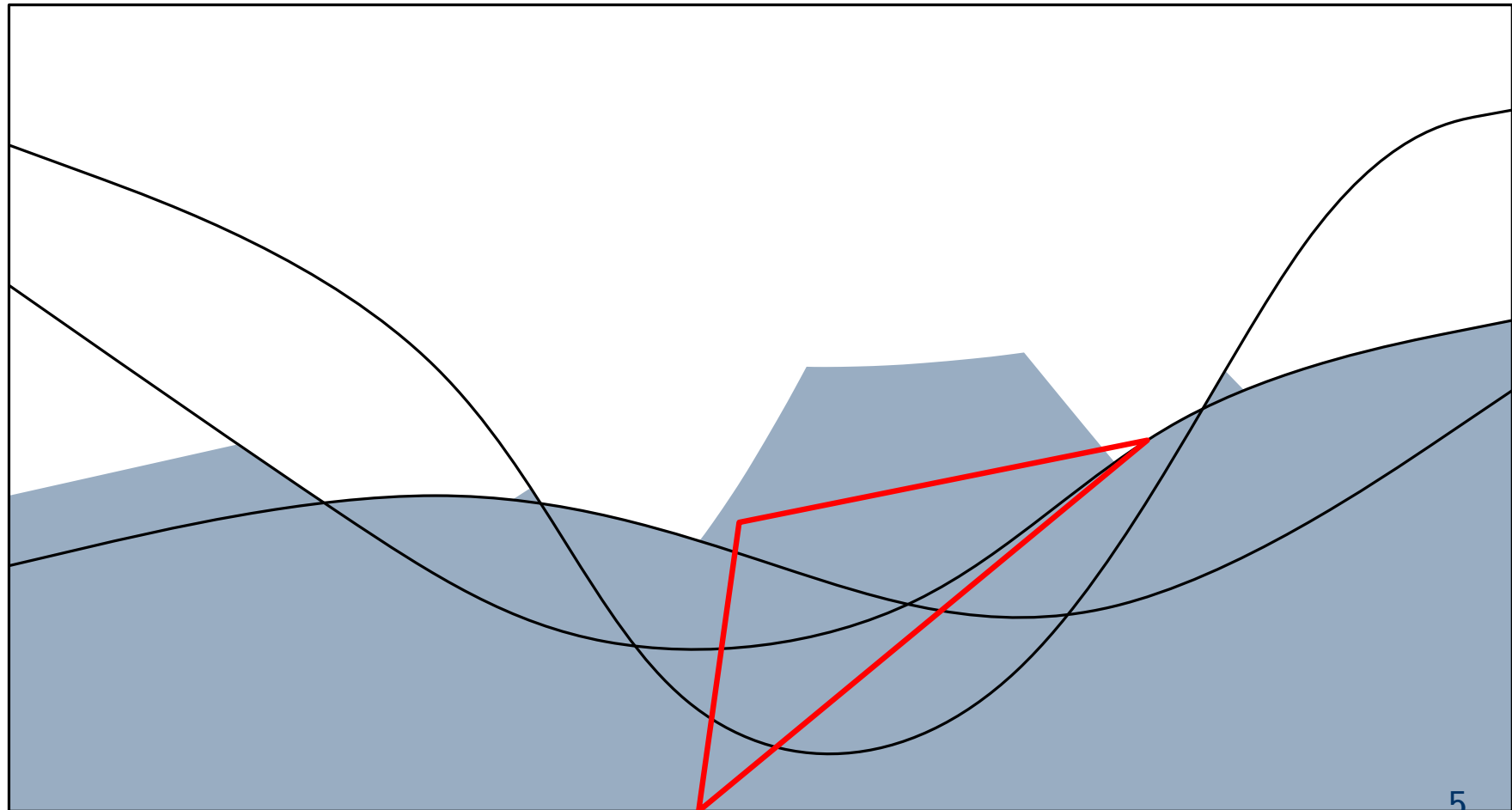
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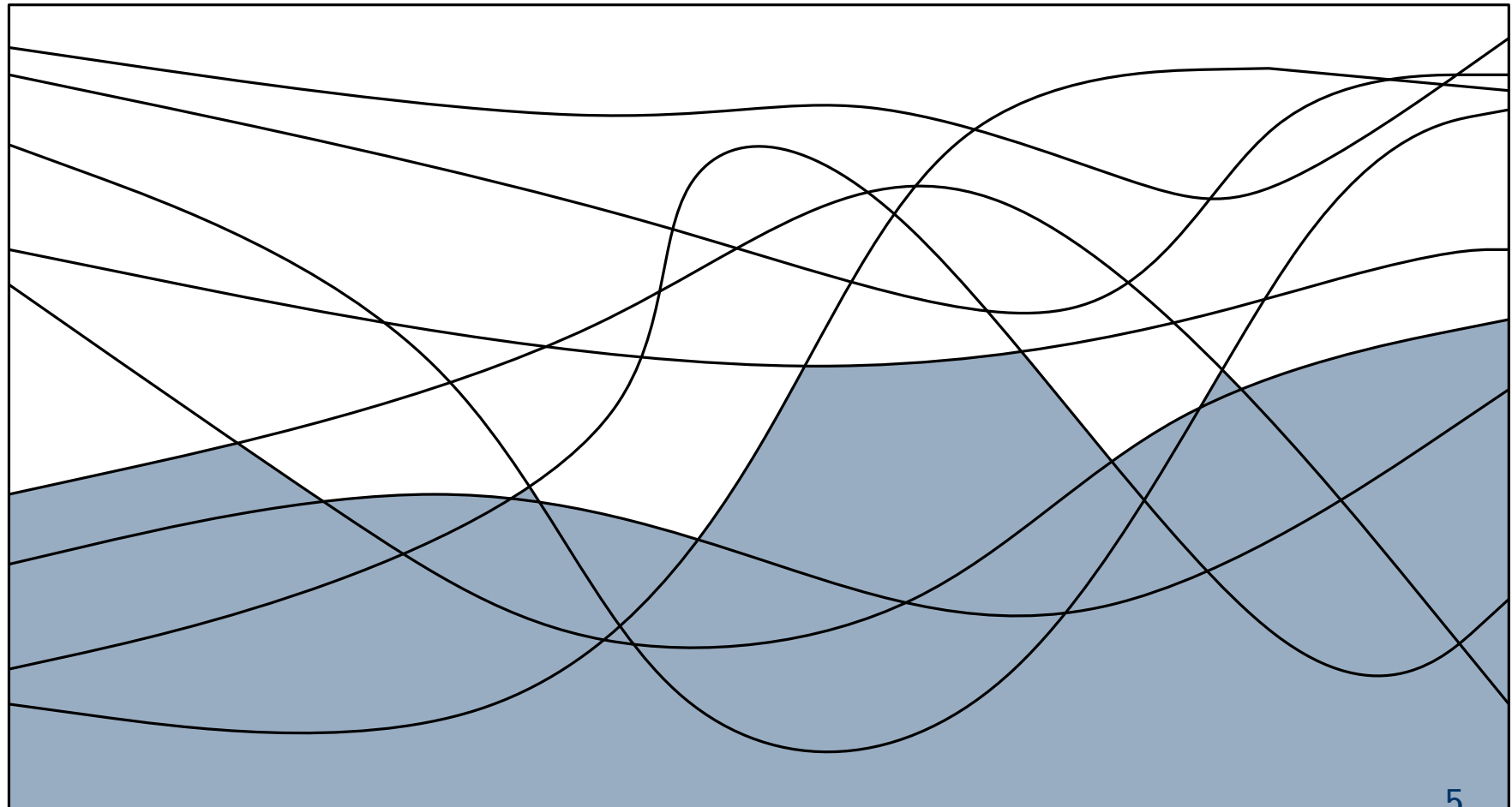
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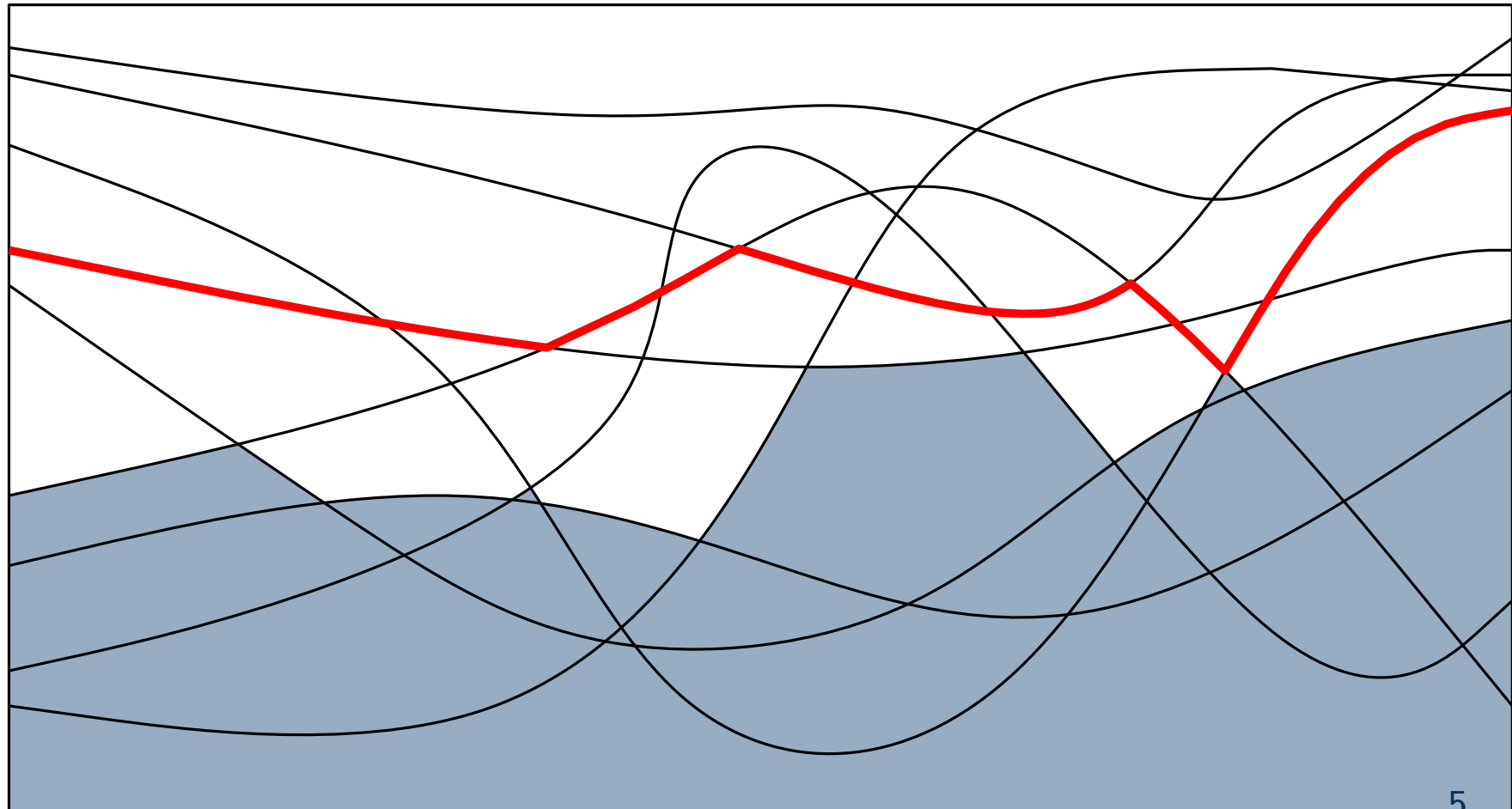
obtained from an x - y -monotone **terrain**



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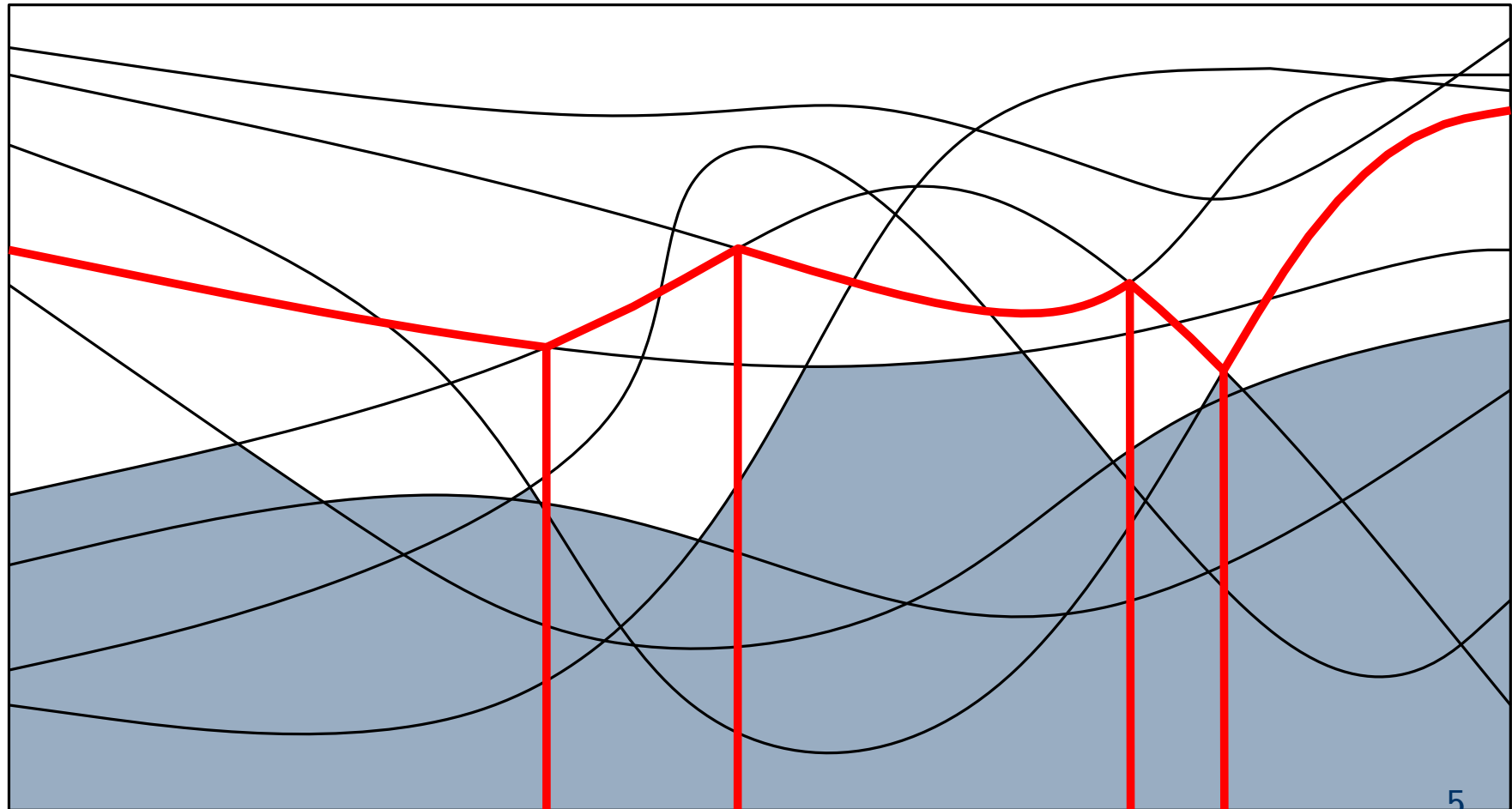
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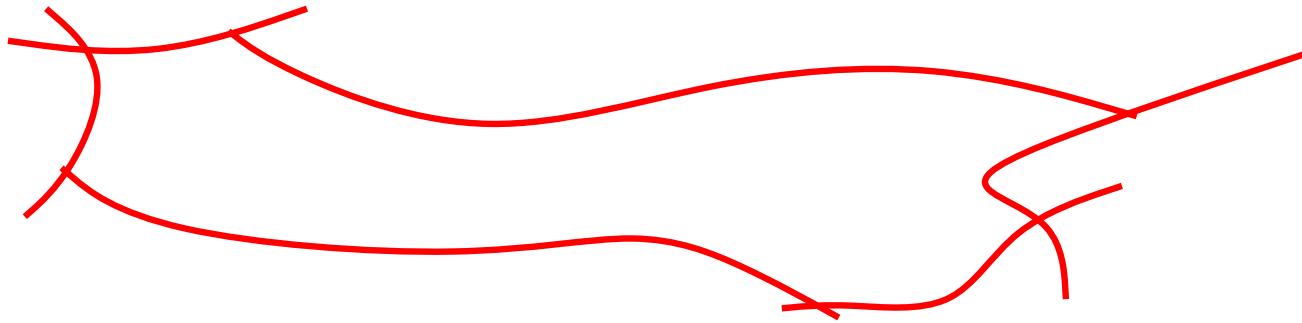


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3D

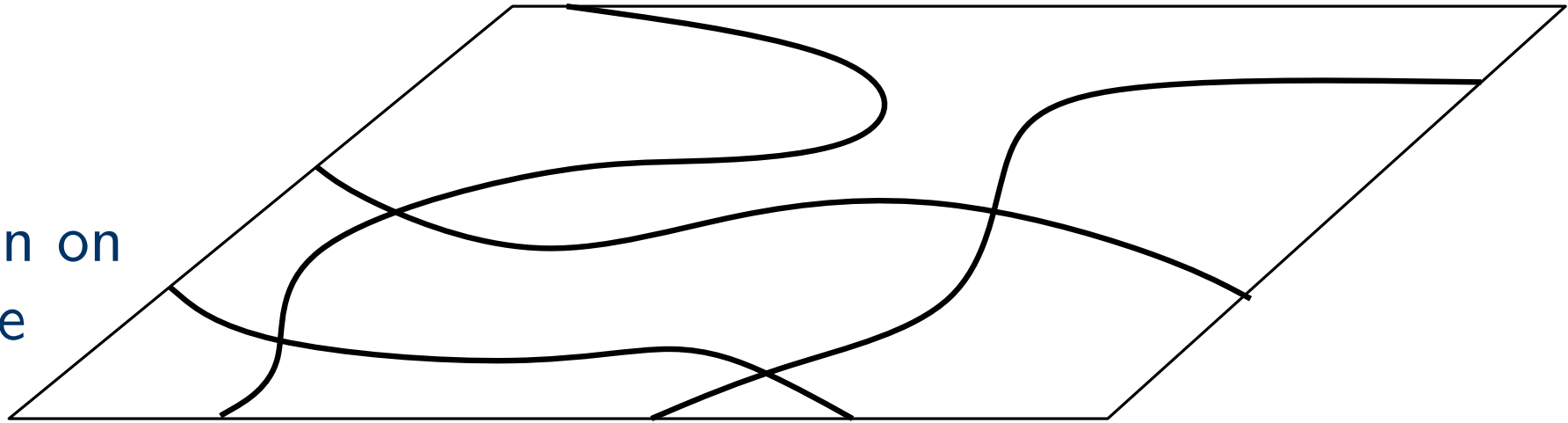


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projection on
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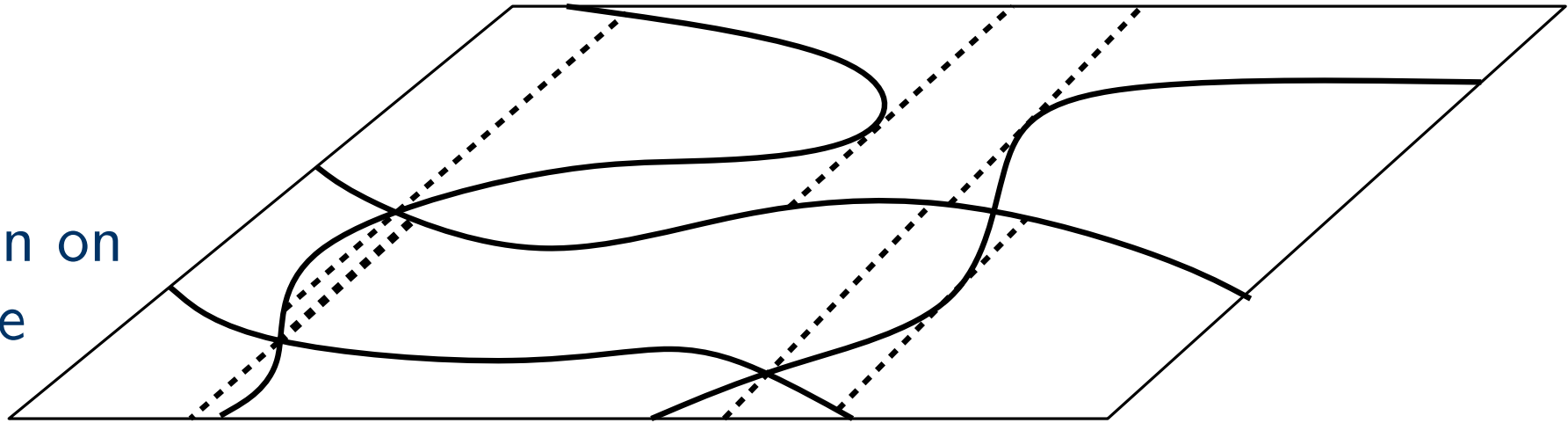


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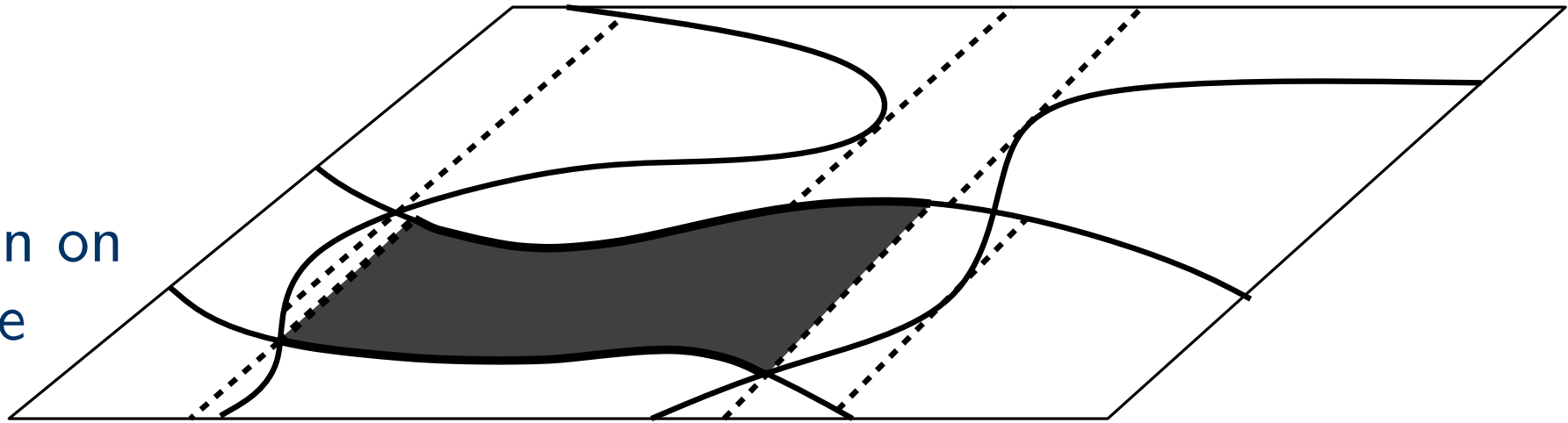


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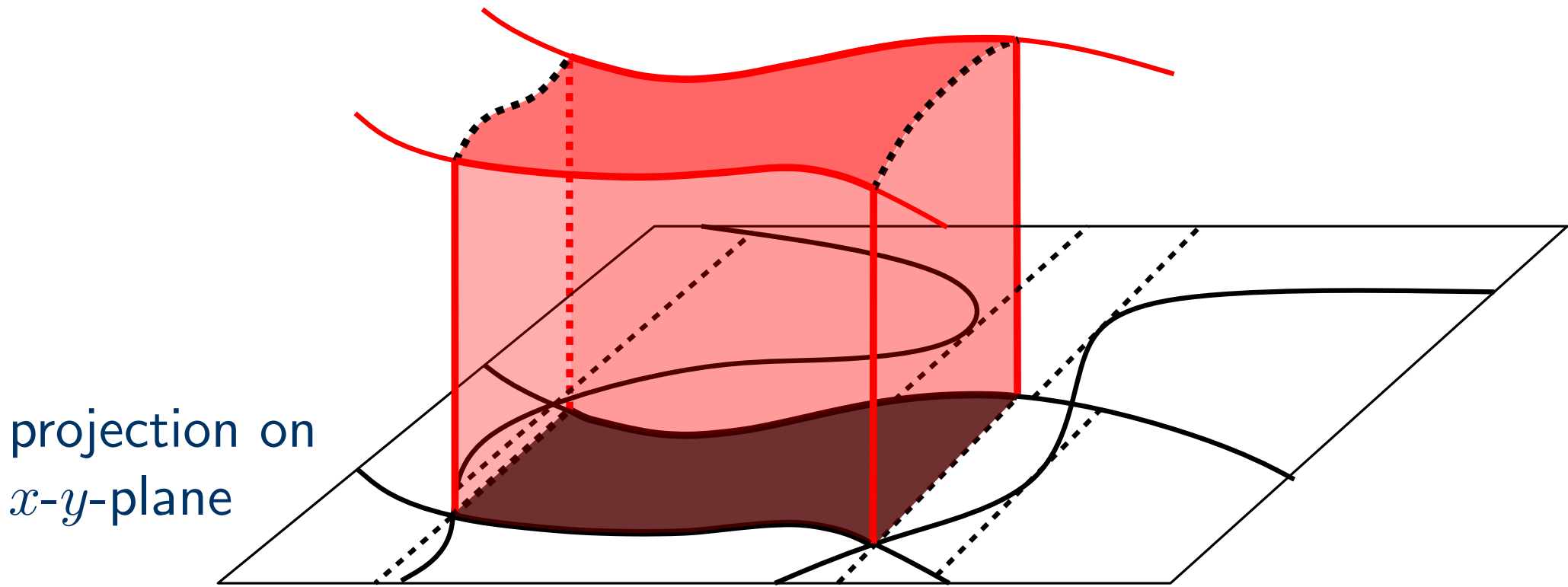
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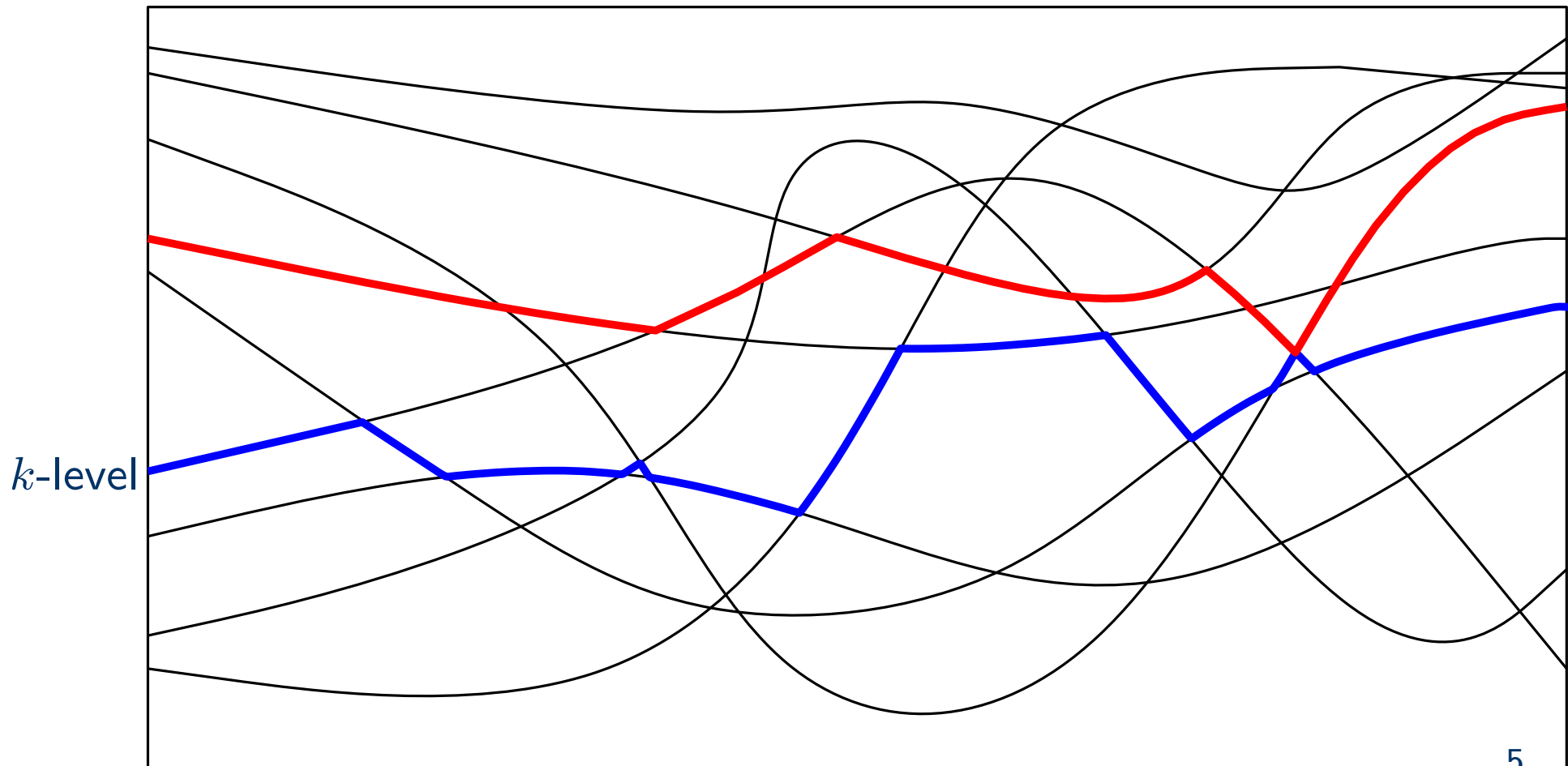
obtained from an x - y -monotone terrain



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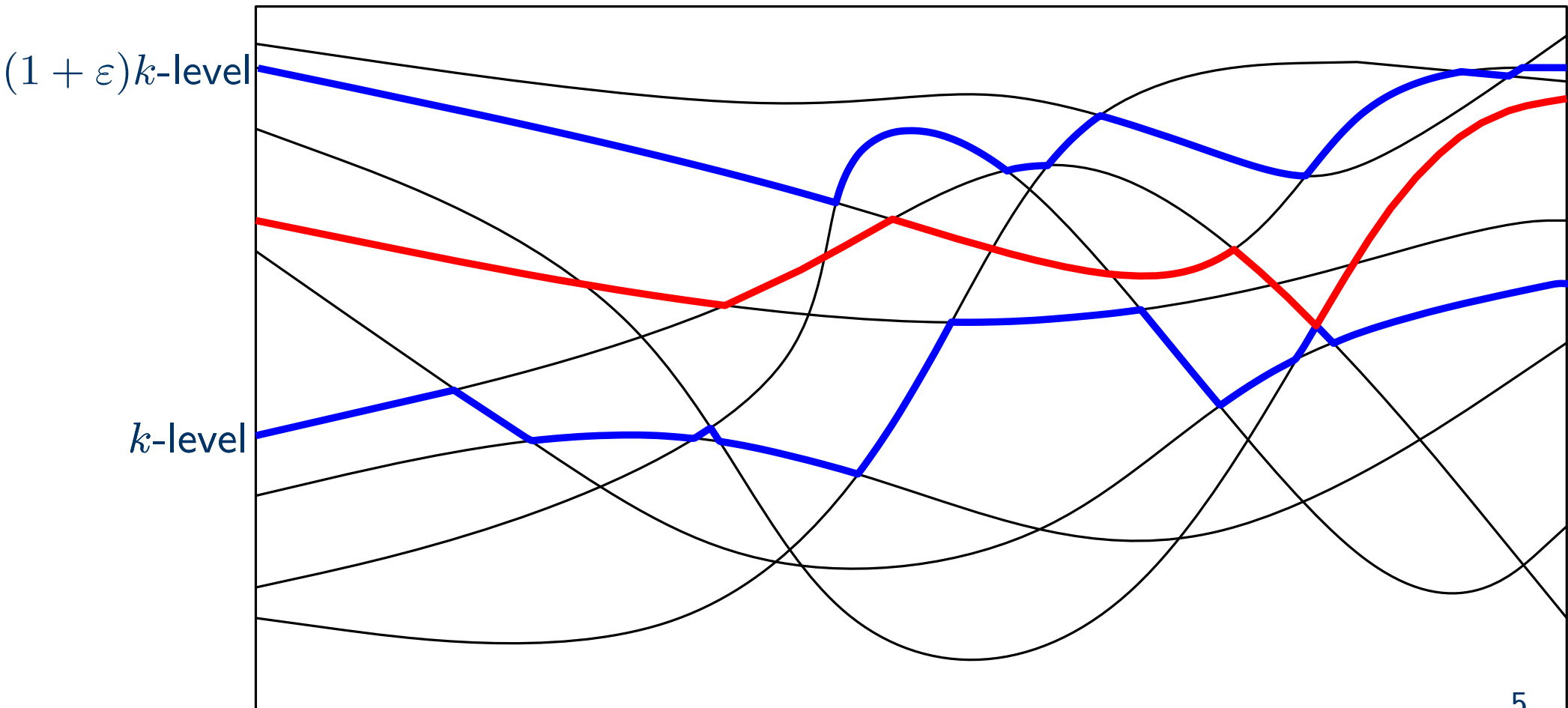
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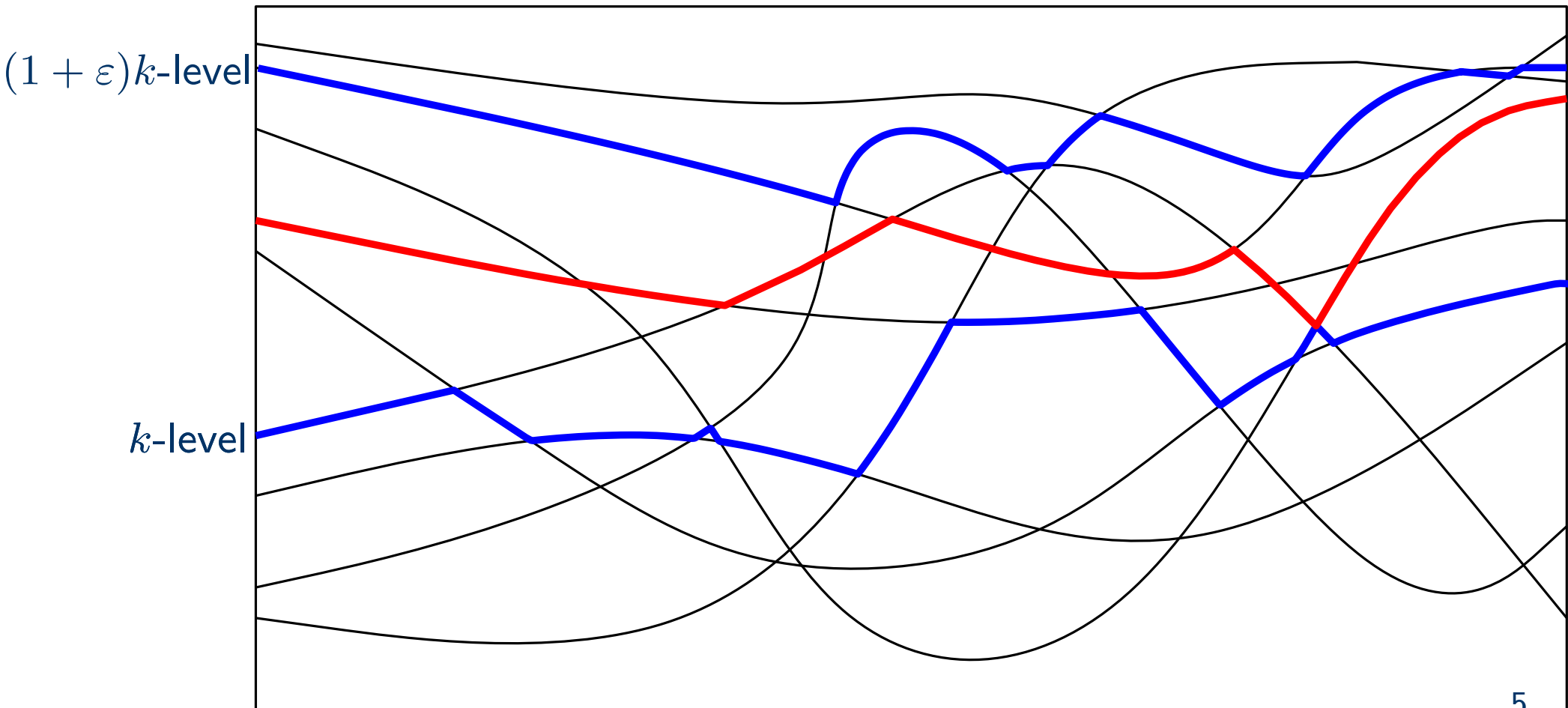
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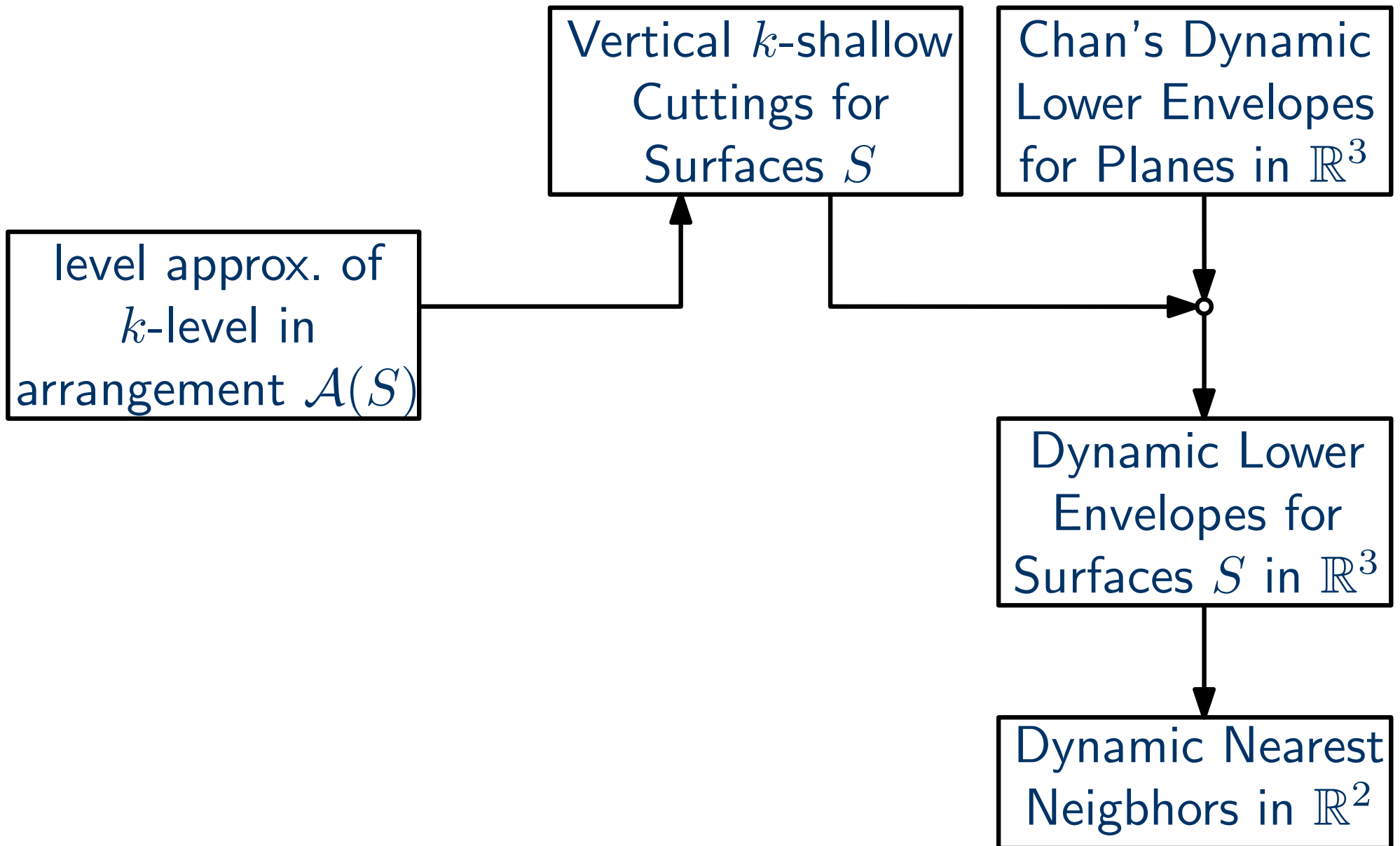


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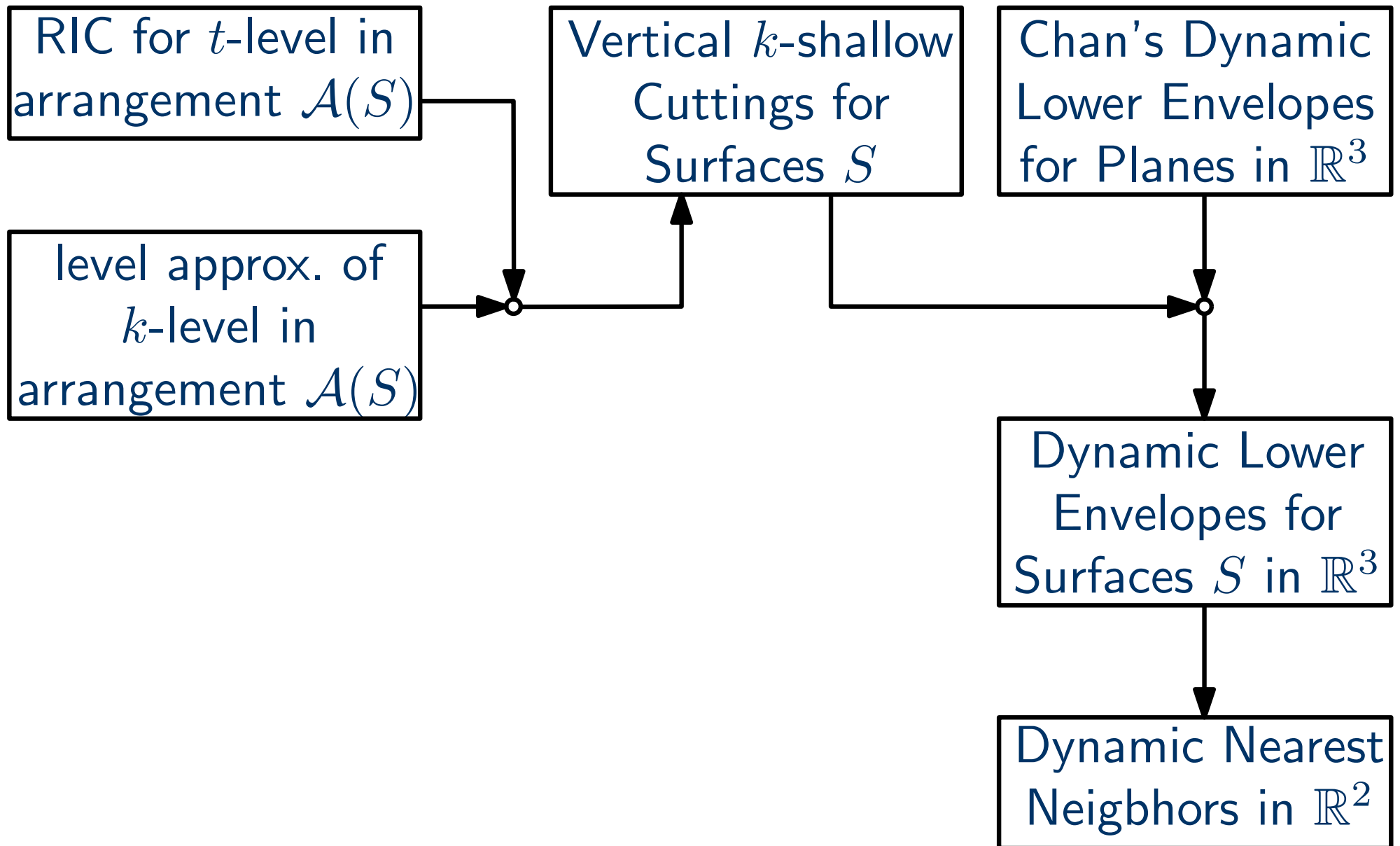
Theorem: The $t = O(\log n)$ -level of a sample of size $O((n/k) \log n)$ yields a level approximation with **expected complexity** $O((n/k) \log^2 n)$



Overview

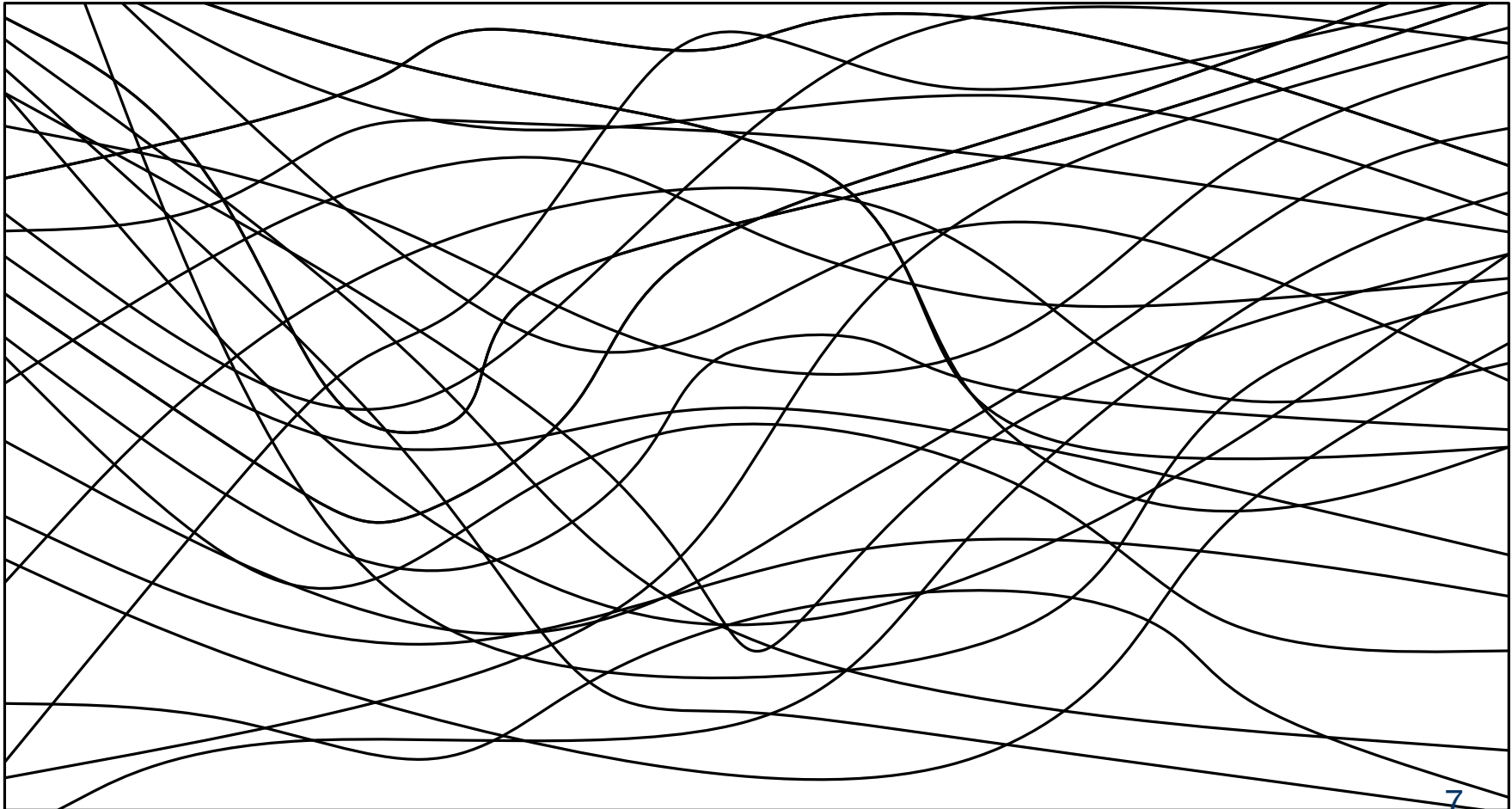


Overview



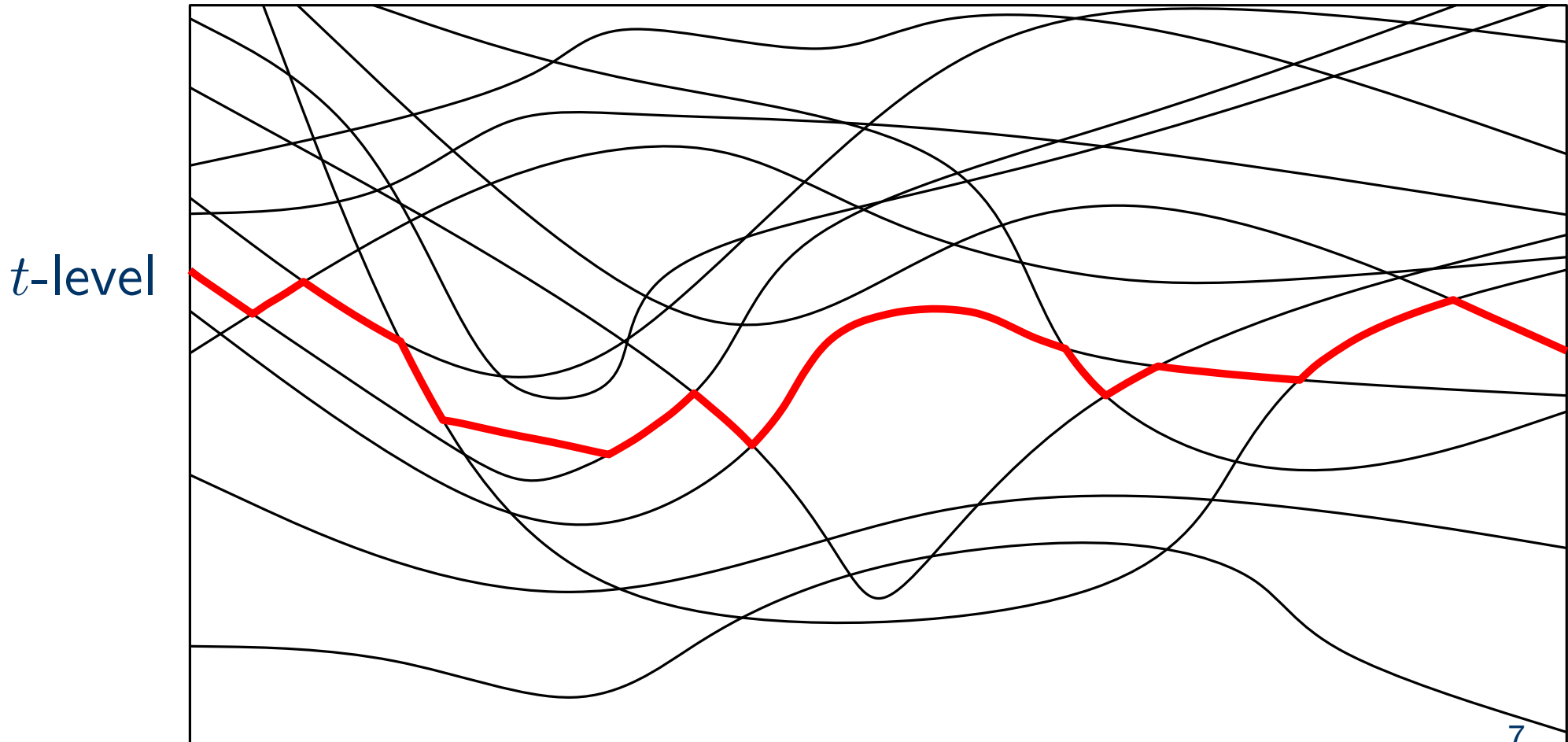
Randomized Incremental Construction

- Strategy:
- take rand. perm. $s_1, s_2, s_3, s_4, \dots, s_n$
 - perform RIC for $t = O(\log n)$ level of surfaces \mathcal{S}



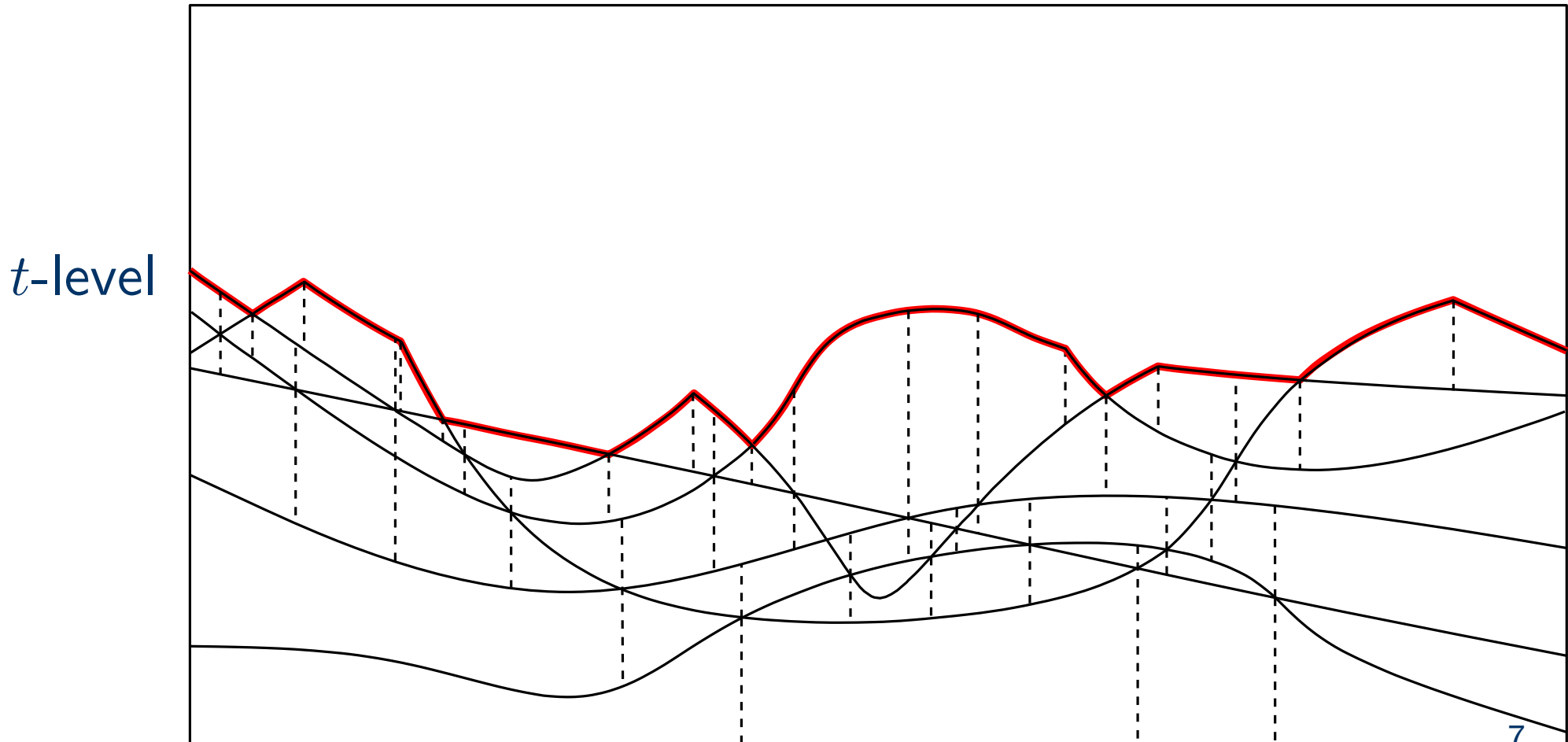
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 - stop after $O((n/k) \log n)$ steps



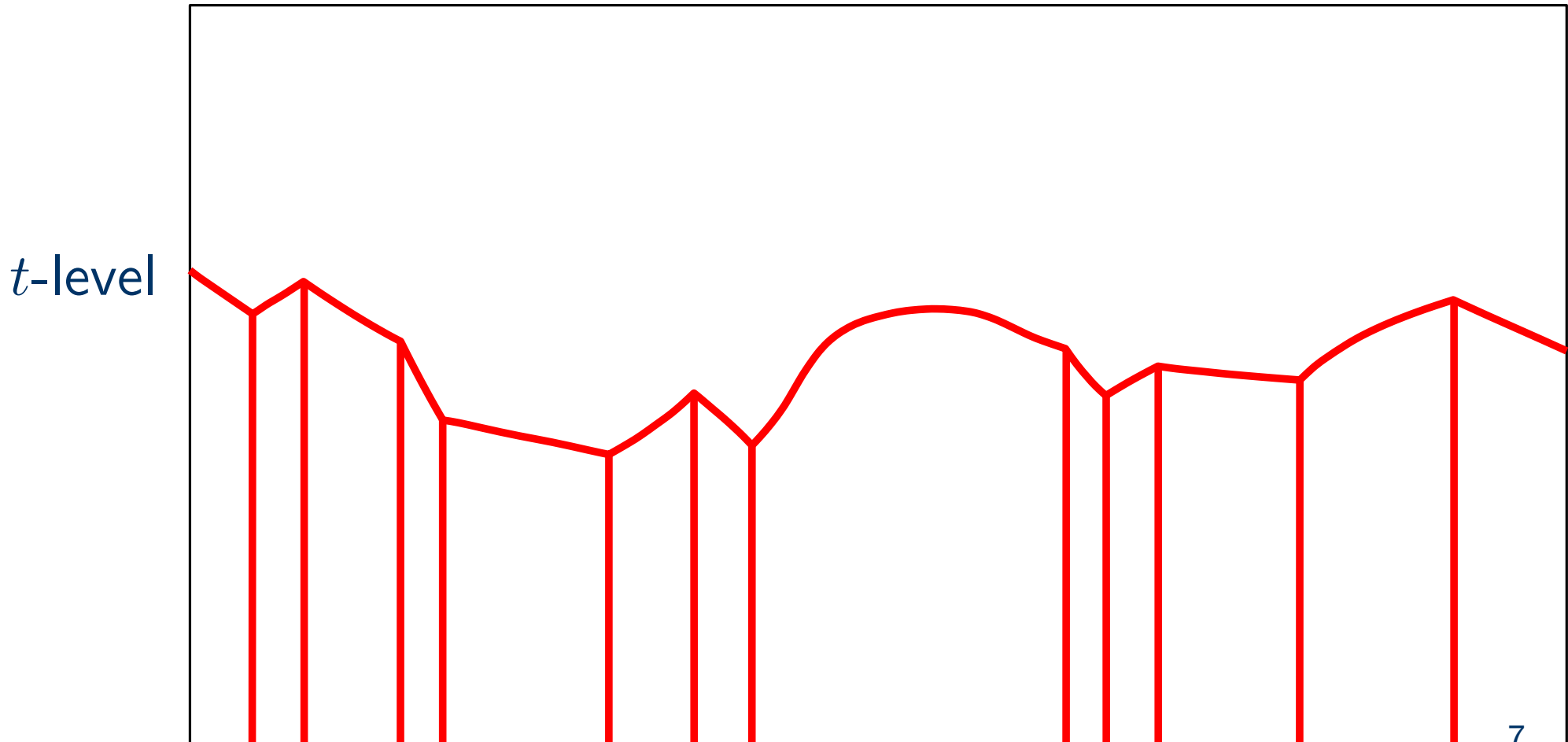
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 - perform RIC for $t = O(\log n)$ level of surfaces S
 - stop after $O((n/k) \log n)$ steps



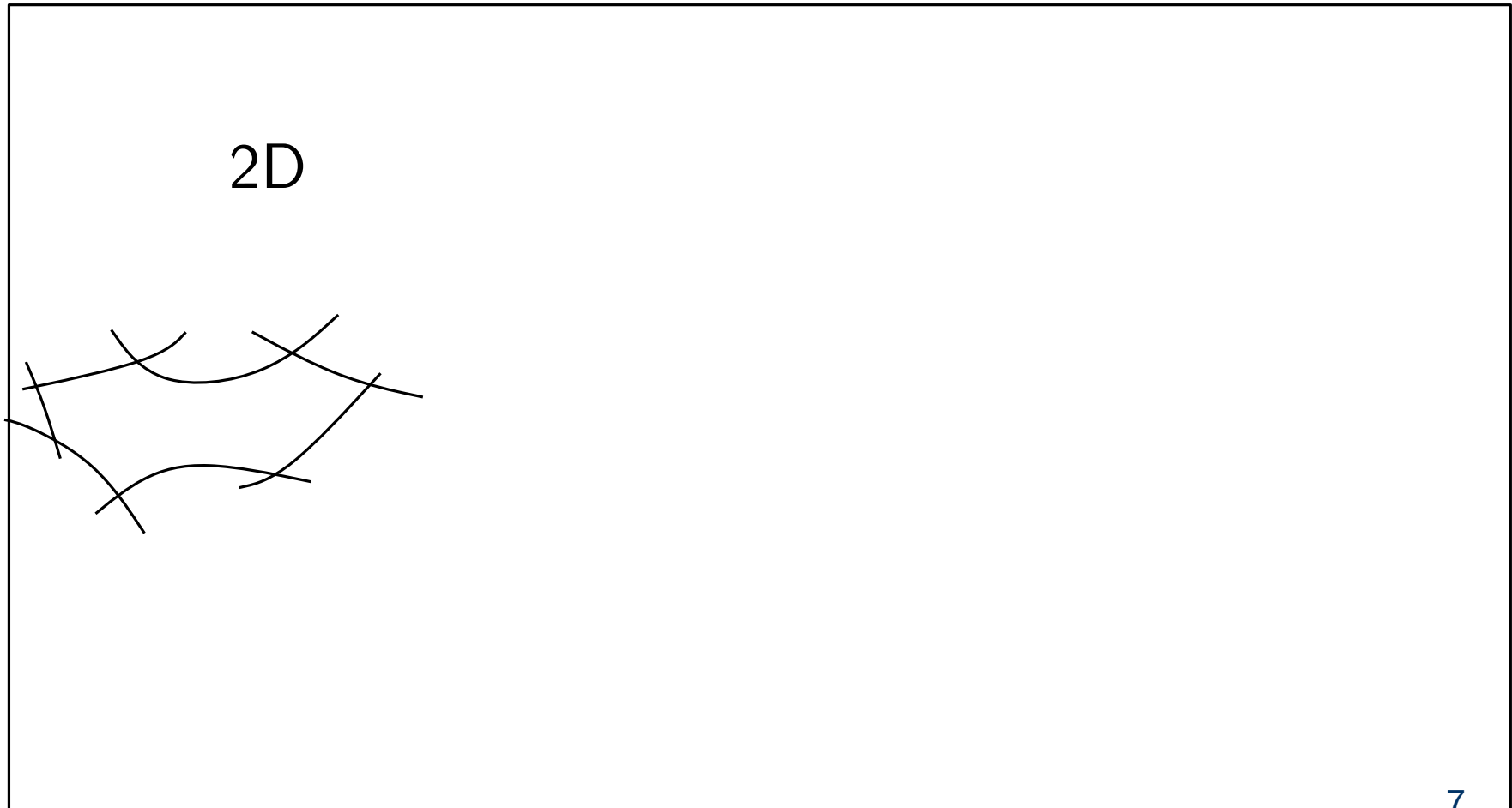
Randomized Incremental Construction

- Strategy:
- take rand. perm. $s_1, s_2, s_3, s_4, \dots, s_n$
 - perform RIC for $t = O(\log n)$ level of surfaces \mathcal{S}
 - stop after $O((n/k) \log n)$ steps



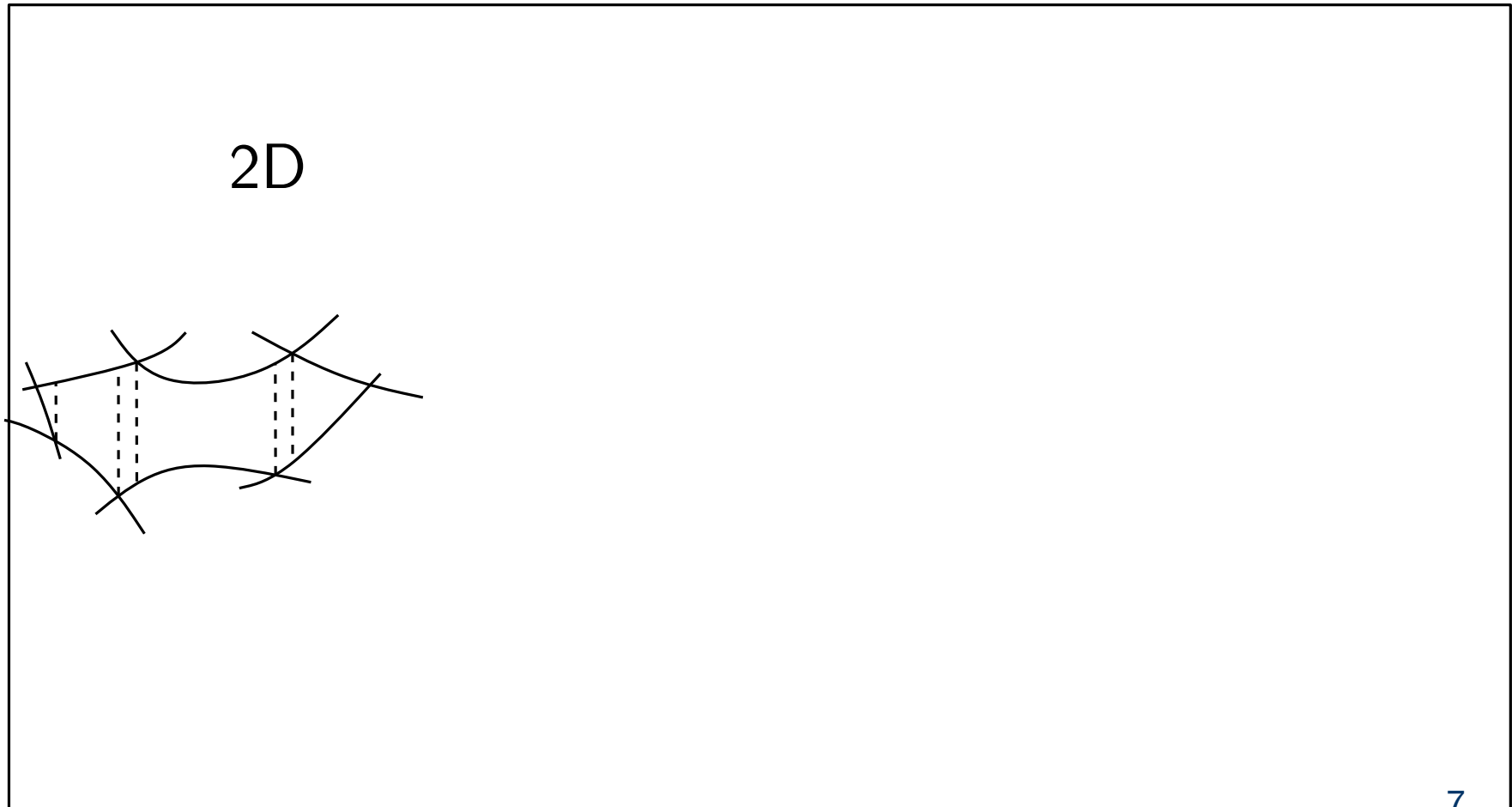
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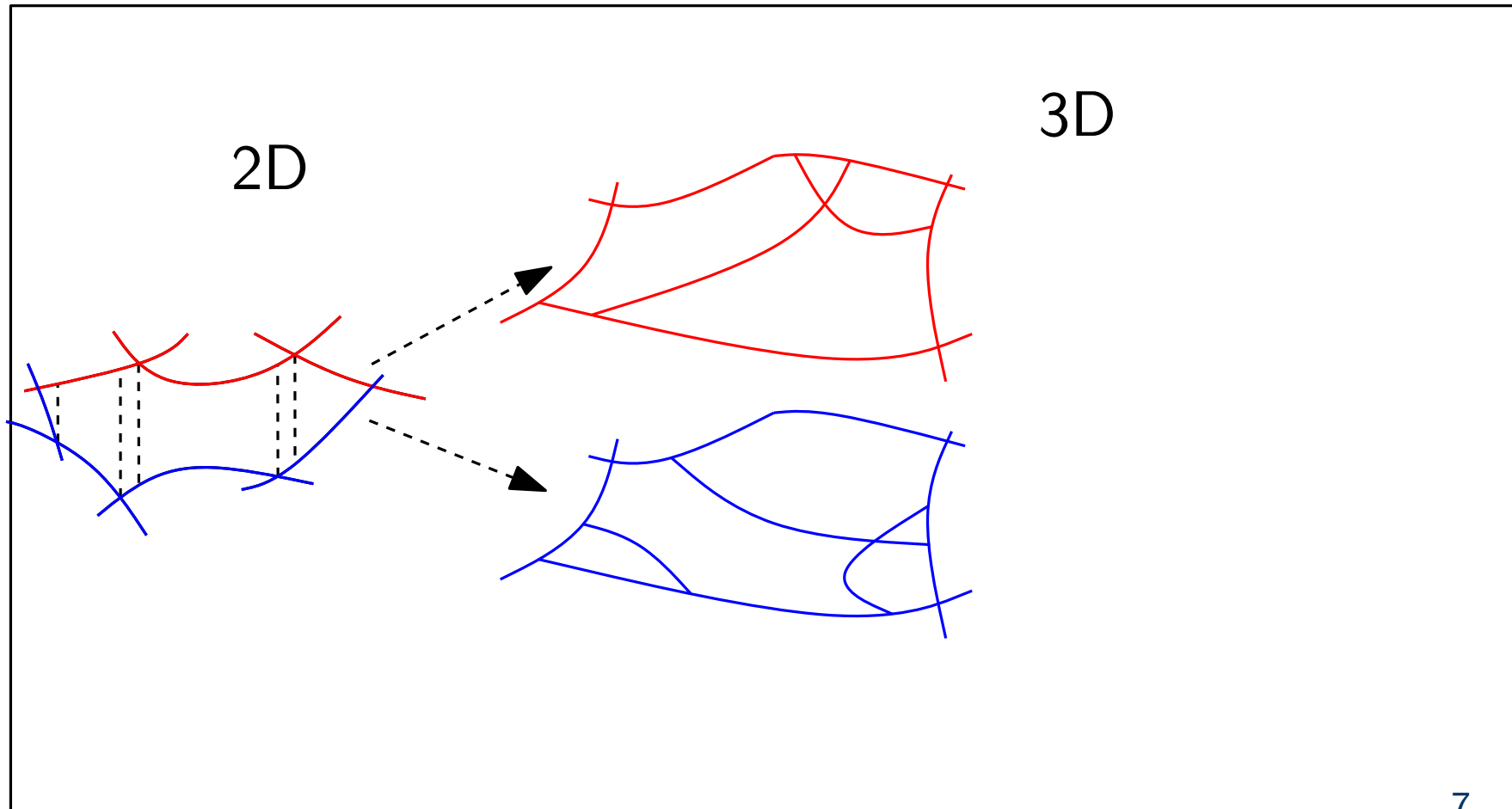
Randomized Incremental Construction

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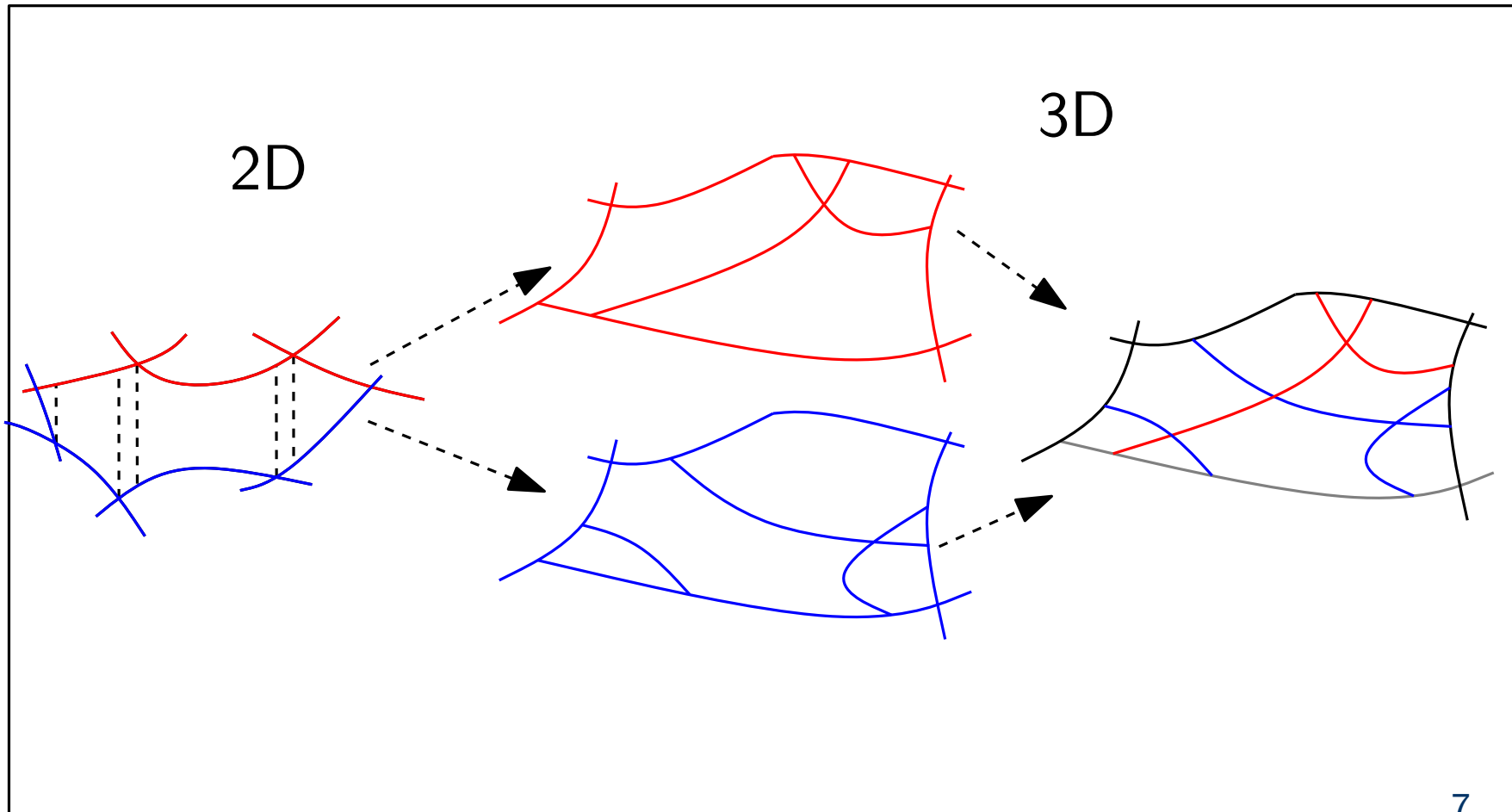
Randomized Incremental Construction

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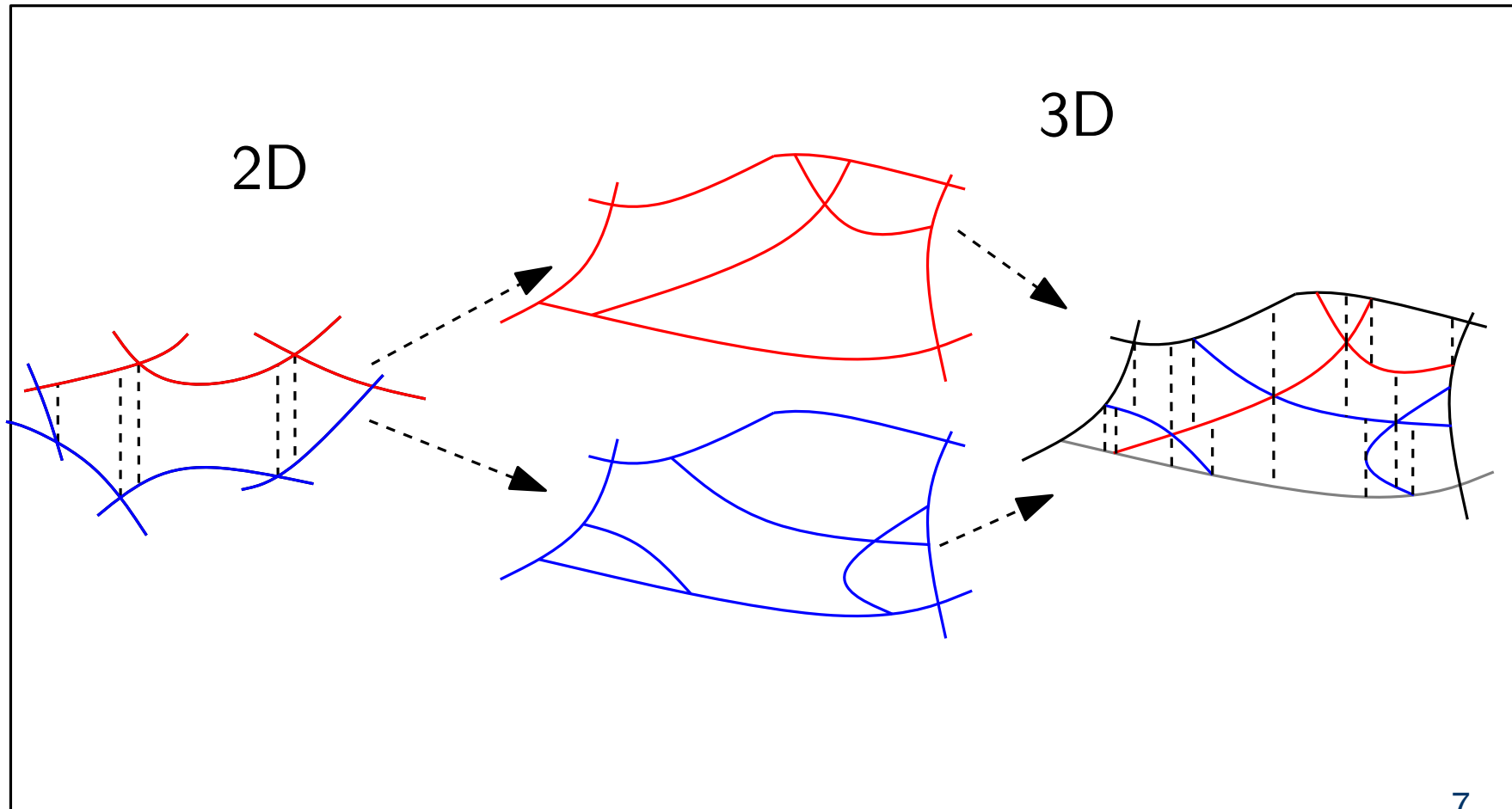
Randomized Incremental Construction

- Strategy:
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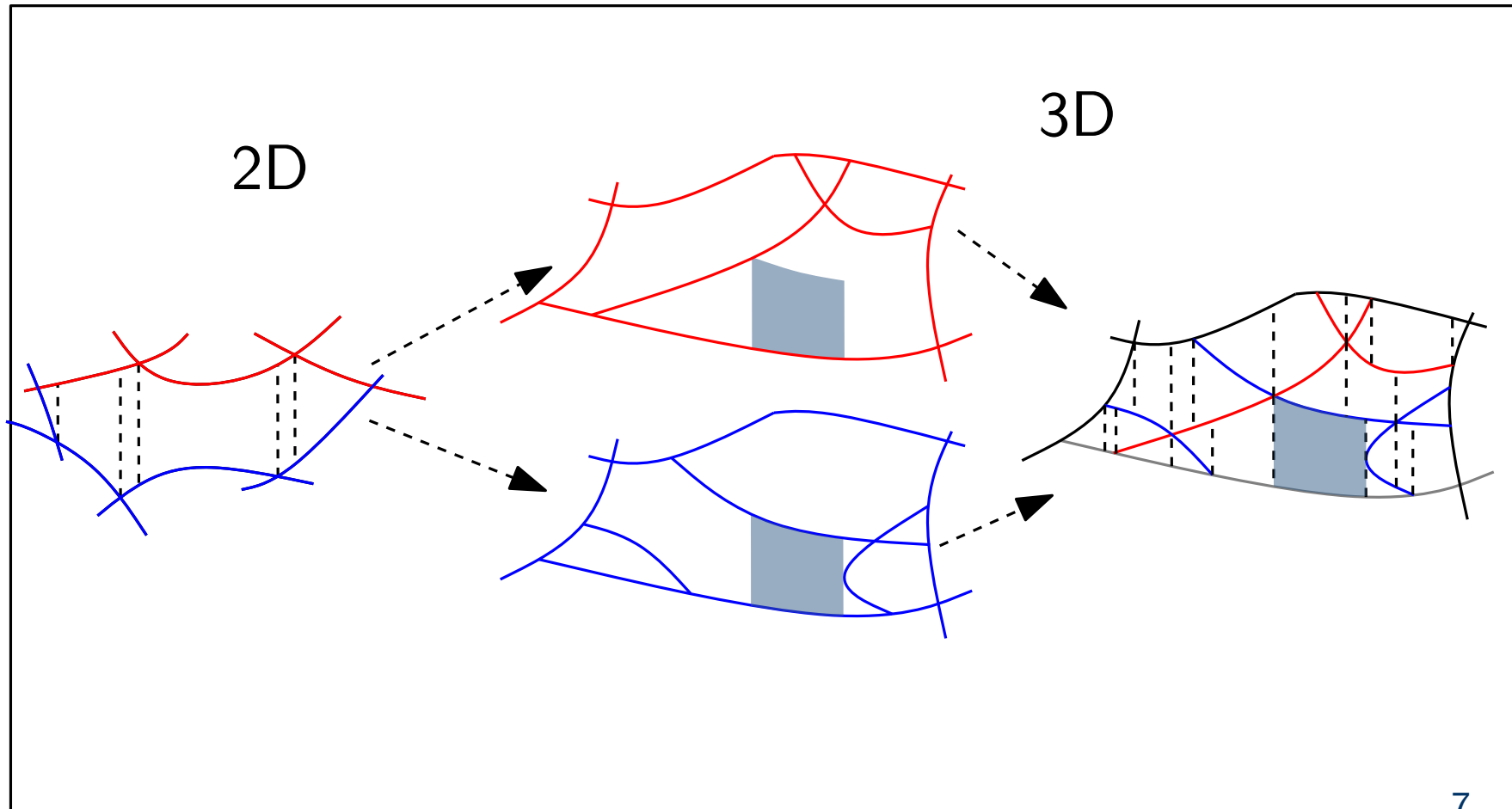
Randomized Incremental Construction

- Strategy:
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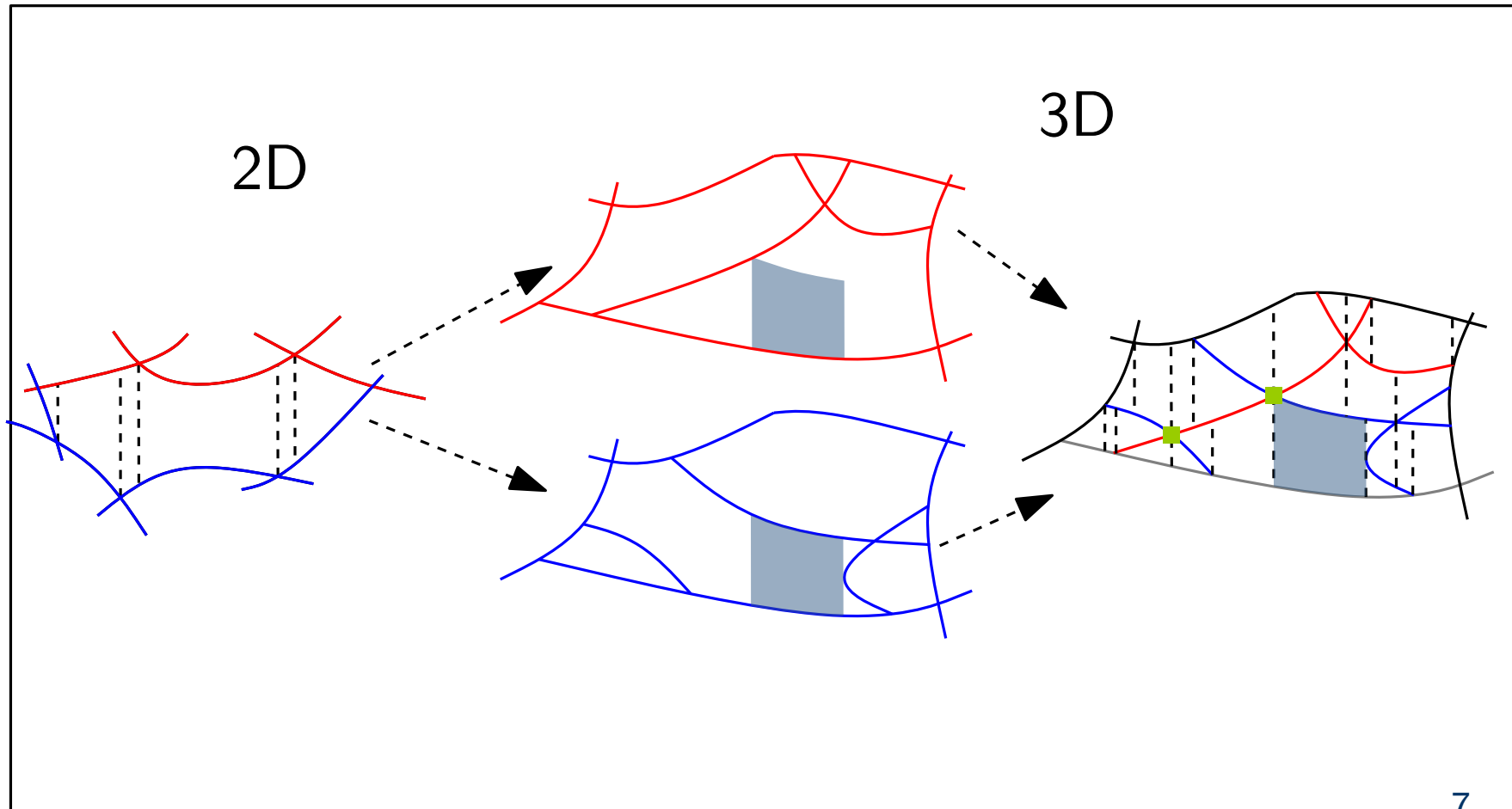
Randomized Incremental Construction

- Strategy:
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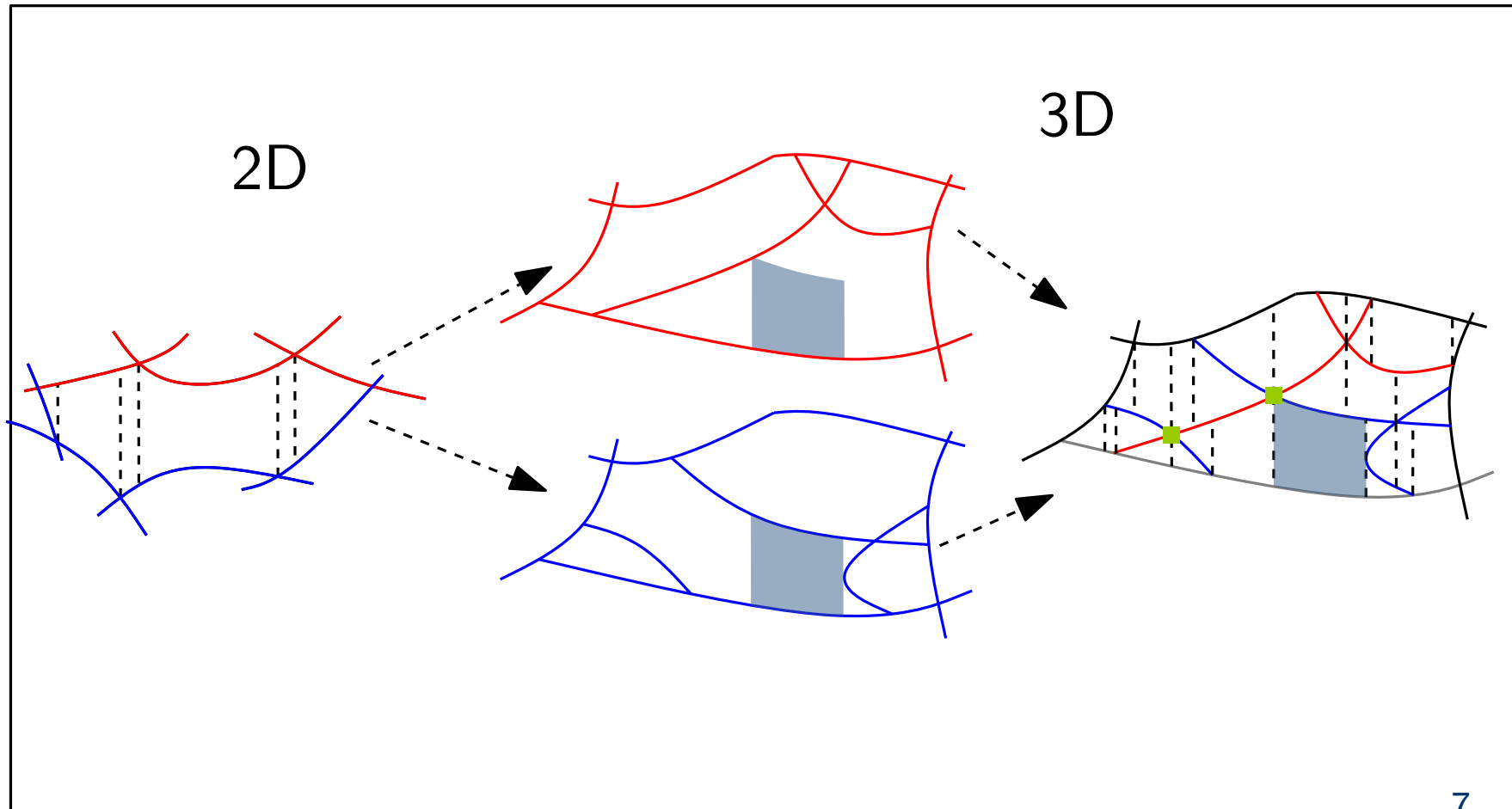
Randomized Incremental Construction

- Strategy:
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 - perform RIC for $t = O(\log n)$ level of surfaces S
 - stop after $O((n/k) \log n)$ steps



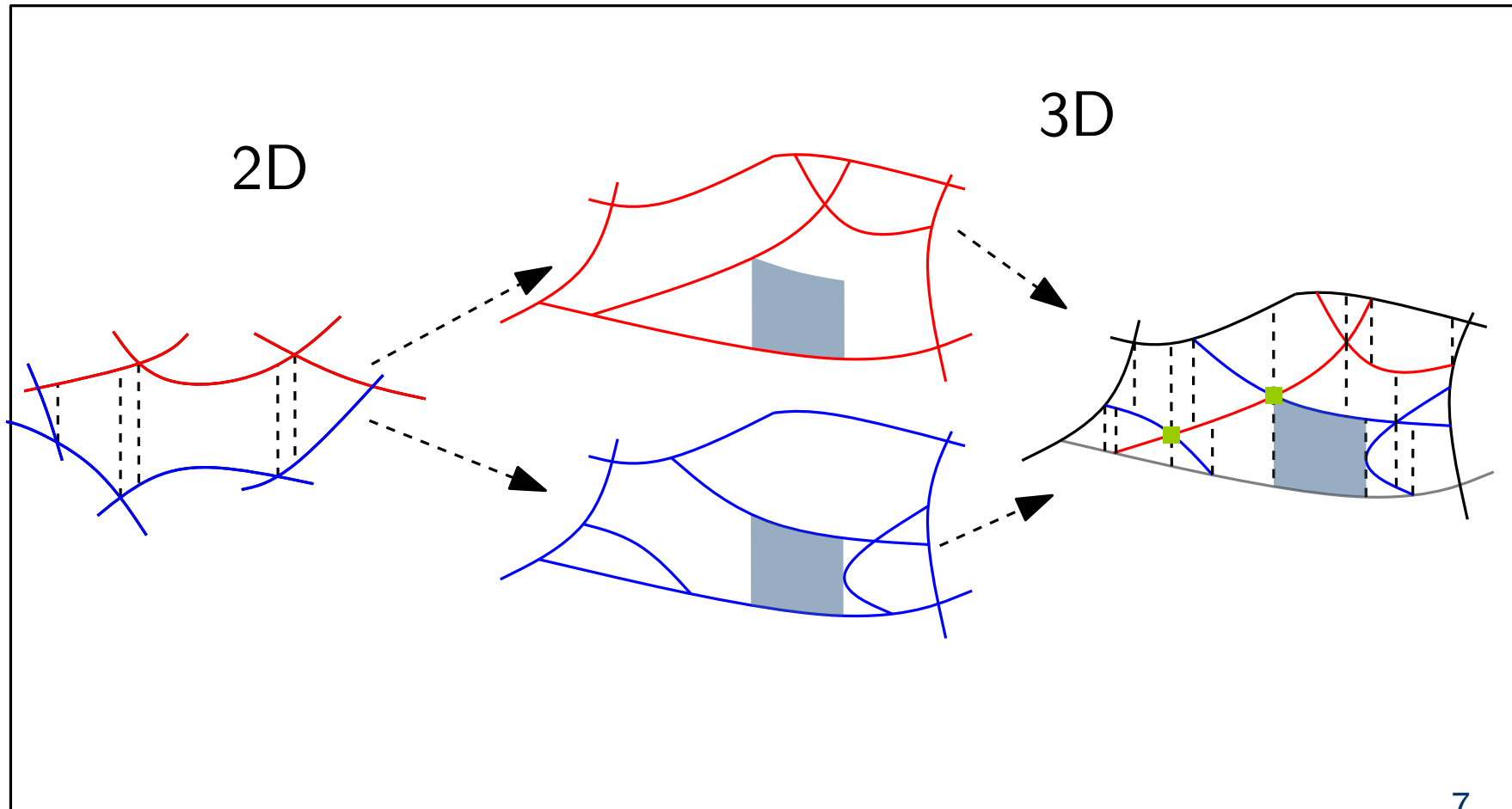
Randomized Incremental Construction

Theorem: The vertical decomposition of the $\leq t$ level of $\mathcal{A}(S)$ has complexity $O(nt\lambda_{s+2}(t))$.

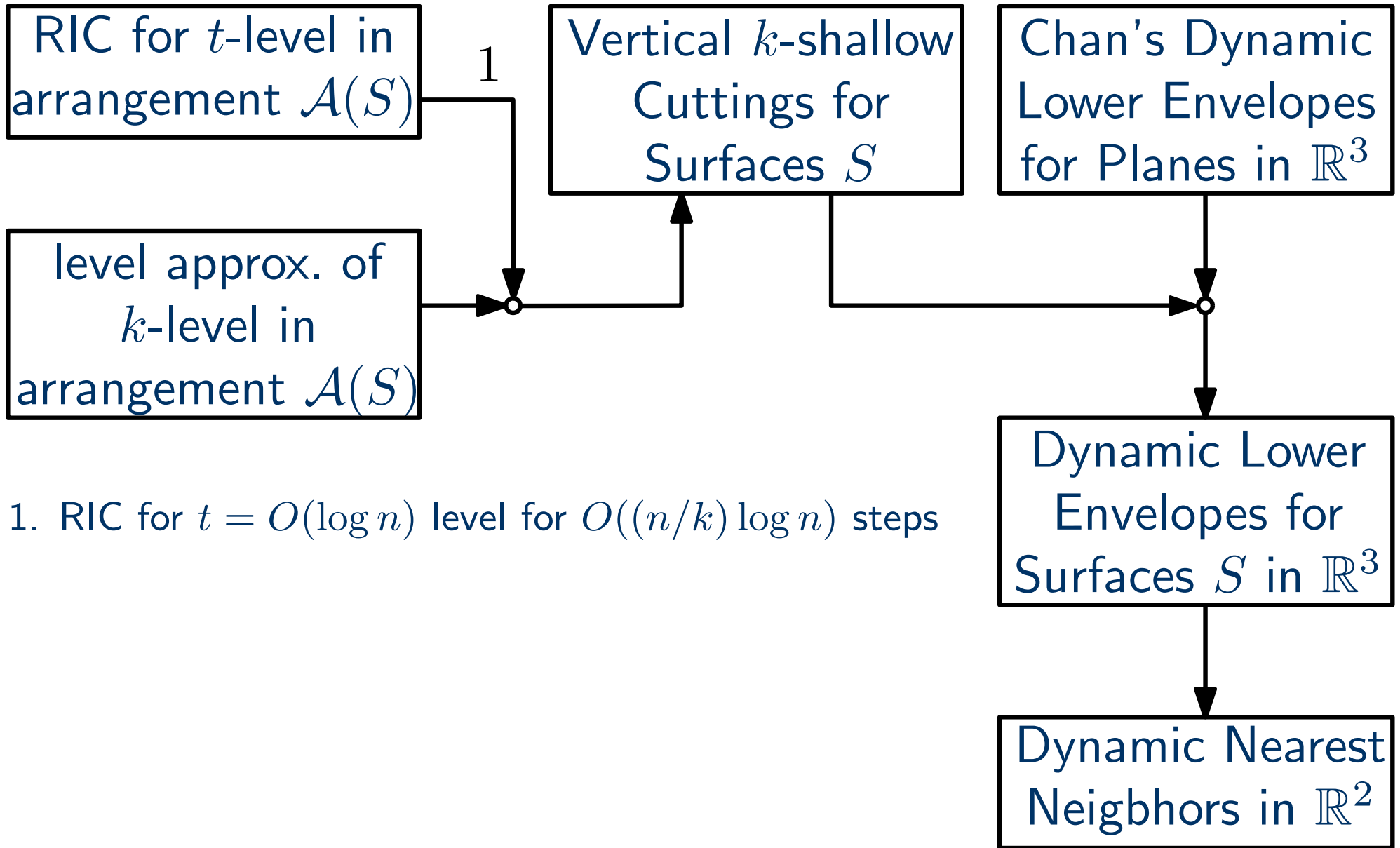


Randomized Incremental Construction

Theorem: Constructing the $\leq t$ -level of $\mathcal{A}(S)$ takes $O(nt^2 \text{polylog}(n))$ expected time.

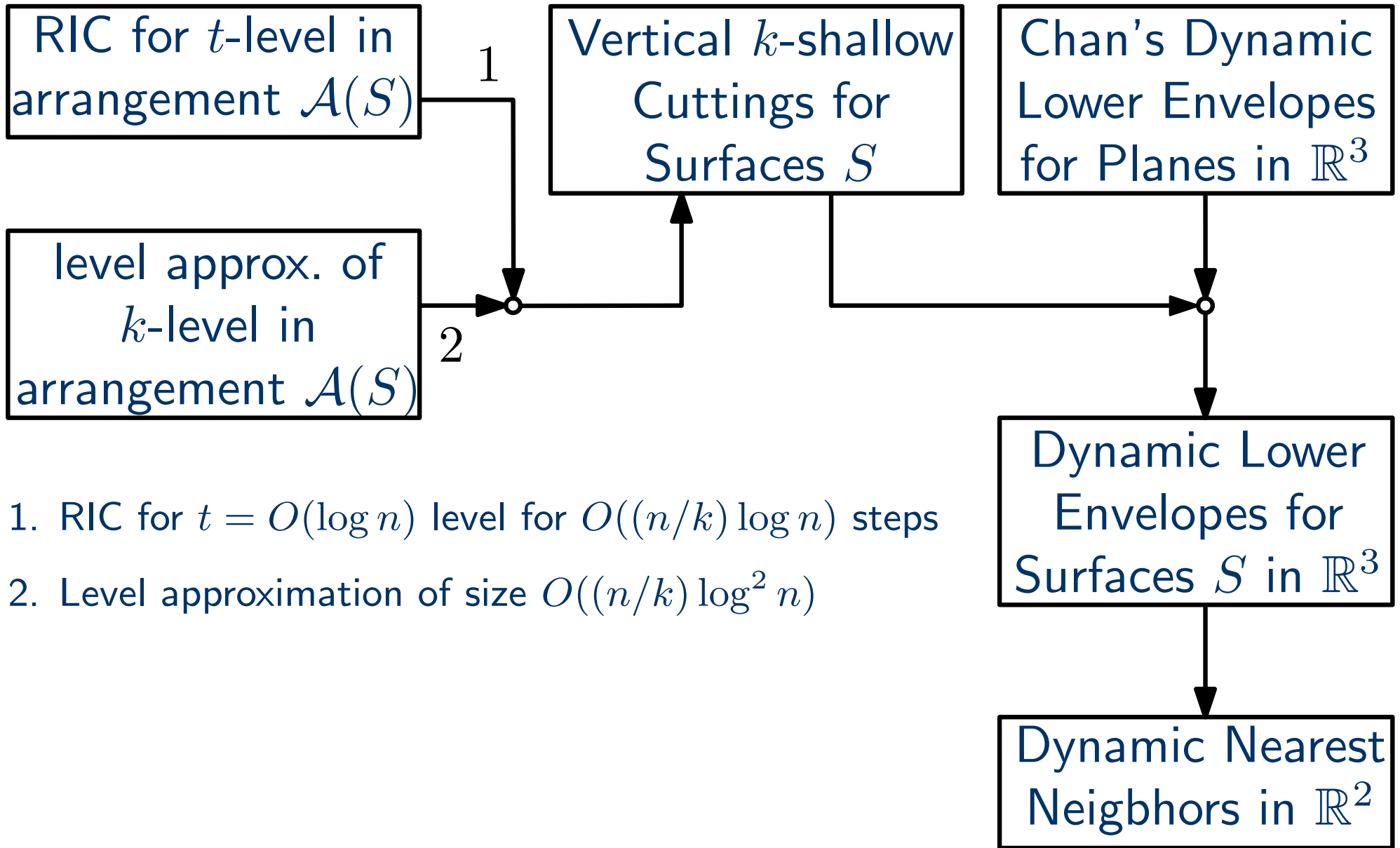


Overview



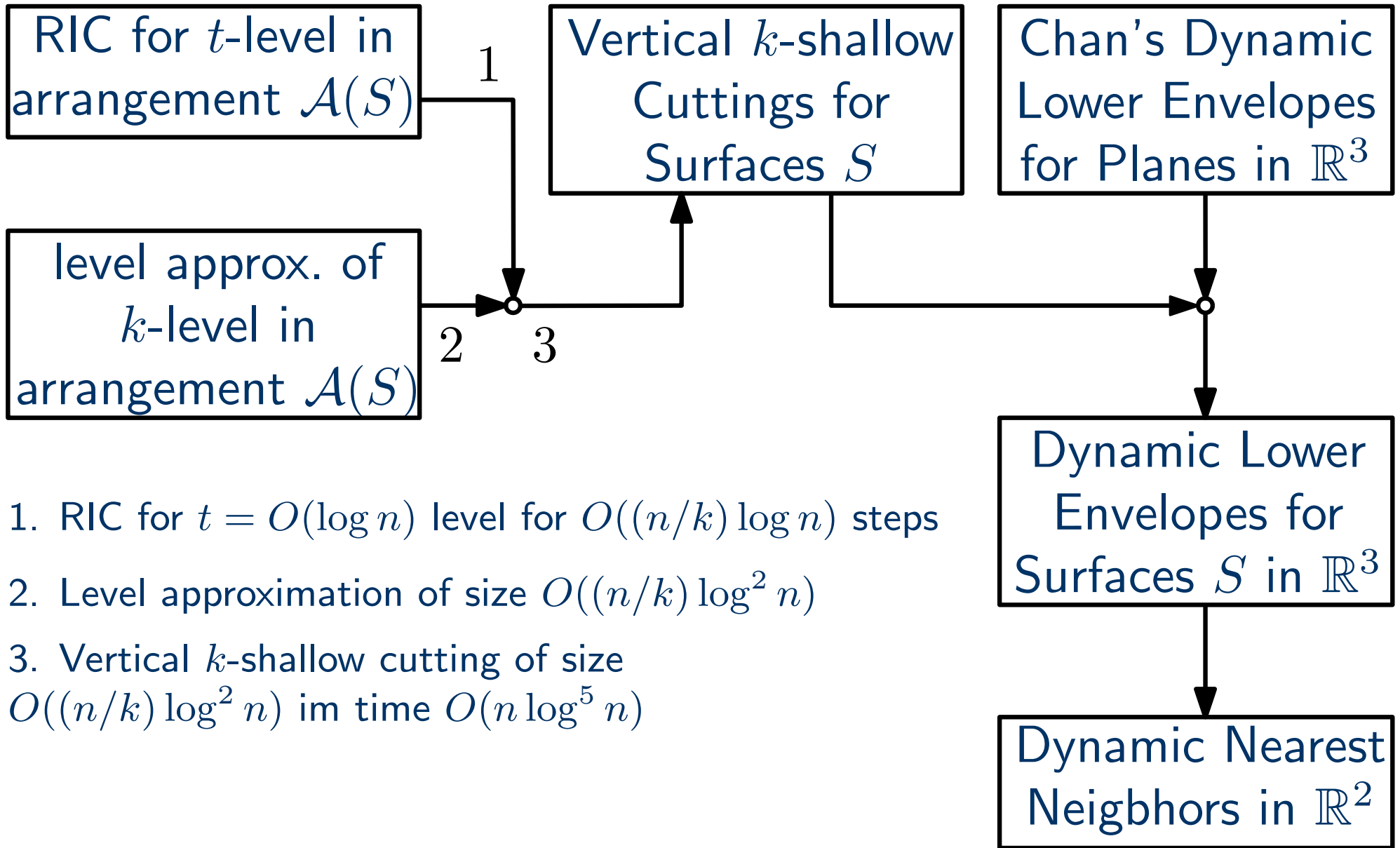
1. RIC for $t = O(\log n)$ level for $O((n/k) \log n)$ steps

Overview



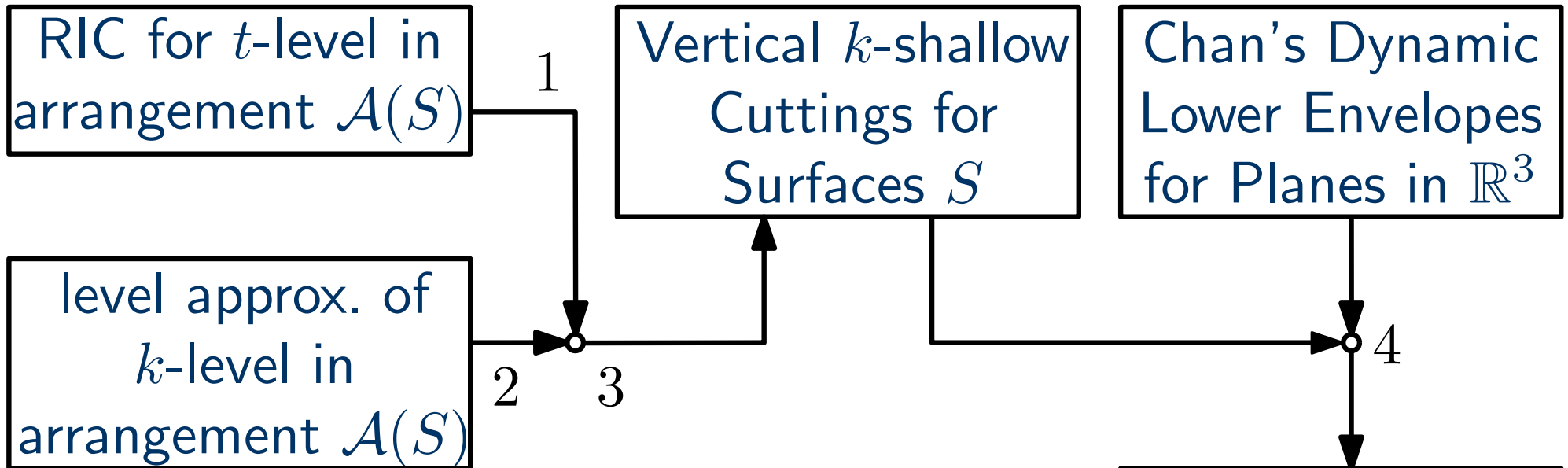
1. RIC for $t = O(\log n)$ level for $O((n/k) \log n)$ steps
2. Level approximation of size $O((n/k) \log^2 n)$

Overview



1. RIC for $t = O(\log n)$ level for $O((n/k) \log n)$ steps
2. Level approximation of size $O((n/k) \log^2 n)$
3. Vertical k -shallow cutting of size $O((n/k) \log^2 n)$ in time $O(n \log^5 n)$

Overview



1. RIC for $t = O(\log n)$ level for $O((n/k) \log n)$ steps
2. Level approximation of size $O((n/k) \log^2 n)$
3. Vertical k -shallow cutting of size $O((n/k) \log^2 n)$ in time $O(n \log^5 n)$
4. Dynamic Lower Envelopes with
 - insertions $O(\log^7 n)$ (am. exp.)
 - deletions: $O(\log^{11} n)$ (am. exp.)
 - queries: $O(\log^2 n)$ (w.c.)

Dynamic Lower Envelopes for Surfaces S in \mathbb{R}^3

Dynamic Nearest Neighbors in \mathbb{R}^2