

# Transition Path Theory

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## 1 Basic Definitions

Let  $X = \{1, \dots, m\}$  be a discrete state space and let  $X(t)$  be a Markov chain, where  $t$  may be either discrete or continuous.

### 1.1 Time-Discrete Markov Chain

with propagator / transition matrix  $P \in \mathbb{R}^{m \times m}$ :

$$\begin{aligned} p_{ij} &\geq 0 \quad \forall i, j \\ \sum_{j=1 \dots m} p_{ij} &= 1 \quad \forall i \end{aligned}$$

Unless the system is inherently time-discrete, the meaning of  $p_{ij}$  is that it represents the transition probability of state  $i$  to state  $j$  within time  $\tau$ :

$$p_{ij} = \mathbb{P}[X(t + \tau) = j \mid X(t) = i]$$

$P$  has a single eigenvalue of 1 and otherwise eigenvalues in  $(-1, \dots, 1)$ . When  $\mu(t) \in \mathbb{R}^m$  is a probability vector,  $P$  can be used to transport this probability vector:

$$\mu(t + n\tau) = \mu(t)P^n(\tau).$$

If  $P$  is irreducible it has a stationary distribution given by

$$\pi = \pi P$$

The backward propagator is defined as:

$$\tilde{p}_{ij} = \frac{\pi_j}{\pi_i} p_{ji}$$

If  $P$  is furthermore reversible it fulfills the detailed balance equation:

$$\begin{aligned}\tilde{p}_{ij} &= p_{ij} \forall i, j \\ \pi_i p_{ij} &= \pi_j p_{ji} \forall i, j.\end{aligned}$$

## 1.2 Time-continuous Markov Chain

with generator / rate matrix  $L \in \mathbb{R}^{m \times m}$ :

$$\begin{aligned}l_{ij} &\geq 0 \forall i \neq j \\ l_{ii} &= - \sum_{i \neq j} l_{ij} \forall i\end{aligned}$$

$l_{ij}$  is the rate of change from  $i$  to  $j$  in infinitesimal time and has therefore no parameter  $\tau$ .  $L$  has a single eigenvalue of 0 and otherwise negative eigenvalues. When  $\mu(t) \in \mathbb{R}^m$  is a probability vector,  $L$  can be used to compute the change of this probability vector:

$$\frac{d\mu(t)}{dt} = \mu(t)L$$

If  $L$  is irreducible it has a stationary distribution given by

$$0 = \pi L$$

The backward generator is defined as:

$$\tilde{l}_{ij} = \frac{\pi_j}{\pi_i} l_{ji}$$

If  $P$  is furthermore reversible it fulfills the detailed balance equation:

$$\begin{aligned}\tilde{l}_{ij} &= l_{ij} \forall i, j. \\ \pi_i l_{ij} &= \pi_j l_{ji} \forall i, j.\end{aligned}$$

$P$  and  $L$  are related via

$$P(\tau) = \exp(\tau L).$$

Thus for every generator we can derive a unique transition matrix, but the inverse is not always possible. The generator can be obtained *via* following limit if it exists:

$$L = \lim_{\tau \rightarrow 0^+} \frac{P(\tau) - I}{\tau}$$

The generator corresponding to the time-discrete Markov process with  $\tau = 1$  is

$$L_0 = P(\tau) - I$$

also known as pseudogenerator.

## 2 Ingredients

### 2.1 Hitting probabilities for Time-Discrete Markov Chains

Hitting time of  $A$ :  $H^A : \Omega \rightarrow \{0, 1, 2, \dots\} \cup \{\infty\}$ :

$$H^A(\omega) = \inf\{n \geq 0 : X_n(\omega) \in A\}$$

Hitting probability: The probability that starting from  $i$  we ever hit  $A$  is:

$$h_i^A = \mathbb{P}_i(H^A < \infty).$$

The vector of hitting probabilities  $h^A = (h_i^A : i \in I)$  is the minimal non-negative solution to the system of linear equations:

$$\begin{aligned} h_i^A &= 1 \text{ for } i \in A \\ h_i^A &= \sum_{j \in I} p_{ij} h_j^A \text{ for } i \notin A. \end{aligned}$$

(Minimality means that if  $x = (x_i : i \in S)$  is another solution with  $x_i \geq 0$  for all  $i$ , then  $x_i \geq h_i$  for all  $i$ .)

**Proof:**

First we show that  $h^A$  satisfies the above equation.

- 1) If  $X_0 = i \in A$ , then  $H^A = 0$ , so  $h_i^A = 1$ .
- 2) If  $X_0 = i \notin A$ , then  $H^A \geq 1$ , so by the Markov property:

$$\mathbb{P}_i(H^A < \infty \mid X_1 = j) = \mathbb{P}_j(H^A < \infty) = h_j^A$$

and

$$\begin{aligned} h_i^A &= \mathbb{P}_i(H^A < \infty) \\ &= \sum_{j \in I} \mathbb{P}_i(H^A < \infty, X_1 = j) \\ &= \sum_{j \in I} \mathbb{P}_i(H^A < \infty \mid X_1 = j) \mathbb{P}_i(X_1 = j) \\ &= \sum_{j \in I} h_j^A p_{ij}. \end{aligned}$$

Next, we show that  $h^A$  are the minimal solution

1) Suppose that  $x = (x_i : i \in I)$  is any solution to the equation. then  $h_i^A = x_i = 1$  for  $i \in A$ .

2) Suppose  $i \notin A$ , then:

$$x_i = \sum_{j \in I} p_{ij} x_j = \sum_{j \in A} p_{ij} + \sum_{j \notin A} p_{ij} x_j$$

Substitute for  $x_j$  to obtain:

$$\begin{aligned} x_i &= \sum_{j \in I} p_{ij} x_j = \sum_{j \in A} p_{ij} + \sum_{j \notin A} p_{ij} \left( \sum_{k \in A} p_{jk} + \sum_{k \notin A} p_{jk} x_k \right) \\ &= \mathbb{P}_i(X_1 \in A) + \mathbb{P}_i(X_1 \notin A, X_2 \in A) + \sum_{j \notin A} \sum_{k \notin A} p_{ij} p_{jk} x_k. \end{aligned}$$

By repeated substitution for  $x$  in the final term, we obtain after  $n$  steps:

$$x_i = \mathbb{P}_i(X_i \in A) + \dots + \mathbb{P}_i(X_1 \notin A, \dots, X_{n-1} \notin A, X_n \in A) + \sum_{j_1 \notin A} \dots \sum_{j_n \notin A} p_{ij_1} p_{j_1 j_2} \dots p_{j_{n-1} j_n} x_{j_n}.$$

Now if  $x$  is non-negative, so is the last term on the right, and the remaining terms sum to  $\mathbb{P}_i(H^A < n)$ . So  $x_i \geq \mathbb{P}_i(H^A < n)$  for all  $n$  and then:

$$x_i \geq \lim_{n \rightarrow \infty} \mathbb{P}_i(H^A < n) = \mathbb{P}_i(H^A < \infty) = h_i.$$

## 2.2 Hitting probabilities for time-continuous Markov Chains

Using

$$\begin{aligned} h_i^A &= 1 \text{ for } i \in A \\ h_i^A &= \sum_{j \in I} p_{ij} h_j^A \text{ for } i \notin A. \end{aligned}$$

with  $L = P - I$  yields

$$\begin{aligned} h_i^A &= 1 \text{ for } i \in A \\ h_i^A &= \sum_{j \in I, j \neq i} l_{ij} h_j^A + (l_{ii} + 1) h_i^A \text{ for } i \notin A. \end{aligned}$$

and thus

$$\begin{aligned}
h_i^A &= 1 \text{ for } i \in A \\
\sum_{j \in I} l_{ij} h_j^A &= 0 \text{ for } i \notin A.
\end{aligned}$$

### 2.3 Time-discrete Committor Probabilities

The committor probability,  $q_i^+$  pertaining to two sets  $A, B$  is the probability that starting in state  $i$ , we will go to  $B$  next rather than to  $A$ :

$$q_i^+ = \mathbb{P}_i(H^B < H^A).$$

In order to compute this, we define an  $A$ -absorbing process as

$$\hat{p}_{ij} = \begin{cases} p_{ij} & i \notin A, j \in S \\ 1 & i \in A, i = j \\ 0 & i \in A, i \neq j \end{cases}$$

and then compute the hitting probability to  $B$ . Since the process is absorbing in  $A$  only, the hitting probability to  $B$  will reflect the probability to go to  $B$  next rather than to  $A$ .

Using the hitting probability equations:

$$\begin{aligned}
q_i^+ &= 1 \text{ for } i \in B \\
q_i^+ &= \sum_{j \in I} p_{ij} q_j^+ \text{ for } i \notin B.
\end{aligned}$$

with the absorbing process yields:

$$\begin{aligned}
q_i^+ &= 0 \text{ for } i \in A \\
q_i^+ &= 1 \text{ for } i \in B \\
q_i^+ &= \sum_{j \in I} p_{ij} q_j^+ \text{ for } i \notin \{A, B\}.
\end{aligned}$$

The backward committor probability,  $q_i^-$  pertaining to two sets  $A, B$  is the probability that being in state  $i$ , we have been in  $A$  last rather than in  $B$ . In order to get the backward committor, we use the backwards propagator  $\tilde{p}_{ij} = \frac{\pi_j}{\pi_i} p_{ji}$ , consider a  $B$ -absorbing process for the reverse dynamics and compute the hitting probability for  $A$ :

$$\begin{aligned}
q_i^- &= 1 \text{ for } i \in A \\
q_i^- &= 0 \text{ for } i \in B \\
q_i^- &= \sum_{j \in I} \tilde{p}_{ij} q_j^- \text{ for } i \notin \{A, B\}.
\end{aligned}$$

for reversibility / detailed balance,  $p_{ij} = \frac{\pi_j}{\pi_i} p_{ji} = \tilde{p}_{ij}$  and thus:

$$\begin{aligned}
q_i^- &= 1 \text{ for } i \in A \\
q_i^- &= 0 \text{ for } i \in B \\
q_i^- &= \sum_{j \in I} p_{ij} q_j^- \text{ for } i \notin \{A, B\}.
\end{aligned}$$

it can be easily checked that:

$$q^- = 1 - q^+$$

satisfies this equation as it transforms it to the forward committor equation.

## 2.4 Time-continuous Committor Probabilities

$$\hat{l}_{ij} = \begin{cases} l_{ij} & i \notin A \\ 0 & i \in A \end{cases}$$

substituted into the Dirichlet problem:

$$\begin{aligned}
q_i^+ &= 1 \text{ for } i \in B \\
\sum_{j \in I} l_{ij} q_j^+ &= 0 \text{ for } i \notin B.
\end{aligned}$$

yields

$$\begin{aligned}
q_i^+ &= 0 \text{ for } i \in A \\
q_i^+ &= 1 \text{ for } i \in B \\
\sum_{j \in I} l_{ij} q_j^+ &= 0 \text{ for } i \notin \{A, B\}.
\end{aligned}$$

In order to get the backward committor, we define the backwards propagator  $\tilde{l}_{ij} = \frac{\pi_j}{\pi_i} l_{ji}$  and obtain:

$$\begin{aligned}
q_i^- &= 1 \text{ for } i \in A \\
q_i^- &= 0 \text{ for } i \in B \\
\sum_{j \in I} \tilde{l}_{ij} q_j^- &= 0 \text{ for } i \notin \{A, B\}.
\end{aligned}$$

for reversibility / detailed balance,  $l_{ij} = \frac{\pi_j}{\pi_i} l_{ji}$  and it can be easily checked that:

$$q^- = 1 - q^+$$

### 3 Reactive Flux:

#### 3.1 Probability weight of reactive trajectories:

$$m_i^R = \pi_i q_i^- q_i^+$$

with  $Z_{AB} = \sum_i m_i^R = \sum_i \pi_i q_i^- q_i^+ < 1$  it is clear that we need to normalize:

$$m_i^{AB} = Z_{AB}^{-1} \pi_i q_i^- q_i^+.$$

For detailed balance, we have:

$$m_i^{AB} = Z_{AB}^{-1} \pi_i (1 - q_i^+) q_i^+.$$

to obtain the probability distribution of reaction trajectories, i.e. the probability to be at state  $i$  and to be reactive.

#### 3.2 Probability current of reactive trajectories:

$$f_{ij}^{AB} = \begin{cases} \pi_i q_i^- l_{ij} q_i^+ & i \neq j \\ 0 & i = j \end{cases}.$$

(for detailed balance, we have  $q_i^- = 1 - q_i^+$ ). *The probability current is the number of jumps  $i \rightarrow j$  which lie on reactive  $A \rightarrow B$  trajectories.*

We have a number of nice properties:

##### 1) Flux conservation (Kirchhoff's 1st law)

$$\sum_{j \in S} (f_{ij}^{AB} - f_{ji}^{AB}) = 0 \quad \forall i \notin \{A, B\}$$

Proof:

$$\begin{aligned}
\sum_{j \in S} (f_{ij}^{AB} - f_{ji}^{AB}) &= \pi_i q_i^- \sum_{j \neq i} l_{ij} q_j^+ - q_i^+ \sum_{j \neq i} \pi_j q_j^- l_{ji} \\
&= \pi_i q_i^- \sum_{j \neq i} l_{ij} q_j^+ - \pi_i q_i^+ \sum_{j \neq i} q_j^- \tilde{l}_{ij}
\end{aligned}$$

Due to the committor equations, we have  $\sum_{j \notin \{A, B\}} l_{ij} q_j^+ = 0$  and  $\sum_{j \notin \{A, B\}} \tilde{l}_{ji} q_j^- = 0$  and thus:

$$\sum_{j \in S} (f_{ij}^{AB} - f_{ji}^{AB}) = -\pi_i q_i^- l_{ii} q_i^+ + \pi_i q_i^+ \tilde{l}_{ii} q_i^- = 0.$$

From  $q_i^+ = 1 \forall i \in A$  and  $q_i^- = 0 \forall i \in B$  we see that

$$\begin{aligned}
f_{ij}^{AB} &= 0 \forall j \in A \\
f_{ij}^{AB} &= 0 \forall i \in B
\end{aligned}$$

thus flux is not conserved at A and B, but throughout the network such that:

$$\sum_{i \in A, j \notin A} f_{ij}^{AB} = \sum_{j \notin B, i \in B} f_{ji}^{AB}.$$

**Remarks:**

- It is worth noting that by setting  $q_i^+$  as negative potential,  $f_{ij}^+$  as current and  $\pi_i l_{ij}$  as conductance provides an electric network theory with Ohm's law and Kirchhoff's laws being valid.

- All TPT is valid when substituting  $p_{ij}$  in  $l_{ij}$ .

### 3.3 Effective current

is defined as

$$f_{ij}^+ = \max\{f_{ij}^{AB} - f_{ji}^{AB}, 0\}$$

and gives the *net average number of reactive trajectories per time unit making a transition from  $i$  to  $j$  on their way from  $A$  to  $B$ .*

### 3.4 Total rate

The total number of reactive  $A \rightarrow B$  trajectories per time unit is simply given by the effective current flowing out of  $A$  and into  $B$ :



$$K = \sum_{i \in A, j \notin A} f_{ij}^{AB} = \sum_{i \in A, j \notin A} \pi_i l_{ij} q_i^+ = \sum_{j \notin B, i \in B} f_{ji}^{AB} = \sum_{i \in B, j \notin B} \pi_j q_j^- l_{ji}$$

If the system is ergodic, every trajectory must go back from  $B$  to  $A$  in order to be able to transit to  $B$  again. Thus,  $K$  is also equal to the number of reactive  $B \rightarrow A$  trajectories and equal to the number of  $A \rightarrow B \rightarrow A$  cycles.

## 4 Pathways

- A reaction pathway  $w = (i_0, i_1, \dots, i_n)$  from  $A$  to  $B$  is a simple pathway, such that

$$i_0 \in A, i_n \in B, i_1 \dots i_{n-1} \notin \{A, B\}.$$

- the capacity of a pathway  $w$  is the minimal effective current:

$$c(w) = \min_{(i,j) \in w} \{f_{ij}^+\}$$

- the bottleneck of a reaction pathway  $w$  is the edge with the minimal effective current:

$$(b_1, b_2) = \arg \min_{(i,j) \in w} \{f_{ij}^+\}$$

- The best pathway is one that maximizes the minimal current. This is only necessarily unique at the bottleneck. However, following algorithm is a rational way to find a unique best pathway in graph  $G$ :

BestPath( $G, A, B$ )

1. Determine bottleneck  $(b_1, b_2)$  in  $G$

2. Decompose  $G$  into  $L$  and  $R$ , which are the parts of  $G$  left of  $b_1$  and right of  $b_2$

$$3. w_L = \begin{cases} b_1 & \text{if } b_1 \in A \\ \text{BestPath}(L, A, \{b_1\}) & \text{else} \end{cases}$$

$$4. w_R = \begin{cases} b_2 & \text{if } b_2 \in B \\ \text{BestPath}(L, \{b_2\}, B) & \text{else} \end{cases}$$

5. return  $(w_L, w_R)$

In order to decompose the network into individual pathways, let  $w = \text{BestPath}(G, A, B)$  and subtract that pathway from the network:

$$(f_{ij}^+)' = f_{ij}^+ - c(w) \text{ if } (i, j) \in w$$

$$(f_{ij}^+)' = f_{ij}^+ \text{ else.}$$

It directly follows from the flux conservation laws that in the new pathways we still have flux conservation and

$$K' = K - c(w).$$

We will have  $K' = 0$  when all  $A \rightarrow B$  pathways have been subtracted and the decomposition is finished. This results in a set of  $A \rightarrow B$  pathways whose statistical contribution to the  $A \rightarrow B$  is given by the capacity of each,  $c(w)$ .

## Literature

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