



Numerics of Stochastic Processes

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Illia Horenko



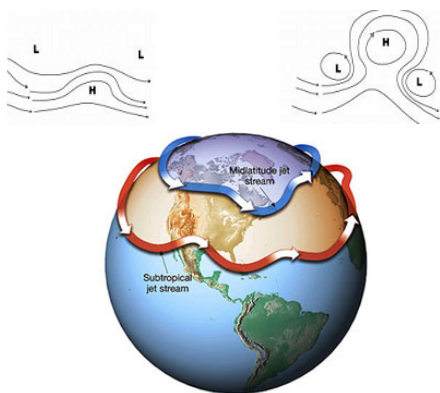
Research Group “**Computational Time Series Analysis**”
Institute of Mathematics
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DFG Research Center **MATHEON**
„Mathematics in key technologies“

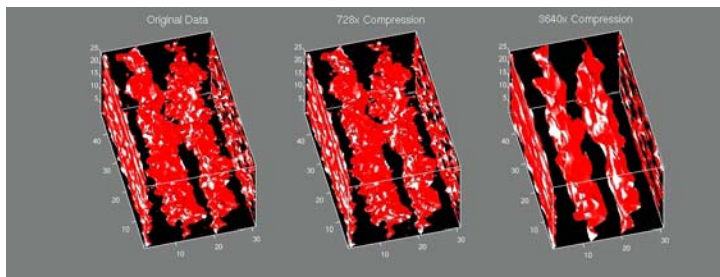




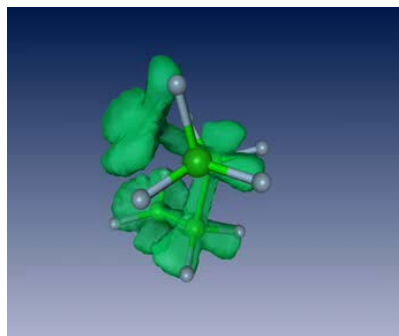
Complex Systems



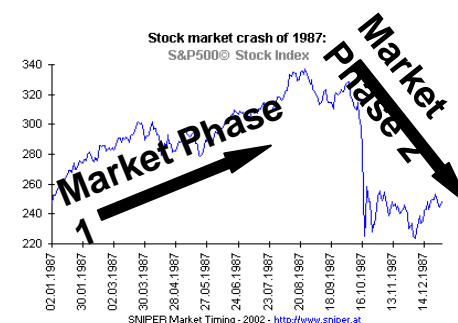
Weather Regimes
Meteorology



Flow Regimes
Fluid Mechanics



Molecular Conformations
Drug Design



Market Phases
Finance

Deterministic Description is Unavailable or Unfeasible!



Properties:

- 1) *non-stationarity*
- 2) a lot of *d.o.f.s* are involved (*multidimensionality*)
- 3) *stochasticity*

Today we look at:

- 1) *Stochastic Processes* and their deterministic interpretation
- 2) *Memory*
- 3) Concept of *Attractors*



Memo I: Probability



A probability space is a **measure space** such that the measure of the whole space is equal to 1.

In other words: a probability space is a triple (Ω, \mathcal{F}, P) consisting of a **set** Ω (called the **sample space**), a **σ -algebra** (also called σ -field) \mathcal{F} of subsets of Ω (these subsets are called **events**), and a **measure** P on (Ω, \mathcal{F}) such that $P(\Omega) = 1$ (called the probability measure).

Event	Probability
A	$P(A) \in [0, 1]$
not A	$P(A') = 1 - P(A)$
A or B	$P(A \cup B) = P(A) + P(B) - P(A \cap B)$ $= P(A) + P(B) \quad \text{if A and B are mutually exclusive}$
A and B	$P(A \cap B) = P(A B)P(B)$ $= P(A)P(B) \quad \text{if A and B are independent}$
A given B	$P(A B)$



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Memo II: Stochastic Process



Given a probability space (Ω, \mathcal{F}, P) , a **stochastic process** (or **random process**) with state space X is a collection of X -valued **random variables** indexed by a set T ("time"). That is, a stochastic process F is a collection

$$\{F_t : t \in T\}$$

where each F_t is an X -valued random variable.

Probability Density Function:

$$\Pr(4.3 \leq X \leq 7.8) = \int_{4.3}^{7.8} p(x) dx.$$

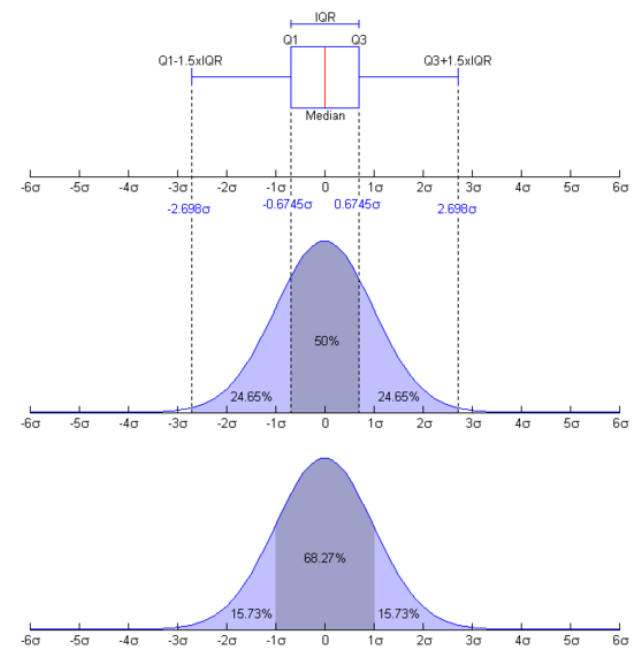
Expectation Value:

$$E(X) = \int_{\Omega} X dP \quad \mu = \int x p(x) dx$$

Variance:

$$\text{Var}(X) = \int (x - \mu)^2 p(x) dx$$

White Noise: $\epsilon_t \sim \mathcal{N}(0, 1)$

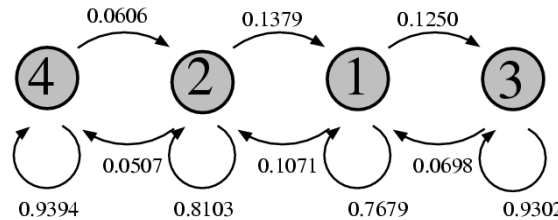




Classification of Stochastic Process



Discrete State Space,
Discrete Time:
Markov Chain



Discrete State Space,
Continuous Time:
Markov Process

Stochastic Processes

Continuous State Space,
Discrete Time:
Autoregressive Process

$$X_{t+\tau} = \sum_{k=0}^p \alpha_k X_{t-k\tau} + \sigma \epsilon_t$$

Continuous State Space,
Continuous Time:
Stochastic Differential Equation

$$dX_t = f(X_t, t) dt + \sigma dW_t$$

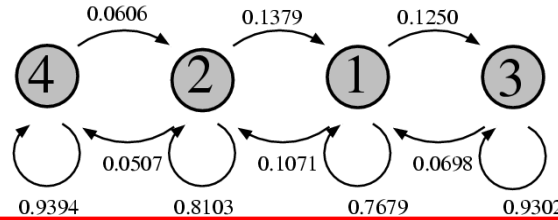


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TODAY

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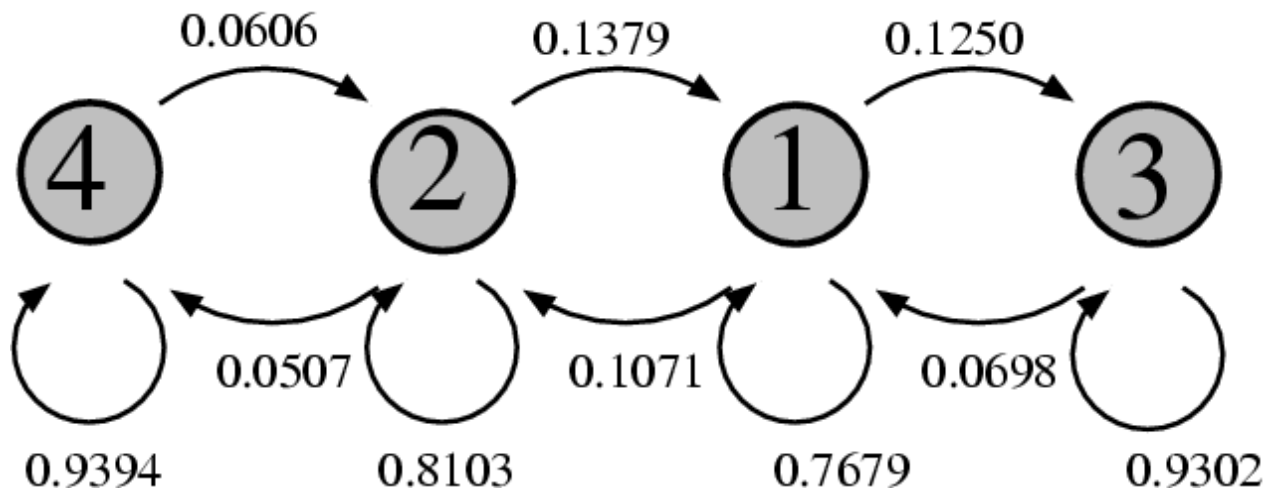


Realizations of the process: $X_t \in s_1, \dots, s_m$
 $\{X_0, X_\tau, X_{2\tau}, \dots, X_{t-\tau}\}$

Markov-Property:

$$\mathbb{P}[X_t = s_j | X_0, X_\tau, X_{2\tau}, \dots, X_{t-\tau} = s_j] = \mathbb{P}[X_t = s_j | X_{t-\tau} = s_j] = P_{ij}(t, \tau)$$

Example:





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State Probabilities:

$$\pi(t) = (\pi_1(t), \pi_2(t), \dots, \pi_m(t))$$



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Dynamics:

$$\pi(t + \tau) = \pi(t)P(t)$$

This Equation is Deterministic!



Markov Processes



Infinitesimal Generator:

$$\mathcal{G}(t) = \lim_{\tau \rightarrow 0} \frac{P(t, \tau) - \mathcal{I}}{\tau}$$

Markov Process Dynamics:

$$\dot{\pi} = \pi \mathcal{G}(t)$$

This Equation is Deterministic: ODE!



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Concepts from the *Theory of Dynamical Systems* are Applicable



Thank you for attention!