

CUT-SIMULATION AND IMPREDICATIVITY *

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ABSTRACT. We investigate cut-elimination and cut-simulation in impredicative (higher-order) logics. We illustrate that adding simple axioms such as Leibniz equations to a calculus for an impredicative logic — in our case a sequent calculus for classical type theory — is like adding cut. The phenomenon equally applies to prominent axioms like Boolean- and functional extensionality, induction, choice, and description. This calls for the development of calculi where these principles are built-in instead of being treated axiomatically.

1. INTRODUCTION

One of the key questions of automated reasoning is the following: “When does a set Φ of sentences have a model?” In fact, given reasonable assumptions about calculi, most inference problems can be reduced to determining (un)-satisfiability of a set Φ of sentences. Since building models for Φ is hard in practice, much research in computational logic has concentrated on finding sufficient conditions for satisfiability, e.g. whether there is a Hintikka set \mathcal{H} extending Φ .

Of course in general the answer to the satisfiability question depends on the class of models at hand. In classical first-order logic, model classes are well-understood. In impredicative higher-order logic, there is a whole landscape of plausible model classes differing in their treatment of functional and Boolean extensionality. Satisfiability then strongly depends on these classes, for instance, the set $\Phi := \{a, b, qa, \neg qb\}$ is unsatisfiable in a model

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class where the universes of Booleans are required to have at most two members (see property **b** below), but satisfiable in the class without this restriction.

In [5] we have shown that certain (i.e. *saturated*) Hintikka sets always have models and have derived syntactical conditions (so-called *saturated* abstract consistency properties) for satisfiability from this fact. The importance of abstract consistency properties is that one can check completeness for a calculus \mathcal{C} by verifying proof-theoretic conditions (checking that \mathcal{C} -irrefutable sets of formulae have the saturated abstract consistency property) instead of performing model-theoretic analysis (for historical background of the abstract consistency method in first-order logic, cf. [11, 16, 17]). Unfortunately, the saturation condition (if Φ is abstractly consistent, then for all sentences \mathbf{A} one of $\Phi \cup \{\mathbf{A}\}$ or $\Phi \cup \{\neg\mathbf{A}\}$ is as well) is very difficult to prove for machine-oriented calculi (indeed as hard as cut elimination as we will show).

In this paper we investigate further the relation between the lack of the subformula property in the saturation condition (we need to “guess” whether to extend Φ by \mathbf{A} or $\neg\mathbf{A}$ on our way to a Hintikka set) and the cut rule (where we have to “guess,” i.e. “search for” in an automated reasoning setting the cut formula \mathbf{A}). An important result is the insight that there exist “cut-strong” formulae which support the effective simulation of cut in calculi for impredicative logics. Prominent examples of cut-strong formulae are Leibniz equations and the axioms for comprehension, extensionality, induction, description and choice. The naive addition of any of these cut-strong formulae to any calculus for an impredicative logic is a strong threat for effective automated proof search, since these formulae in a way introduce the cut rule through the backdoor (even if the original calculus is cut-free and thus appears appropriate for proof automation at first sight). Cut-strong formulae thus introduce additional sources for breaking the subformula property and therefore they should either be avoided completely or treated with great care in calculi designed for automated proof search.

Consider the following formula of higher-order logic representing Boolean extensionality:

$$\forall A_o \forall B_o (A \Leftrightarrow B) \Rightarrow A \doteq^o B$$

For a theorem prover to make use of this formula, it must instantiate A and B with terms of type o . In other words, the theorem prover must synthesize two arbitrary formulas. Requiring a theorem prover to synthesize these formulas is just as hard (and unrealistic) as requiring a theorem prover to synthesize cut formulas. An alternative to including the formula for Boolean extensionality is to include a rule in the search procedure which allows the theorem prover to reduce proving $\mathbf{A} \doteq^o \mathbf{B}$ to the subgoal of proving $\mathbf{A} \Leftrightarrow \mathbf{B}$. Using this rule does not require the prover to synthesize any terms. Simply adding such a rule is not enough to obtain a complete calculus. We will explore what additional rules are required to obtain completeness and argue that these rules are appropriate for mechanized proof search.

In Section 2, we will fix notation and review the relevant results from [5]. We define in Section 3 a basic sequent calculus and study the correspondence between saturation in abstract consistency classes and cut-elimination. In Section 4 we introduce the notion of “cut-strong” formulae and sequents and show that they support the effective simulation of cut. In Section 5 we demonstrate that the pertinent extensionality axioms are cut-strong. We develop alternative extensionality rules which do not suffer from this problem. Further rules are needed to ensure Henkin completeness for this calculus with extensionality. These

new rules correspond to the acceptability conditions we propose in Section 6 to ensure the existence of models and the existence of saturated extensions of abstract consistency classes.

2. HIGHER-ORDER LOGIC

In [5] we have re-examined the semantics of classical higher-order logic with the purpose of clarifying the role of extensionality. For this we have defined eight classes of higher-order models with respect to various combinations of Boolean extensionality and three forms of functional extensionality. We have also developed a methodology of abstract consistency (by providing the necessary model existence theorems) needed for instance, to analyze completeness of higher-order calculi with respect to these model classes. We now briefly summarize the main notions and results of [5] as required for this paper. Our impredicative logic of choice is Church's classical type theory.

2.1. Syntax: Church's Simply Typed λ -Calculus. As in [9], we formulate higher-order logic (\mathcal{HOL}) based on the simply typed λ -calculus. The set of simple types \mathcal{T} is freely generated from basic types o and ι using the function type constructor \rightarrow .

For formulae we start with a set \mathcal{V} of (typed) variables (denoted by $X_\alpha, Y, Z, X_\beta^1, X_\gamma^2, \dots$) and a signature Σ of (typed) constants (denoted by $c_\alpha, f_{\alpha \rightarrow \beta}, \dots$). We let \mathcal{V}_α (Σ_α) denote the set of variables (constants) of type α . The signature Σ of constants includes the logical constants $\neg_{o \rightarrow o}$, $\vee_{o \rightarrow o \rightarrow o}$ and $\Pi_{(\alpha \rightarrow o) \rightarrow o}^\alpha$ for each type α ; all other constants in Σ are called parameters. As in [5], we assume there is an infinite cardinal \aleph_s such that the cardinality of Σ_α is \aleph_s for each type α (cf. [5](3.16)). The set of \mathcal{HOL} -formulae (or terms) are constructed from typed variables and constants using application and λ -abstraction. We let $wff_\alpha(\Sigma)$ be the set of all terms of type α and $wff(\Sigma)$ be the set of all terms.

We use vector notation to abbreviate k -fold applications and abstractions as $\mathbf{A}\overline{\mathbf{U}}^k$ and $\lambda\overline{\mathbf{X}}^k.\mathbf{A}$, respectively. We also use Church's dot notation so that $.$ stands for a (missing) left bracket whose mate is as far to the right as possible (consistent with given brackets). We use infix notation $\mathbf{A} \vee \mathbf{B}$ for $((\vee \mathbf{A})\mathbf{B})$ and binder notation $\forall X_\alpha.\mathbf{A}$ for $(\Pi^\alpha(\lambda X_\alpha.\mathbf{A}_o))$. We further use $\mathbf{A} \wedge \mathbf{B}$, $\mathbf{A} \Rightarrow \mathbf{B}$, $\mathbf{A} \Leftrightarrow \mathbf{B}$ and $\exists X_\alpha.\mathbf{A}$ as shorthand for formulae defined in terms of \neg , \vee and Π^α (cf. [5]). Finally, we let $(\mathbf{A}_\alpha \doteq^\alpha \mathbf{B}_\alpha)$ denote the Leibniz equation $\forall P_{\alpha \rightarrow o}.(PA) \Rightarrow .PB$.

Each occurrence of a variable in a term is either bound by a λ or free. We use $free(\mathbf{A})$ to denote the set of free variables of \mathbf{A} (i.e., variables with a free occurrence in \mathbf{A}). We consider two terms to be equal if the terms are the same up to the names of bound variables (i.e., we consider α -conversion implicitly). A term \mathbf{A} is closed if $free(\mathbf{A})$ is empty. We let $cwff_\alpha(\Sigma)$ denote the set of closed terms of type α and $cwff(\Sigma)$ denote the set of all closed terms. Each term $\mathbf{A} \in wff_o(\Sigma)$ is called a proposition and each term $\mathbf{A} \in cwff_o(\Sigma)$ is called a sentence.

We denote substitution of a term \mathbf{A}_α for a variable X_α in a term \mathbf{B}_β by $[\mathbf{A}/X]\mathbf{B}$. Since we consider α -conversion implicitly, we assume the bound variables of \mathbf{B} avoid variable capture.

Two common relations on terms are given by β -reduction and η -reduction. A β -redex $(\lambda X.\mathbf{A})\mathbf{B}$ β -reduces to $[\mathbf{B}/X]\mathbf{A}$. An η -redex $(\lambda X.\mathbf{C}X)$ (where $X \notin free(\mathbf{C})$) η -reduces to \mathbf{C} . For $\mathbf{A}, \mathbf{B} \in wff_\alpha(\Sigma)$, we write $\mathbf{A} \equiv_\beta \mathbf{B}$ to mean \mathbf{A} can be converted to \mathbf{B} by a series of β -reductions and expansions. Similarly, $\mathbf{A} \equiv_{\beta\eta} \mathbf{B}$ means \mathbf{A} can be converted to \mathbf{B} using both

β and η . For each $\mathbf{A} \in \text{wff}(\Sigma)$ there is a unique β -normal form (denoted $\mathbf{A} \downarrow_{\beta}$) and a unique $\beta\eta$ -normal form (denoted $\mathbf{A} \downarrow_{\beta\eta}$). From this fact we know $\mathbf{A} \equiv_{\beta} \mathbf{B}$ ($\mathbf{A} \equiv_{\beta\eta} \mathbf{B}$) iff $\mathbf{A} \downarrow_{\beta} \equiv \mathbf{B} \downarrow_{\beta}$ ($\mathbf{A} \downarrow_{\beta\eta} \equiv \mathbf{B} \downarrow_{\beta\eta}$).

A non-atomic formula in $\text{wff}_o(\Sigma)$ is any formula whose β -normal form is of the form $[c\overline{\mathbf{A}^n}]$ where c is a logical constant. An atomic formula is any other formula in $\text{wff}_o(\Sigma)$.

2.2. Semantics: Eight Model Classes. A model of \mathcal{HOL} is given by four objects: a typed collection of nonempty sets $(\mathcal{D}_{\alpha})_{\alpha \in \mathcal{T}}$, an application operator $@: \mathcal{D}_{\alpha \rightarrow \beta} \times \mathcal{D}_{\alpha} \rightarrow \mathcal{D}_{\beta}$, an evaluation function \mathcal{E} for terms and a valuation function $v: \mathcal{D}_o \rightarrow \{\mathbf{T}, \mathbf{F}\}$. A pair $(\mathcal{D}, @)$ is called a Σ -applicative structure (cf. [5](3.1)). If \mathcal{E} is an evaluation function for $(\mathcal{D}, @)$ (cf. [5](3.18)), then we call the triple $(\mathcal{D}, @, \mathcal{E})$ a Σ -evaluation. If v satisfies appropriate properties, then we call the tuple $(\mathcal{D}, @, \mathcal{E}, v)$ a Σ -model (cf. [5](3.40 and 3.41)).

Given an applicative structure $(\mathcal{D}, @)$, an assignment φ is a (typed) function from \mathcal{V} to \mathcal{D} . An evaluation function \mathcal{E} maps an assignment φ and a term $\mathbf{A}_{\alpha} \in \text{wff}_{\alpha}(\Sigma)$ to an element $\mathcal{E}_{\varphi}(\mathbf{A}) \in \mathcal{D}_{\alpha}$. Evaluations \mathcal{E} are required to satisfy four properties (cf. [5](3.18)):

- (1) $\mathcal{E}_{\varphi}|_{\mathcal{V}} \equiv \varphi$.
- (2) $\mathcal{E}_{\varphi}(\mathbf{FA}) \equiv \mathcal{E}_{\varphi}(\mathbf{F})@ \mathcal{E}_{\varphi}(\mathbf{A})$ for any $\mathbf{F} \in \text{wff}_{\alpha \rightarrow \beta}(\Sigma)$, $\mathbf{A} \in \text{wff}_{\alpha}(\Sigma)$ and types α and β .
- (3) $\mathcal{E}_{\varphi}(\mathbf{A}) \equiv \mathcal{E}_{\psi}(\mathbf{A})$ for any type α and $\mathbf{A} \in \text{wff}_{\alpha}(\Sigma)$, whenever φ and ψ coincide on $\text{free}(\mathbf{A})$.
- (4) $\mathcal{E}_{\varphi}(\mathbf{A}) \equiv \mathcal{E}_{\varphi}(\mathbf{A} \downarrow_{\beta})$ for all $\mathbf{A} \in \text{wff}_{\alpha}(\Sigma)$.

If \mathbf{A} is closed, then we can simply write $\mathcal{E}(\mathbf{A})$ since the value $\mathcal{E}_{\varphi}(\mathbf{A})$ cannot depend on φ .

Given an evaluation $(\mathcal{D}, @, \mathcal{E})$, we define several properties a function $v: \mathcal{D}_o \rightarrow \{\mathbf{T}, \mathbf{F}\}$ may satisfy (cf. [5](3.40)).

| prop. | where | holds when | for all |
|---|--|--|--|
| $\mathfrak{L}_{\neg}(\mathfrak{n})$ | $\mathfrak{n} \in \mathcal{D}_{o \rightarrow o}$ | $v(\mathfrak{n}@a) \equiv \mathbf{T}$ iff $v(a) \equiv \mathbf{F}$ | $a \in \mathcal{D}_o$ |
| $\mathfrak{L}_{\vee}(\mathfrak{d})$ | $\mathfrak{d} \in \mathcal{D}_{o \rightarrow o \rightarrow o}$ | $v(\mathfrak{d}@a@b) \equiv \mathbf{T}$ iff $v(a) \equiv \mathbf{T}$ or $v(b) \equiv \mathbf{T}$ | $a, b \in \mathcal{D}_o$ |
| $\mathfrak{L}_{\forall}^{\alpha}(\pi)$ | $\pi \in \mathcal{D}_{(\alpha \rightarrow o) \rightarrow o}$ | $v(\pi@f) \equiv \mathbf{T}$ iff $\forall a \in \mathcal{D}_{\alpha} v(f@a) \equiv \mathbf{T}$ | $f \in \mathcal{D}_{\alpha \rightarrow o}$ |
| $\mathfrak{L}_{=}^{\alpha}(\mathfrak{q})$ | $\mathfrak{q} \in \mathcal{D}_{\alpha \rightarrow \alpha \rightarrow o}$ | $v(\mathfrak{q}@a@b) \equiv \mathbf{T}$ iff $a \equiv b$ | $a, b \in \mathcal{D}_{\alpha}$ |

A valuation $v: \mathcal{D}_o \rightarrow \{\mathbf{T}, \mathbf{F}\}$ is required to satisfy $\mathfrak{L}_{\neg}(\mathcal{E}(-))$, $\mathfrak{L}_{\vee}(\mathcal{E}(\vee))$ and $\mathfrak{L}_{\forall}^{\alpha}(\mathcal{E}(\Pi^{\alpha}))$ for every type α .

Given a model $\mathcal{M} := (\mathcal{D}, @, \mathcal{E}, v)$, an assignment φ and a proposition \mathbf{A} (or set of propositions Φ), we say \mathcal{M} satisfies \mathbf{A} (or Φ) and write $\mathcal{M} \models_{\varphi} \mathbf{A}$ (or $\mathcal{M} \models_{\varphi} \Phi$) if $v(\mathcal{E}_{\varphi}(\mathbf{A})) \equiv \mathbf{T}$ (or $v(\mathcal{E}_{\varphi}(\mathbf{A})) \equiv \mathbf{T}$ for each $\mathbf{A} \in \Phi$). If \mathbf{A} is closed (or every member of Φ is closed), then we simply write $\mathcal{M} \models \mathbf{A}$ (or $\mathcal{M} \models \Phi$) and say \mathcal{M} is a model of \mathbf{A} (or Φ).

In order to define model classes \mathfrak{M}_{*} which correspond to different notions of extensionality, we define five properties of models (cf. [5](3.46, 3.21 and 3.5)). Let $\mathcal{M} := (\mathcal{D}, @, \mathcal{E}, v)$ be a model. We define:

- \mathfrak{q} : iff for all $\alpha \in \mathcal{T}$ there is a $\mathfrak{q}^{\alpha} \in \mathcal{D}_{\alpha \rightarrow \alpha \rightarrow o}$ with $\mathfrak{L}_{=}^{\alpha}(\mathfrak{q}^{\alpha})$.
- η : iff $(\mathcal{D}, @, \mathcal{E})$ is η -functional (i.e., for each $\mathbf{A} \in \text{wff}_{\alpha}(\Sigma)$ and assignment φ , $\mathcal{E}_{\varphi}(\mathbf{A}) \equiv \mathcal{E}_{\varphi}(\mathbf{A} \downarrow_{\beta\eta})$).
- ξ : iff $(\mathcal{D}, @, \mathcal{E})$ is ξ -functional (i.e., for each $\mathbf{M}, \mathbf{N} \in \text{wff}_{\beta}(\Sigma)$, $X \in \mathcal{V}_{\alpha}$ and assignment φ , $\mathcal{E}_{\varphi}(\lambda X_{\alpha}.\mathbf{M}_{\beta}) \equiv \mathcal{E}_{\varphi}(\lambda X_{\alpha}.\mathbf{N}_{\beta})$ whenever $\mathcal{E}_{\varphi, [a/X]}(\mathbf{M}) \equiv \mathcal{E}_{\varphi, [a/X]}(\mathbf{N})$ for every $a \in \mathcal{D}_{\alpha}$).
- \mathfrak{f} : iff $(\mathcal{D}, @)$ is functional (i.e., for each $f, g \in \mathcal{D}_{\alpha \rightarrow \beta}$, $f \equiv g$ whenever $f@a \equiv g@a$ for every $a \in \mathcal{D}_{\alpha}$).
- \mathfrak{b} : iff \mathcal{D}_o has at most two elements.

For each $* \in \{\beta, \beta\eta, \beta\xi, \beta\mathfrak{f}, \beta\mathfrak{b}, \beta\eta\mathfrak{b}, \beta\xi\mathfrak{b}, \beta\mathfrak{f}\mathfrak{b}\}$ (the latter set will be abbreviated by \square_8 in the remainder) we define \mathfrak{M}_* to be the class of all Σ -models \mathcal{M} such that \mathcal{M} satisfies property \mathfrak{q} and each of the additional properties $\{\eta, \xi, \mathfrak{f}, \mathfrak{b}\}$ indicated in the subscript $*$ (cf. [5](3.49)). We always include β in the subscript to indicate that β -equal terms are always interpreted as identical elements. We do not include property \mathfrak{q} as an explicit subscript; \mathfrak{q} is treated as a basic, implicit requirement for all model classes. See [5](3.52) for a discussion on why we require property \mathfrak{q} . Since we are varying four properties, one would expect to obtain 16 model classes. However, we showed in [5] that \mathfrak{f} is equivalent to the conjunction of ξ and η . Hence we obtain the eight model classes depicted as a cube in Figure 1. There are example models constructed in [5] to demonstrate that each of the eight model classes is distinct. For instance, Example 5.6 of [5] describes how to construct a model without η by attaching labels to functions.

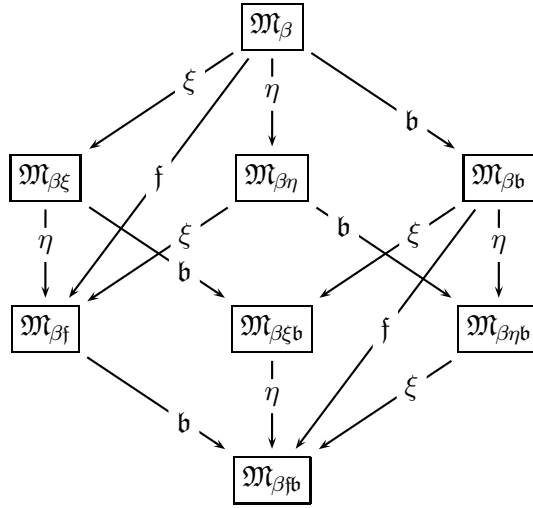


Figure 1: The Landscape of \mathcal{HOL} -Semantics.

Special cases of Σ -models are Henkin models and standard models (cf. [5](3.50 and 3.51)). A Henkin model is a model in $\mathfrak{M}_{\beta\mathfrak{f}\mathfrak{b}}$ such that the applicative structure $(\mathcal{D}, @)$ is a frame, i.e. $\mathcal{D}_{\alpha \rightarrow \beta}$ is a subset of the function space $(\mathcal{D}_\beta)^{\mathcal{D}_\alpha}$ for each $\alpha, \beta \in \mathcal{T}$ and $@$ is function application. A standard model is a Henkin model in which $\mathcal{D}_{\alpha \rightarrow \beta}$ is the full function space $(\mathcal{D}_\beta)^{\mathcal{D}_\alpha}$. Every model in $\mathfrak{M}_{\beta\mathfrak{f}\mathfrak{b}}$ is isomorphic to a Henkin model (see the discussion following [5](3.68)).

2.3. Saturated Abstract Consistency Classes and Model Existence. Finally, we review the model existence theorems proved in [5]. There are three stages to obtaining a model in our framework. First, we obtain an abstract consistency class Γ_Σ (usually defined as the class of irrefutable sets of sentences with respect to some calculus). Second, given a (sufficiently pure) set of sentences Φ in the abstract consistency class Γ_Σ we construct a Hintikka set \mathcal{H} extending Φ . Third, we construct a model of this Hintikka set (and hence a model of Φ).

A Σ -abstract consistency class Γ_Σ is a class of sets of Σ -sentences. An abstract consistency class is always required to be closed under subsets (cf. [5](6.1)). Sometimes we require

the stronger property that Γ_Σ is compact, i.e. a set Φ is in Γ_Σ iff every finite subset of Φ is in Γ_Σ (cf. [5](6.1,6.2)).

To describe further properties of abstract consistency classes, we use the notation $S * a$ for $S \cup \{a\}$ as in [5]. The following is a list of properties a class Γ_Σ of sets of sentences can satisfy with respect to arbitrary $\Phi \in \Gamma_\Sigma$ (cf. [5](6.5)):

- ∇_c : If \mathbf{A} is atomic, then $\mathbf{A} \notin \Phi$ or $\neg\mathbf{A} \notin \Phi$.
- ∇_{\neg} : If $\neg\neg\mathbf{A} \in \Phi$, then $\Phi * \mathbf{A} \in \Gamma_\Sigma$.
- ∇_β : If $\mathbf{A} \equiv_\beta \mathbf{B}$ and $\mathbf{A} \in \Phi$, then $\Phi * \mathbf{B} \in \Gamma_\Sigma$.
- ∇_η : If $\mathbf{A} \equiv_{\beta\eta} \mathbf{B}$ and $\mathbf{A} \in \Phi$, then $\Phi * \mathbf{B} \in \Gamma_\Sigma$.
- ∇_\vee : If $\mathbf{A} \vee \mathbf{B} \in \Phi$, then $\Phi * \mathbf{A} \in \Gamma_\Sigma$ or $\Phi * \mathbf{B} \in \Gamma_\Sigma$.
- ∇_\wedge : If $\neg(\mathbf{A} \vee \mathbf{B}) \in \Phi$, then $\Phi * \neg\mathbf{A} * \neg\mathbf{B} \in \Gamma_\Sigma$.
- ∇_{\forall} : If $\Pi^\alpha \mathbf{F} \in \Phi$, then $\Phi * \mathbf{F}\mathbf{W} \in \Gamma_\Sigma$ for each $\mathbf{W} \in \text{cwff}_\alpha(\Sigma)$.
- ∇_{\exists} : If $\neg\Pi^\alpha \mathbf{F} \in \Phi$, then $\Phi * \neg(\mathbf{F}w) \in \Gamma_\Sigma$ for any parameter $w_\alpha \in \Sigma_\alpha$ which does not occur in any sentence of Φ .
- ∇_b : If $\neg(\mathbf{A} \doteq^o \mathbf{B}) \in \Phi$, then $\Phi * \mathbf{A} * \neg\mathbf{B} \in \Gamma_\Sigma$ or $\Phi * \neg\mathbf{A} * \mathbf{B} \in \Gamma_\Sigma$.
- ∇_ξ : If $\neg(\lambda X_\alpha. \mathbf{M} \doteq^{\alpha \rightarrow \beta} \lambda X_\alpha. \mathbf{N}) \in \Phi$, then $\Phi * \neg([w/X]\mathbf{M} \doteq^\beta [w/X]\mathbf{N}) \in \Gamma_\Sigma$ for any parameter $w_\alpha \in \Sigma_\alpha$ which does not occur in any sentence of Φ .
- ∇_f : If $\neg(\mathbf{G} \doteq^{\alpha \rightarrow \beta} \mathbf{H}) \in \Phi$, then $\Phi * \neg(\mathbf{G}w \doteq^\beta \mathbf{H}w) \in \Gamma_\Sigma$ for any parameter $w_\alpha \in \Sigma_\alpha$ which does not occur in any sentence of Φ .
- ∇_{sat} : Either $\Phi * \mathbf{A} \in \Gamma_\Sigma$ or $\Phi * \neg\mathbf{A} \in \Gamma_\Sigma$.

We say Γ_Σ is an abstract consistency class if it is closed under subsets and satisfies ∇_c , ∇_{\neg} , ∇_β , ∇_\vee , ∇_\wedge , ∇_{\forall} and ∇_{\exists} . We let \mathfrak{Acc}_β denote the collection of all abstract consistency classes. For each $* \in \square_8$ we refine \mathfrak{Acc}_β to a collection \mathfrak{Acc}_* where the additional properties $\{\nabla_\eta, \nabla_\xi, \nabla_f, \nabla_b\}$ indicated by $*$ are required (cf. [5](6.7)). We say an abstract consistency class Γ_Σ is saturated if ∇_{sat} holds.

Using ∇_c (atomic consistency) and the fact that there are infinitely many parameters at each type, we can show every abstract consistency class satisfies non-atomic consistency. That is, for every abstract consistency class Γ_Σ , $\mathbf{A} \in \text{cwff}_o(\Sigma)$ and $\Phi \in \Gamma_\Sigma$, we have either $\mathbf{A} \notin \Phi$ or $\neg\mathbf{A} \notin \Phi$ (cf. [5](6.10)).

In [5](6.32) we show that sufficiently Σ -pure sets in saturated abstract consistency classes extend to saturated Hintikka sets. (A set of sentences Φ is sufficiently Σ -pure if for each type α there is a set \mathcal{P}_α of parameters of type α with cardinality \aleph_s and such that no parameter in \mathcal{P} occurs in a sentence in Φ . A Hintikka set is a maximal element in an abstract consistency class.)

In the Model Existence Theorem for Saturated Sets [5](6.33) we show that these saturated Hintikka sets can be used to construct models \mathcal{M} which are members of the corresponding model classes \mathfrak{M}_* . Then we conclude (cf. [5](6.34)):

Model Existence Theorem for Saturated Abstract Consistency Classes: *For all $* \in \square_8$, if Γ_Σ is a saturated abstract consistency class in \mathfrak{Acc}_* and $\Phi \in \Gamma_\Sigma$ is a sufficiently Σ -pure set of sentences, then there exists a model $\mathcal{M} \in \mathfrak{M}_*$ that satisfies Φ . Furthermore, each domain of \mathcal{M} has cardinality at most \aleph_s .*

In [5] we apply the abstract consistency method to analyze completeness for different natural deduction calculi. Unfortunately, the saturation condition is very difficult to prove for machine-oriented calculi (indeed as we will see in Section 3 it is equivalent to cut elimination), so Theorem [5](6.34) cannot be easily used for this purpose directly.

In Section 6 we therefore motivate and present a set of extra conditions for $\mathfrak{Acc}_{\beta\mathfrak{fb}}$ we call *acceptability* conditions. The new conditions are sufficient to prove model existence.

3. SEQUENT CALCULI, CUT AND SATURATION

We will now study cut-elimination and cut-simulation with respect to (one-sided) sequent calculi.

3.1. Sequent Calculi \mathcal{G} . We consider a sequent to be a finite set Δ of β -normal sentences from $cwff_o(\Sigma)$. A sequent calculus \mathcal{G} provides an inductive definition for when $\Vdash_{\mathcal{G}} \Delta$ holds. We say a sequent calculus rule

$$\frac{\Delta_1 \quad \cdots \quad \Delta_n}{\Delta} r$$

is *admissible* in \mathcal{G} if $\Vdash_{\mathcal{G}} \Delta$ holds whenever $\Vdash_{\mathcal{G}} \Delta_i$ for all $1 \leq i \leq n$. For any natural number $k \geq 0$, we call an admissible rule r *k-admissible* if any instance of r can be replaced by a derivation with at most k additional proof steps. Given a sequent Δ , a model \mathcal{M} , and a class \mathfrak{M} of models, we say Δ is *valid for \mathcal{M}* (or *valid for \mathfrak{M}*), if $\mathcal{M} \models \mathbf{D}$ for some $\mathbf{D} \in \Delta$ (or Δ is valid for every $\mathcal{M} \in \mathfrak{M}$). As for sets in abstract consistency classes, we use the notation $\Delta * \mathbf{A}$ to denote the set $\Delta \cup \{\mathbf{A}\}$ (which is simply Δ if $\mathbf{A} \in \Delta$). Figure 2 introduces several sequent calculus rules. Some of these rules will be used to define sequent calculi, while others will be shown admissible (or even k -admissible).

| | | |
|--------------------------------|---|---|
| <u>Basic Rules</u> | $\frac{\mathbf{A} \text{ atomic (and } \beta\text{-normal)}}{\Delta * \mathbf{A} * \neg \mathbf{A}} \mathcal{G}(init)$ | $\frac{\Delta * \mathbf{A}}{\Delta * \neg \neg \mathbf{A}} \mathcal{G}(\neg)$ |
| | $\frac{\Delta * \neg \mathbf{A} \quad \Delta * \neg \mathbf{B}}{\Delta * \neg(\mathbf{A} \vee \mathbf{B})} \mathcal{G}(\vee_-)$ | $\frac{\Delta * \mathbf{A} * \mathbf{B}}{\Delta * (\mathbf{A} \vee \mathbf{B})} \mathcal{G}(\vee_+)$ |
| | $\frac{\Delta * \neg(\mathbf{A}\mathbf{C}) \downarrow_{\beta} \quad \mathbf{C} \in cwff_{\alpha}(\Sigma)}{\Delta * \neg \Pi^{\alpha} \mathbf{A}} \mathcal{G}(\Pi^{\mathbf{C}}_-)$ | $\frac{\Delta * (\mathbf{A}\mathbf{c}) \downarrow_{\beta} \quad c_{\alpha} \in \Sigma \text{ new}}{\Delta * \Pi^{\alpha} \mathbf{A}} \mathcal{G}(\Pi^{\mathbf{c}}_+)$ |
| <u>Inversion Rule</u> | | $\frac{\Delta * \neg \neg \mathbf{A}}{\Delta * \mathbf{A}} \mathcal{G}(Inv^-)$ |
| <u>Weakening and Cut Rules</u> | $\frac{\Delta}{\Delta \cup \Delta'} \mathcal{G}(weak)$ | $\frac{\Delta * \mathbf{C} \quad \Delta * \neg \mathbf{C}}{\Delta} \mathcal{G}(cut)$ |

Figure 2: Sequent Calculus Rules

Remark 3.1 (Alternative Formulations). There are many kinds of sequent calculi given in the literature. We could have chosen to work with two sided sequents. This choice would have allowed us to generalize many of our results to the intuitionistic case. The notion of cut-strong formulae could still be defined and many of our examples of cut-strong formulae would also be cut-strong in the intuitionistic case. On the other hand, assuming we only treat the classical case, we could restrict to negation normal forms in the same way that we

restrict to β -normal forms. This would eliminate the need to consider the rules $\mathcal{G}(\neg)$ and $\mathcal{G}(Inv^\neg)$. Both of these alternatives are reasonable. The choices we have made are for ease of presentation and to make the connection with [5] as simple as possible.

3.2. Abstract Consistency Classes for Sequent Calculi. For any sequent calculus \mathcal{G} we can define a class $\Gamma_\Sigma^\mathcal{G}$ of sets of sentences. Under certain assumptions, $\Gamma_\Sigma^\mathcal{G}$ is an abstract consistency class. First we adopt the notation $\neg\Phi$ and $\Phi\downarrow_\beta$ for the sets $\{\neg\mathbf{A} \mid \mathbf{A} \in \Phi\}$ and $\{\mathbf{A}\downarrow_\beta \mid \mathbf{A} \in \Phi\}$, resp., where $\Phi \subseteq \text{cwff}_o(\Sigma)$. Furthermore, we assume this use of \neg binds more strongly than \cup or $*$, so that $\neg\Phi \cup \Delta$ means $(\neg\Phi) \cup \Delta$ and $\neg\Phi * \mathbf{A}$ means $(\neg\Phi) * \mathbf{A}$.

Definition 3.2. Let \mathcal{G} be a sequent calculus. We define $\Gamma_\Sigma^\mathcal{G}$ to be the class of all finite $\Phi \subseteq \text{cwff}_o(\Sigma)$ such that $\Vdash_{\mathcal{G}} \neg\Phi\downarrow_\beta$ does not hold.

In a straightforward manner, one can prove the following results (see the Appendix).

Lemma 3.3. *Let \mathcal{G} be a sequent calculus such that $\mathcal{G}(Inv^\neg)$ is admissible. For any finite sets Φ and Δ of sentences, if $\Phi \cup \neg\Delta \notin \Gamma_\Sigma^\mathcal{G}$, then $\Vdash_{\mathcal{G}} \neg\Phi\downarrow_\beta \cup \Delta\downarrow_\beta$ holds.*

Theorem 3.4. *Let \mathcal{G} be a sequent calculus. If the rules $\mathcal{G}(Inv^\neg)$, $\mathcal{G}(\neg)$, $\mathcal{G}(weak)$, $\mathcal{G}(init)$, $\mathcal{G}(\vee_-)$, $\mathcal{G}(\vee_+)$, $\mathcal{G}(\Pi_-^C)$ and $\mathcal{G}(\Pi_+^C)$ are admissible in \mathcal{G} , then $\Gamma_\Sigma^\mathcal{G} \in \mathfrak{Acc}_\beta$.*

We can furthermore show the following relationship between saturation and cut (see the Appendix).

Theorem 3.5. *Let \mathcal{G} be a sequent calculus.*

- (1) *If $\mathcal{G}(cut)$ is admissible in \mathcal{G} , then $\Gamma_\Sigma^\mathcal{G}$ is saturated.*
- (2) *If $\mathcal{G}(\neg)$ and $\mathcal{G}(Inv^\neg)$ are admissible in \mathcal{G} and $\Gamma_\Sigma^\mathcal{G}$ is saturated, then $\mathcal{G}(cut)$ is admissible in \mathcal{G} .*

Since saturation is equivalent to admissibility of cut, we need weaker conditions than saturation. A natural condition to consider is the existence of saturated extensions.

Definition 3.6 (Saturated Extension). Let $*$ $\in \{\square, \circ\}$ and $\Gamma_\Sigma, \Gamma'_\Sigma \in \mathfrak{Acc}_*$ be abstract consistency classes. We say Γ'_Σ is an *extension* of Γ_Σ if $\Phi \in \Gamma'_\Sigma$ for every sufficiently Σ -pure $\Phi \in \Gamma_\Sigma$. We say Γ'_Σ is a *saturated extension* of Γ_Σ if Γ'_Σ is saturated and an extension of Γ_Σ .

There exist abstract consistency classes Γ in $\mathfrak{Acc}_{\beta\text{fb}}$ which have no saturated extension.

Example 3.7. Let $a_o, b_o, q_{o \rightarrow o} \in \Sigma$ and $\Phi := \{a, b, (qa), \neg(qb)\}$. We construct an abstract consistency class Γ_Σ from Φ by first building the closure Φ' of Φ under relation \equiv_β and then taking the power set of Φ' . It is easy to check that this Γ_Σ is in $\mathfrak{Acc}_{\beta\text{fb}}$. Suppose we have a saturated extension Γ'_Σ of Γ_Σ in $\mathfrak{Acc}_{\beta\text{fb}}$. Then $\Phi \in \Gamma'_\Sigma$ since Φ is finite (hence sufficiently Σ -pure). By saturation, $\Phi * (a \doteq^o b) \in \Gamma'_\Sigma$ or $\Phi * \neg(a \doteq^o b) \in \Gamma'_\Sigma$. In the first case, applying ∇_\vee with the constant q , ∇_\vee and ∇_c contradicts $(qa), \neg(qb) \in \Phi$. In the second case, ∇_b and ∇_c contradict $a, b \in \Phi$.

Existence of any saturated extension of a sound sequent calculus \mathcal{G} implies admissibility of cut. The proof uses the model existence theorem for saturated abstract consistency classes (cf. [5](6.34)). The proof is in the Appendix.

Theorem 3.8. *Let \mathcal{G} be a sequent calculus which is sound for \mathfrak{M}_* . If $\Gamma_\Sigma^\mathcal{G}$ has a saturated extension $\Gamma'_\Sigma \in \mathfrak{Acc}_*$, then $\mathcal{G}(cut)$ is admissible in \mathcal{G} .*

3.3. Sequent Calculus \mathcal{G}_β . We now study a particular sequent calculus \mathcal{G}_β defined by the rules $\mathcal{G}(init)$, $\mathcal{G}(\neg)$, $\mathcal{G}(\vee_-)$, $\mathcal{G}(\vee_+)$, $\mathcal{G}(\Pi_-^C)$ and $\mathcal{G}(\Pi_+^c)$ (cf. Figure 2). It is easy to show that \mathcal{G}_β is sound for the eight model classes and in particular for class \mathfrak{M}_β .

The reader may easily prove the following Lemma.

Lemma 3.9. *Let $\mathbf{A} \in \text{cwff}_o(\Sigma)$ be an atom, $\mathbf{B} \in \text{cwff}_\alpha(\Sigma)$, and Δ be a sequent.*

- (1) $\Delta * \mathbf{A} \Leftrightarrow \mathbf{A} := \Delta * \neg(\neg(\neg\mathbf{A} \vee \mathbf{A}) \vee \neg(\neg\mathbf{A} \vee \mathbf{A}))$ is derivable in 7 steps in \mathcal{G}_β .
- (2) $\Delta * \mathbf{B} \doteq^\alpha \mathbf{B} := \Delta * \Pi^\alpha(\lambda P_{\alpha \rightarrow o} \neg(P\mathbf{B}) \vee (P\mathbf{B}))$ is derivable in 3 steps in \mathcal{G}_β .

The proof of the next Lemma is by induction on derivations and is given in the Appendix.

Lemma 3.10. *The rules $\mathcal{G}(Inv^-)$ and $\mathcal{G}(weak)$ are 0-admissible in \mathcal{G}_β .*

Theorem 3.11. *The sequent calculus \mathcal{G}_β is complete for the model class \mathfrak{M}_β and the rule $\mathcal{G}(cut)$ is admissible.*

Proof. By Theorem 3.4 and Lemma 3.10, $\Gamma_\Sigma^{\mathcal{G}_\beta} \in \mathfrak{Acc}_\beta$. Suppose $\Vdash_{\mathcal{G}_\beta} \Delta$ does not hold. Then $\neg\Delta \in \mathfrak{Acc}_\beta$ by Lemma 3.3. By the model existence theorem for \mathfrak{Acc}_β (cf. [6](8.1)) there exists a model for $\neg\Delta$ in \mathfrak{M}_β . This gives completeness of \mathcal{G}_β . We can use completeness to conclude cut is admissible in \mathcal{G}_β . \square

Andrews proves admissibility of cut for a sequent calculus similar to \mathcal{G}_β in [1]. The proof in [1] contains the essential ingredients for showing completeness.

While $\mathcal{G}(cut)$ is admissible in \mathcal{G}_β the next theorem shows that $\mathcal{G}(cut)$ is not k -admissible in \mathcal{G}_β for any $k \in \mathbb{N}$, which means \mathcal{G}_β is not only superficially cut-free and that by adding $\mathcal{G}(cut)$ to \mathcal{G}_β we can achieve significantly shorter proofs.

Theorem 3.12. *$\mathcal{G}(cut)$ is not k -admissible in \mathcal{G}_β for any $k \in \mathbb{N}$.*

Proof. The proof is not formally worked out here; we only sketch the argumentation: The main idea is to show that the hyper-exponential speed-up results known for first-order logic do transfer to (the first-order fragment of) our calculus. For this, we compare our sequent calculus \mathcal{G}_β with a standard first-order variant of it which we call \mathcal{G}_β^{FO} (this only requires appropriate modifications of the rules $\mathcal{G}(\Pi_-^C)$ and $\mathcal{G}(\Pi_+^c)$). Clearly, any first-order sequent which can be derived in \mathcal{G}_β^{FO} can be derived in \mathcal{G}_β with the same number of steps (using essentially the same derivation). More interestingly, one can show that for any derivation \mathcal{D} in \mathcal{G}_β of a first-order sequent Δ there is a derivation \mathcal{D}' in \mathcal{G}_β^{FO} of Δ with the same number of rule applications. (During the induction, one collapses higher-order terms to first-order terms in such a way that first-order terms collapse to themselves.) Thus no speedup with respect to first-order provability can be achieved by using \mathcal{G}_β instead of the cut-free first-order sequent calculus \mathcal{G}_β^{FO} . Finally we refer to the following results:

- Theorem 5.2.13 in [19] shows that for a classical first-order sequent calculus there is at least an exponential speed-up of proofs with cut. Furthermore, Propositions 6.11.3 and 6.11.4 there show a related hyper-exponential speed-up result.
- An example for hyper-exponential speed-up is also given in [18, 13].
- In higher-order logic the speed-up should be faster than any primitive recursive function according to the “curious inference” George Boolos presents in [7].

\square

We will now show that $\mathcal{G}(cut)$ actually becomes k -admissible in \mathcal{G}_β if certain formulae are available in the sequent Δ we wish to prove.

4. CUT-SIMULATION

4.1. Cut-Strong Formulae and Sequents. k -cut-strong formulae can be used to effectively simulate cut. Effectively means that the elimination of each application of a cut-rule introduces maximally k additional proof steps, where k is constant.

Definition 4.1. Given an arbitrary but fixed number $k > 0$. We call formula $\mathbf{A} \in \text{cuff}_o(\Sigma)$ k -cut-strong for \mathcal{G} (or simply *cut-strong*) if the following cut rule variant is k -admissible in \mathcal{G} :¹

$$\frac{\Delta * \mathbf{C} \quad \Delta * \neg \mathbf{C}}{\Delta * \neg \mathbf{A}} \mathcal{G}(cut^{\mathbf{A}})$$

We can alternative state the condition for \mathbf{A} to be k -cut-strong for \mathcal{G} as follows: For all Δ and \mathbf{C} , if $\Vdash_{\mathcal{G}} \Delta * \mathbf{C}$ in n steps and $\Vdash_{\mathcal{G}} \Delta * \neg \mathbf{C}$ in m steps, then $\Vdash_{\mathcal{G}} \Delta * \neg \mathbf{A}$ in at most $n + m + k$ steps.

Our examples below illustrate that cut-strength of a formula usually only weakly depends on the calculus \mathcal{G} : it only presumes standard ingredients such as β -normalization, weakening, and rules for the logical connectives.

We present some simple examples of cut-strong formulae for our sequent calculus \mathcal{G}_β . A corresponding phenomenon is observable in other higher-order calculi, for instance, for the calculi presented in [1, 4, 8, 12].

Example 4.2. The Formula $\forall P_o.P := \Pi^o(\lambda P_o.P)$ is 3-cut-strong in \mathcal{G}_β . This is justified by the following derivation which actually shows that rule $\mathcal{G}(cut^{\mathbf{A}})$ for this specific choice of \mathbf{A} is derivable in \mathcal{G}_β by maximally 3 additional proof steps. The only interesting proof step is the instantiation of P with formula $\mathbf{D} := \neg \mathbf{C} \vee \mathbf{C}$ in rule $\mathcal{G}(\Pi^{\mathbf{D}})$. (Note that \mathbf{C} must be β -normal; sequents such as $\Delta * \mathbf{C}$ by definition contain only β -normal formulae.)

$$\frac{\frac{\frac{\Delta * \mathbf{C}}{\Delta * \neg \neg \mathbf{C}} \mathcal{G}(\neg)}{\Delta * \neg(\neg \mathbf{C} \vee \mathbf{C})} \mathcal{G}(\vee_-)}{\Delta * \neg \Pi^o(\lambda P_o.P)} \mathcal{G}(\Pi^{\mathbf{D}})$$

Clearly, $\forall P_o.P$ is not a very interesting cut-strong formula since it implies falsehood, i.e. inconsistency.

Example 4.3. The formula $\forall P_o.P \Rightarrow P := \Pi^o(\lambda P_o.\neg P \vee P)$ is 3-cut-strong in \mathcal{G}_β . This is an example of a tautologous cut-strong formula. Now P is simply instantiated with $\mathbf{D} := \mathbf{C}$ in rule $\mathcal{G}(\Pi^{\mathbf{D}})$. Except for this first step the derivation is identical to the one for Example 4.2.

¹Here, we could alternatively use (k -)derivability (see [10]) to give a stronger but less general notion of k -cut-strongness. In fact, all axioms we discuss in this paper would remain k -cut-strong. From a proof theoretic point of view one may argue that this alternative notion leads to a more interesting result although it may generally apply to fewer axioms.

Example 4.4. Leibniz equations $\mathbf{M} \doteq^\alpha \mathbf{N} := \Pi^\alpha(\lambda P. \neg PM \vee PN)$ (for arbitrary formulae $\mathbf{M}, \mathbf{N} \in \text{cwoff}_\alpha(\Sigma)$ and types $\alpha \in \mathcal{T}$) are 3-cut-strong in \mathcal{G}_β . This includes the special cases $\mathbf{M} \doteq^\alpha \mathbf{M}$. Now P is instantiated with $\mathbf{D} := \lambda X_\alpha. \mathbf{C}$ in rule $\mathcal{G}(\Pi_-^{\mathbf{D}})$. Except for this first step the derivation is identical to the one for Example 4.2.

Example 4.5. The original formulation of higher-order logic (cf. [15]) contained comprehension axioms of the form $\mathcal{C} := \exists P_{\alpha^1 \rightarrow \dots \rightarrow \alpha^n \rightarrow o} \forall \overline{X^n}. P \overline{X^n} \Leftrightarrow \mathbf{B}_o$, where $\mathbf{B}_o \in \text{wff}_o(\Sigma)$ is arbitrary with $P \notin \text{free}(\mathbf{B})$. Church eliminated the need for such axioms by formulating higher-order logic using typed λ -calculus. We will now show that the instance $\mathcal{C}^I := \exists P_{\iota \rightarrow o} \forall X_\iota. P X \Leftrightarrow X \doteq^\iota X$ is 16-cut-strong in \mathcal{G}_β (note that $\mathcal{G}(\text{weak})$ is 0-admissible). This motivates building-in comprehension principles instead of treating comprehension axiomatically.

$$\begin{array}{c}
\text{3 steps; see Lemma 3.9} \\
\vdots \\
\frac{\Delta * \neg(pa \Rightarrow a \doteq^\iota a) * a \doteq^\iota a}{\Delta * \neg(pa \Rightarrow a \doteq^\iota a) * \neg\neg(a \doteq^\iota a)} \mathcal{G}(\neg) \quad \mathcal{D} \\
\frac{\Delta * \neg(pa \Rightarrow a \doteq^\iota a) * \neg\neg(a \doteq^\iota a)}{\Delta * \neg(pa \Rightarrow a \doteq^\iota a) * \neg(\neg(a \doteq^\iota a) \vee pa)} \mathcal{G}(\vee_-) \\
\frac{\Delta * \neg(pa \Rightarrow a \doteq^\iota a) * \neg(\neg(a \doteq^\iota a) \vee pa)}{\Delta * \neg(pa \Rightarrow a \doteq^\iota a) \vee \neg(a \doteq^\iota a \Rightarrow pa)} \mathcal{G}(\vee_+) \\
\frac{\Delta * \neg(pa \Rightarrow a \doteq^\iota a) \vee \neg(a \doteq^\iota a \Rightarrow pa)}{\Delta * \neg\neg(\neg(pa \Rightarrow a \doteq^\iota a) \vee \neg(a \doteq^\iota a \Rightarrow pa))} \mathcal{G}(\neg) \\
\frac{\Delta * \neg\neg(\neg(pa \Rightarrow a \doteq^\iota a) \vee \neg(a \doteq^\iota a \Rightarrow pa))}{\Delta * \neg\Pi^\iota(\lambda X_\iota. p X \Leftrightarrow X \doteq^\iota X)} \mathcal{G}(\Pi^{a_\iota}) \\
\frac{\Delta * \neg\Pi^\iota(\lambda X_\iota. p X \Leftrightarrow X \doteq^\iota X)}{\Delta * \Pi^{\iota \rightarrow o}(\lambda P^{\iota \rightarrow o}. \neg\Pi^\iota(\lambda X_\iota. p X \Leftrightarrow X \doteq^\iota X))} \mathcal{G}(\Pi_+^{p_\iota \rightarrow o}) \\
\frac{\Delta * \Pi^{\iota \rightarrow o}(\lambda P^{\iota \rightarrow o}. \neg\Pi^\iota(\lambda X_\iota. p X \Leftrightarrow X \doteq^\iota X))}{\Delta * \mathcal{C}^I} \mathcal{G}(\neg)
\end{array}$$

Derivation \mathcal{D} is:

$$\begin{array}{c}
\Delta * \mathbf{C} \quad \Delta * \neg \mathbf{C} \\
\vdots \text{ 3 steps; see Ex. 4.4} \\
\frac{\Delta * pa * \neg pa}{\Delta * \neg\neg pa * \neg pa} \mathcal{G}(\text{init}) \quad \frac{\Delta * \neg(a \doteq^o a)}{\Delta * \neg(a \doteq^\iota a) * \neg pa} \mathcal{G}(\text{weak}) \\
\frac{\Delta * \neg\neg pa * \neg pa}{\Delta * \neg(\neg pa \vee a \doteq^\iota a) * \neg pa} \mathcal{G}(\neg) \quad \mathcal{G}(\vee_-)
\end{array}$$

As we will show later, many prominent axioms for higher-order logic also belong to the class of cut-strong formulae.

4.2. Cut-Simulation. The cut-simulation theorem is a main result of this paper. It says that cut-strong sequents support an effective simulation (and thus elimination) of cut in \mathcal{G}_β . Effective means that the size of cut-free derivation grows only linearly for the number of cut rule applications to be eliminated.

Definition 4.6. A sequent Δ is called *k-cut-strong* (or simply *cut-strong*) if there exists a *k-cut-strong* formula $\mathbf{A} \in \text{cwoff}_o(\Sigma)$ such that $\neg \mathbf{A} \in \Delta$. We call \mathbf{A} the *k-realizer* of Δ .

We first fix the following calculi: Calculus $\mathcal{G}_\beta^{\text{cut}}$ extends \mathcal{G}_β by the rule $\mathcal{G}(\text{cut})$ and calculus $\mathcal{G}_\beta^{\text{cut}^\mathbf{A}}$ extends \mathcal{G}_β by the rule $\mathcal{G}(\text{cut}^\mathbf{A})$ for some arbitrary but fixed cut-strong formula \mathbf{A} .

Theorem 4.7. *Let Δ be a k -cut-strong sequent with realizer \mathbf{A} . For each derivation $\mathcal{D}: \Vdash_{\mathcal{G}_\beta^{\text{cut}}} \Delta$ with d proof steps there is an alternative derivation $\mathcal{D}': \Vdash_{\mathcal{G}_\beta^{\text{cut}^\mathbf{A}}} \Delta$ with d proof steps.*

Proof. Note that the rules $\mathcal{G}(\text{cut})$ and $\mathcal{G}(\text{cut}^\mathbf{A})$ coincide whenever $\neg\mathbf{A} \in \Delta$. Intuitively, we can replace each occurrence of $\mathcal{G}(\text{cut})$ in \mathcal{D} by $\mathcal{G}(\text{cut}^\mathbf{A})$ in order to obtain a \mathcal{D}' of same size. Technically, in the induction proof one must weaken to ensure $\neg\mathbf{A}$ stays in the sequent and carry out a parameter renaming to make sure the eigenvariable condition is satisfied. \square

Theorem 4.8. *Let Δ be a k -cut-strong sequent with realizer \mathbf{A} . For each derivation $\mathcal{D}: \Vdash_{\mathcal{G}_\beta^{\text{cut}^\mathbf{A}}} \Delta$ with d proof steps and with n applications of rule $\mathcal{G}(\text{cut})$ there exists an alternative derivation $\mathcal{D}': \Vdash_{\mathcal{G}_\beta} \Delta$ with maximally $d + nk$ proof steps.*

Proof. \mathbf{A} is k -cut-strong so by definition $\mathcal{G}(\text{cut}^\mathbf{A})$ is k -admissible in \mathcal{G}_β . This means that $\mathcal{G}(\text{cut}^\mathbf{A})$ can be eliminated in \mathcal{D} and each single elimination of $\mathcal{G}(\text{cut}^\mathbf{A})$ introduces maximally k new proof steps. Now the assertion can be easily obtained by a simple induction over n . \square

Corollary 4.9. *Let Δ be a k -cut-strong sequent. For each derivation $\mathcal{D}: \Vdash_{\mathcal{G}_\beta^{\text{cut}}} \Delta$ with d proof steps and n applications of rule $\mathcal{G}(\text{cut})$ there exists an alternative cut-free derivation $\mathcal{D}': \Vdash_{\mathcal{G}_\beta} \Delta$ with maximally $d + nk$ proof steps.*

5. THE EXTENSIONALITY AXIOMS ARE CUT-STRONG

We have shown comprehension axioms can be cut-strong (cf. Example 4.5). Further prominent examples of cut-strong formulae are the Boolean and functional extensionality axioms. The Boolean extensionality axiom (abbreviated as \mathcal{B}_o in the remainder) is

$$\forall A_o \cdot \forall B_o \cdot (A \Leftrightarrow B) \Rightarrow A \doteq^o B$$

The infinitely many functional extensionality axioms (abbreviated as $\mathcal{F}_{\alpha\beta}$) are parameterized over $\alpha, \beta \in \mathcal{T}$.

$$\forall F_{\alpha \rightarrow \beta} \cdot \forall G_{\alpha \rightarrow \beta} \cdot (\forall X_\alpha \cdot FX \doteq^\beta GX) \Rightarrow F \doteq^{\alpha \rightarrow \beta} G$$

These axioms usually have to be added to higher-order calculi to reach Henkin completeness, i.e. completeness with respect to model class $\mathfrak{M}_{\beta\text{fb}}$. For example, Huet's constrained resolution approach as presented in [12] is not Henkin complete without adding extensionality axioms. The need for adding Boolean extensionality to this calculus is actually illustrated by the set of unit literals $\Phi := \{a, b, (qa), \neg(qb)\}$ from Example 3.7. As the reader may easily check, this clause set Φ , which is inconsistent for Henkin semantics, cannot be proven by Huet's system without, e.g., adding the Boolean extensionality axiom. By relying on results in [1], Huet essentially shows completeness with respect to model class \mathfrak{M}_β as opposed to Henkin semantics.

We will now investigate whether adding the extensionality axioms to a machine-oriented calculus in order to obtain Henkin completeness is a suitable option.

Theorem 5.1. *The Boolean extensionality axiom \mathcal{B}_o is a 14-cut-strong formula in \mathcal{G}_β .*

Proof. The following derivation justifies this theorem (a_o is a parameter).

$$\begin{array}{c}
 \text{7 steps; see Lemma 3.9} \\
 \vdots \\
 \frac{\Delta * a \Leftrightarrow a}{\Delta * \neg(a \Leftrightarrow a)} \mathcal{G}(\neg) \quad \frac{\Delta * \mathbf{C} \quad \Delta * \neg \mathbf{C}}{\Delta * \neg(a \doteq^o a)} \text{3 steps; see Ex. 4.4} \\
 \hline
 \frac{\Delta * \neg(\neg(a \Leftrightarrow a) \vee a \doteq^o a)}{\Delta * \neg \mathcal{B}_o} \mathcal{G}(\vee_-) \quad 2 \times \mathcal{G}(\Pi_-^a)
 \end{array}$$

□

Theorem 5.2. *The functional extensionality axioms $\mathcal{F}_{\alpha\beta}$ are 11-cut-strong formulae in \mathcal{G}_β .*

Proof. The following derivation justifies this theorem ($f_{\alpha \rightarrow \beta}$ is a parameter).

$$\begin{array}{c}
 \text{3 steps; see Lemma 3.9} \\
 \vdots \\
 \frac{\Delta * fa \doteq^\beta fa}{\Delta * (\forall X_\alpha. fX \doteq^\beta fX)} \mathcal{G}(\Pi_+^{a_\alpha}) \quad \frac{\Delta * \mathbf{C} \quad \Delta * \neg \mathbf{C}}{\Delta * \neg(f \doteq^{\alpha \rightarrow \beta} f)} \text{3 steps; see Ex. 4.4} \\
 \hline
 \frac{\Delta * \neg(\neg(\forall X_\alpha. fX \doteq^\beta fX) \vee f \doteq^{\alpha \rightarrow \beta} f)}{\Delta * \neg \mathcal{F}_{\alpha\beta}} \mathcal{G}(\vee_-) \quad 2 \times \mathcal{G}(\Pi_-^f)
 \end{array}$$

□

In [4] and [8] we have already argued that the extensionality principles should not be treated axiomatically in machine-oriented higher-order calculi and there we have developed resolution and sequent calculi in which these principles are built-in. Here we have now developed a strong theoretical justification for this work: Corollary 4.9 along with Theorems 5.2 and 5.1 tell us that adding the extensionality principles \mathcal{B}_o and $\mathcal{F}_{\alpha\beta}$ as axioms to a calculus is like adding a cut rule.

In Figure 3 we show rules that add Boolean and functional extensionality in an axiomatic manner to \mathcal{G}_β . More precisely we add rules $\mathcal{G}(\mathcal{F}_{\alpha\beta})$ and $\mathcal{G}(\mathcal{B})$ allowing to introduce the axioms for any sequent Δ ; this way we address the problem of the infinitely many possible instantiations of the type-schematic functional extensional axiom $\mathcal{F}_{\alpha\beta}$.

$$\frac{\Delta * \neg \mathcal{F}_{\alpha\beta} \quad \alpha \rightarrow \beta \in \mathcal{T}}{\Delta} \mathcal{G}(\mathcal{F}_{\alpha\beta}) \quad \frac{\Delta * \neg \mathcal{B}_o}{\Delta} \mathcal{G}(\mathcal{B})$$

Figure 3: Axiomatic Extensionality Rules

Calculus \mathcal{G}_β enriched by the new rules $\mathcal{G}(\mathcal{F}_{\alpha\beta})$ and $\mathcal{G}(\mathcal{B})$ is called \mathcal{G}_β^E . Soundness of the the new rules is easy to verify: In [5](4.3) we show that $\mathcal{G}(\mathcal{F}_{\alpha\beta})$ and $\mathcal{G}(\mathcal{B})$ are valid for Henkin models.

$$\frac{\Delta * (\forall X_{\alpha} \cdot \mathbf{A}X \doteq^{\beta} \mathbf{B}X) \Big|_{\beta}}{\Delta * (\mathbf{A} \doteq^{\alpha \rightarrow \beta} \mathbf{B})} \mathcal{G}(\mathbf{f}) \qquad \frac{\Delta * \neg \mathbf{A} * \mathbf{B} \quad \Delta * \neg \mathbf{B} * \mathbf{A}}{\Delta * (\mathbf{A} \doteq^{\circ} \mathbf{B})} \mathcal{G}(\mathbf{b})$$

Figure 4: Proper Extensionality Rules

5.1. Replacing the Extensionality Axioms. In Figure 4 we define alternative extensionality rules which correspond to those developed for resolution and sequent calculi in [4] and [8].

Calculus \mathcal{G}_{β} enriched by $\mathcal{G}(\mathbf{f})$ and $\mathcal{G}(\mathbf{b})$ is called $\mathcal{G}_{\beta\mathbf{fb}}^{-}$. Soundness of $\mathcal{G}(\mathbf{f})$ and $\mathcal{G}(\mathbf{b})$ for Henkin semantics is again easy to show.

Our aim is to develop a machine-oriented sequent calculus for automating Henkin complete proof search. We argue that for this purpose $\mathcal{G}(\mathbf{f})$ and $\mathcal{G}(\mathbf{b})$ are more suitable rules than $\mathcal{G}(\mathcal{F}_{\alpha\beta})$ and $\mathcal{G}(\mathcal{B})$.

Our next step now is to show Henkin completeness for \mathcal{G}_{β}^E . This will be relatively easy since we can employ cut-simulation. Then we analyze whether calculus $\mathcal{G}_{\beta\mathbf{fb}}^{-}$ has the same deductive power as \mathcal{G}_{β}^E .

First we extend Theorem 3.4. The proof is given in the Appendix.

Theorem 5.3. *Let \mathcal{G} be a sequent calculus such that $\mathcal{G}(\text{Inv}^{\neg})$ and $\mathcal{G}(\neg)$ are admissible.*

- (1) *If $\mathcal{G}(\mathbf{f})$ and $\mathcal{G}(\Pi_{+}^c)$ are admissible, then $\Gamma_{\Sigma}^{\mathcal{G}}$ satisfies $\nabla_{\mathbf{f}}$.*
- (2) *If $\mathcal{G}(\mathbf{b})$ is admissible, then $\Gamma_{\Sigma}^{\mathcal{G}}$ satisfies $\nabla_{\mathbf{b}}$.*

Theorem 5.4. *The sequent calculus \mathcal{G}_{β}^E is Henkin complete and the rule $\mathcal{G}(\text{cut})$ is 12-admissible.*

Proof. $\mathcal{G}(\text{cut})$ can be effectively simulated and hence eliminated in \mathcal{G}_{β}^E by combining rule $\mathcal{G}(\mathcal{F}_{\alpha\beta})$ with the 11-step derivation presented in the proof of Theorem 5.2.

Let $\Gamma_{\Sigma}^{\mathcal{G}_{\beta}^E}$ be defined as in Definition 3.2. We prove Henkin completeness of \mathcal{G}_{β}^E by showing that the class $\Gamma_{\Sigma}^{\mathcal{G}_{\beta}^E}$ is a saturated abstract consistency class in $\mathfrak{Acc}_{\beta\mathbf{fb}}$. We here only analyze the crucial conditions $\nabla_{\mathbf{b}}$, $\nabla_{\mathbf{f}}$ and ∇_{sat} . For the other conditions we refer to Theorem 3.4. Note that 0-admissibility of $\mathcal{G}(\text{Inv}^{\neg})$ and $\mathcal{G}(\text{weak})$ can be shown for \mathcal{G}_{β}^E by a suitable induction on derivations as in Lemma 3.10.

$\nabla_{\mathbf{f}}$: $\mathcal{G}(\Pi_{+}^c)$ is a rule of \mathcal{G}_{β}^E and thus admissible. According to Theorem 5.3 it is thus sufficient to ensure admissibility of rule $\mathcal{G}(\mathbf{f})$ to show $\nabla_{\mathbf{f}}$. This is justified by the following derivation where $\mathbf{N} := \mathbf{A} \doteq^{\alpha \rightarrow \beta} \mathbf{B}$ and $\mathbf{M} := (\forall X_{\alpha} \cdot \mathbf{A}X \doteq^{\beta} \mathbf{B}X) \Big|_{\beta}$ (for β -normal \mathbf{A}, \mathbf{B}).

$$\frac{\Delta * (\forall X_{\alpha} \cdot \mathbf{A}X \doteq^{\beta} \mathbf{B}X) \Big|_{\beta}}{\Delta * \mathbf{N} * \neg \neg \mathbf{M}} \mathcal{G}(\mathbf{f}) \quad \begin{array}{c} \text{derivable} \\ \vdots \\ \mathcal{G}(\text{weak}) \end{array} \quad \frac{\Delta * \mathbf{N} * \neg \mathbf{N}}{\Delta * \mathbf{N} * \neg(\neg \mathbf{M} \vee \mathbf{N})} \mathcal{G}(\vee_{-})}{\frac{\Delta * \mathbf{N} * \neg \mathcal{F}_{\alpha\beta}}{\Delta * \mathbf{A} \doteq^{\alpha \rightarrow \beta} \mathbf{B}} \mathcal{G}(\mathcal{F}_{\alpha\beta})} \mathcal{G}(\Pi^{\mathbf{A}}), \mathcal{G}(\Pi^{\mathbf{B}})}$$

$\nabla_{\mathfrak{b}}$: With a similar derivation using $\mathcal{G}(\mathcal{B})$ we can show that $\mathcal{G}(\mathfrak{b})$ is admissible. We conclude $\nabla_{\mathfrak{b}}$ by Theorem 5.3.

∇_{sat} : Since $\mathcal{G}(cut)$ is admissible we get saturation by Theorem 3.5. \square

Does $\mathcal{G}_{\beta\mathfrak{fb}}^-$ have the same deductive strength as \mathcal{G}_{β}^E ? I.e., is $\mathcal{G}_{\beta\mathfrak{fb}}^-$ Henkin complete? We show this is not yet the case.

Theorem 5.5. *The sequent calculus $\mathcal{G}_{\beta\mathfrak{fb}}^-$ is not complete for Henkin semantics.*

We illustrate the problem by a counterexample.

Example 5.6. Consider the sequent $\Delta := \{-a, \neg b, \neg(qa), (qb)\}$ where $a_o, b_o, q_{o \rightarrow o} \in \Sigma$ are parameters. For any $\mathcal{M} \equiv (\mathcal{D}, @, \mathcal{E}, v) \in \mathfrak{M}_{\beta\mathfrak{fb}}$, either $v(\mathcal{E}(a)) \equiv \mathbf{F}$, $v(\mathcal{E}(b)) \equiv \mathbf{F}$ or $\mathcal{E}(a) \equiv \mathcal{E}(b)$ by property \mathfrak{b} . Hence sequent Δ is valid for every $\mathcal{M} \in \mathfrak{M}_{\beta\mathfrak{fb}}$. However, $\Vdash_{\mathcal{G}_{\beta\mathfrak{fb}}^-} \Delta$ does not hold. By inspection, Δ cannot be the conclusion of any rule.

In order to reach Henkin completeness and to show cut-elimination we thus need to add further rules. Our example motivates the two rules presented in Figure 5. $\mathcal{G}(Init^{\dot{=}})$ introduces Leibniz equations such as $qa \dot{=}^o qb$ as is needed in our example and $\mathcal{G}(d)$ realizes the required decomposition into $a \dot{=}^o b$.

$$\frac{\Delta * (\mathbf{A} \dot{=}^o \mathbf{B}) \quad (\dagger)}{\Delta * \neg \mathbf{A} * \mathbf{B}} \mathcal{G}(Init^{\dot{=}}) \qquad \frac{\Delta * (\mathbf{A}^1 \dot{=}^{\alpha_1} \mathbf{B}^1) \dots \Delta * (\mathbf{A}^n \dot{=}^{\alpha_n} \mathbf{B}^n) \quad (\ddagger)}{\Delta * (h\overline{\mathbf{A}}^n \dot{=}^{\beta} h\overline{\mathbf{B}}^n)} \mathcal{G}(d)$$

(\dagger) \mathbf{A}, \mathbf{B} atomic (\ddagger) $n \geq 1, \beta \in \{o, \iota\}, h_{\alpha^n \rightarrow \beta} \in \Sigma$ parameter

Figure 5: Additional Rules $\mathcal{G}(Init^{\dot{=}})$ and $\mathcal{G}(d)$

We thus extend the sequent calculus $\mathcal{G}_{\beta\mathfrak{fb}}^-$ to $\mathcal{G}_{\beta\mathfrak{fb}}$ by adding the decomposition rule $\mathcal{G}(d)$ and the rule $\mathcal{G}(Init^{\dot{=}})$ which generally checks if two atomic sentences of opposite polarity are provably equal (as opposed to syntactically equal).

Is $\mathcal{G}_{\beta\mathfrak{fb}}$ complete for Henkin semantics? We will show in the next Section that this indeed holds (cf. Theorem 6.3).

With \mathcal{G}^E and $\mathcal{G}_{\beta\mathfrak{fb}}$ we have thus developed two Henkin complete calculi and both calculi are cut-free. However, as our exploration shows, “cut-freeness” is not a well-chosen criterion to differentiate between their suitability for proof search automation: \mathcal{G}^E inherently supports effective cut-simulation and thus cut-freeness is meaningless.

The next claim, which is analogous to Theorem 3.12, has not been formally proven yet. It claims that, in contrast to \mathcal{G}^E , the cut-freeness of $\mathcal{G}_{\beta\mathfrak{fb}}$ is meaningful.

Claim 1. $\mathcal{G}(cut)$ is not k -admissible in $\mathcal{G}_{\beta\mathfrak{fb}}$.

The proof idea is similar to that of Theorem 3.12, however, the two additional rules $\mathcal{G}(Init^{\dot{=}})$ and $\mathcal{G}(d)$ do introduce additional technicalities which we have not fully worked out yet.

The criterion we propose for the analysis of calculi in impredicative logics is “freeness of effective cut-simulation”. The idea behind this notion is to capture also hidden sources (such as the extensionality axioms) where the subformula property may break and where the cut rule may creep in through the backdoor.

5.2. Other Rules for Other Model Classes. In [6] we developed respective complete and cut-free sequent calculi not only for Henkin semantics but for five of the eight model classes. In particular, no additional rules are required for the β , $\beta\eta$ and $\beta\xi$ case. Meanwhile, the $\beta\mathfrak{f}$ case requires additional rules allowing η -conversion. We do not present and analyze these cases here.

6. ACCEPTABILITY CONDITIONS

We now turn our attention again to the existence of saturated extensions of abstract consistency classes.

As illustrated by Example 3.7, we need some extra abstract consistency properties to ensure the existence of saturated extensions. We call these extra properties *acceptability conditions*. They actually closely correspond to additional rules $\mathcal{G}(\text{Init}^{\dot{=}})$ and $\mathcal{G}(d)$.

Definition 6.1 (Acceptability Conditions). Let Γ_{Σ} be an abstract consistency class in $\mathfrak{Acc}_{\beta\mathfrak{f}}$. We define the following properties:

- ∇_m If $\mathbf{A}, \mathbf{B} \in \text{cuff}_o(\Sigma)$ are atomic and $\mathbf{A}, \neg\mathbf{B} \in \Phi$, then $\Phi * \neg(\mathbf{A} \dot{=}^o \mathbf{B}) \in \Gamma_{\Sigma}$.
- ∇_d If $\neg(h\overline{\mathbf{A}^n} \dot{=}^{\beta} h\overline{\mathbf{B}^n}) \in \Phi$ for some types α_i where $\beta \in \{o, \iota\}$ and $h_{\alpha^n \rightarrow \beta} \in \Sigma$ is a parameter, then there is an i ($1 \leq i \leq n$) such that $\Phi * \neg(\mathbf{A}^i \dot{=}^{\alpha^i} \mathbf{B}^i) \in \Gamma_{\Sigma}$.

We now replace the strong saturation condition used in [5] by these acceptability conditions.

Definition 6.2 (Acceptable Classes). An abstract consistency class $\Gamma_{\Sigma} \in \mathfrak{Acc}_{\beta\mathfrak{f}}$ is called *acceptable* in $\mathfrak{Acc}_{\beta\mathfrak{f}}$ if it satisfies the conditions ∇_m and ∇_d .

One can show a model existence theorem for acceptable abstract consistency classes in $\mathfrak{Acc}_{\beta\mathfrak{f}}$ (cf. [6](8.1)). From this model existence theorem, one can conclude $\mathcal{G}_{\beta\mathfrak{f}}$ is complete for $\mathfrak{M}_{\beta\mathfrak{f}}$ (hence for Henkin models) and that cut is admissible in $\mathcal{G}_{\beta\mathfrak{f}}$.

Theorem 6.3. *The sequent calculus $\mathcal{G}_{\beta\mathfrak{f}}$ is complete for Henkin semantics and the rule $\mathcal{G}(\text{cut})$ is admissible.*

Proof. The argumentation is similar to Theorem 3.11 but here we employ the acceptability conditions ∇_m and ∇_d . □

One can further show the **Saturated Extension Theorem** (cf. [6](9.3)):

Theorem 6.4. *There is a saturated abstract consistency class in $\mathfrak{Acc}_{\beta\mathfrak{f}}$ that is an extension of all acceptable Γ_{Σ} in $\mathfrak{Acc}_{\beta\mathfrak{f}}$.*

Given Theorem 3.8, one can view the Saturated Extension Theorem as an abstract cut-elimination result.

The proof of a model existence theorem employs Hintikka sets and in the context of studying Hintikka sets we have identified a phenomenon related to cut-strength which we call the *Impredicativity Gap*. That is, a Hintikka set \mathcal{H} is saturated if any cut-strong formula \mathbf{A} (e.g. a Leibniz equation $\mathbf{C} \dot{=} \mathbf{D}$) is in \mathcal{H} . Hence we can reasonably say there is a “gap” between saturated and unsaturated Hintikka sets. Every Hintikka set is either saturated or contains no cut-strong formulae.

7. CONCLUSION

We have shown that adding cut-strong formulae to a calculus for an impredicative logic is like adding cut. For machine-oriented automated theorem proving in impredicative logics — such as classical type theory — it is therefore not recommendable to naively add cut-strong axioms to the search space. In addition to the comprehension principle and the functional and Boolean extensionality axioms as elaborated in this paper the list of cut-strong axioms includes:

Example 7.1 (Other Forms of Defined Equality.). Formulas $\mathbf{A} \doteq^\alpha \mathbf{B}$ are 4-cut-strong in \mathcal{G}_β where \doteq^α is $\lambda X_\alpha.\lambda Y_\alpha.\forall Q_{\alpha \rightarrow \alpha \rightarrow \sigma}(\forall Z_\alpha.(Q Z Z)) \Rightarrow (Q X Y)$ (cf. [3]). The argument is similar to Examples 4.2-4.5; here we the crucial step is to instantiate Q with $\lambda X_\alpha.\lambda Y_\alpha.\mathbf{C}$.

Example 7.2 (Axiom of Induction.). The *axiom of induction* for the naturals $\forall P_{\iota \rightarrow \sigma}.P0 \wedge (\forall X_\iota.PX \Rightarrow P(sX)) \Rightarrow \forall X_\iota.PX$ is 18-cut-strong in \mathcal{G}_β . (Other well-founded ordering axioms are analogous.) The crucial step in the proof is to instantiate P with $\lambda X_\iota.a \doteq^\sigma a$ for some parameter a_σ .

Example 7.3 (Axiom of Choice.). $\exists I_{(\alpha \rightarrow \sigma) \rightarrow \sigma}.\forall Q_{\alpha \rightarrow \sigma}(\exists X_\alpha.QX) \Rightarrow Q(IQ)$ is 7-cut-strong in \mathcal{G}_β . The crucial step is to instantiate Q with $\lambda X_\alpha.\mathbf{C}$.

Example 7.4 (Axiom of Description.). $\exists I_{(\alpha \rightarrow \sigma) \rightarrow \sigma}.\forall Q_{\alpha \rightarrow \sigma}(\exists_1 Y_\alpha.QY) \Rightarrow Q(IQ)$, the *description axiom* (see [2]), where $\exists_1 Y_\alpha.QY$ stands for $\exists Y_\alpha.QY \wedge (\forall Z_\alpha.QZ \Rightarrow Y \doteq Z)$ is 25-cut-strong in \mathcal{G}_β . The crucial step in the proof is to instantiate Q with $\lambda X_\alpha.a \doteq^\alpha X$ for some parameter a_α .

As we have shown in Example 4.5, comprehension axioms can be cut-strong. Church's formulation of type theory (cf. [9]) used typed λ -calculus to build comprehension principles into the language. One can view Church's formulation as a first step in the program to eliminate the need for cut-strong axioms. For the extensionality axioms a start has been made by the sequent calculi in this paper (and [6]), for resolution in [4] and for sequent calculi and extensional expansion proofs in [8]. The extensional systems in [8] also provide a complete method for using primitive equality instead of Leibniz equality. For improving the automation of higher-order logic our exploration thus motivates the development of higher-order calculi which directly include reasoning principles for equality, extensionality, induction, choice, description, etc., without using cut-strong axioms.

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APPENDIX

Proof of Lemma 3.3.

Proof. Suppose $\Phi \cup \neg\Delta \notin \Gamma_\Sigma^{\mathcal{G}}$. By definition, $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_{\beta} \cup \neg \neg \Delta \downarrow_{\beta}$ holds. Applying $\mathcal{G}(Inv^{\neg})$ to each member of $\Delta \downarrow_{\beta}$, we have $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_{\beta} \cup \Delta \downarrow_{\beta}$. \square

Proof of Theorem 3.4:

Proof. We prove $\Gamma_\Sigma^{\mathcal{G}}$ is closed under subsets and satisfies ∇_c , ∇_{\neg} , ∇_{\vee} , ∇_{\wedge} and ∇_{β} . The remaining conditions are proven analogously.

Suppose $\Phi \in \Gamma_\Sigma^{\mathcal{G}}$. If $\Phi_0 \subseteq \Phi$ and $\Phi_0 \notin \Gamma_\Sigma^{\mathcal{G}}$, then $\Vdash_{\mathcal{G}} \neg \Phi_0 \downarrow_{\beta}$ and so $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_{\beta}$ by admissibility of $\mathcal{G}(weak)$. Hence $\Gamma_\Sigma^{\mathcal{G}}$ is closed under subsets.

Suppose $\Phi \in \Gamma_\Sigma^{\mathcal{G}}$ and $\mathbf{A}, \neg\mathbf{A} \in \Phi$ where \mathbf{A} is atomic. By admissibility of $\mathcal{G}(init)$, $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_{\beta} * \mathbf{A} \downarrow_{\beta}$ since $\neg \mathbf{A} \downarrow_{\beta} \in \neg \Phi \downarrow_{\beta}$. By admissibility of $\mathcal{G}(\neg)$, $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_{\beta}$ since $\neg \neg \mathbf{A} \downarrow_{\beta} \in \neg \Phi \downarrow_{\beta}$, contradicting $\Phi \in \Gamma_\Sigma^{\mathcal{G}}$. Thus ∇_c holds.

Suppose $\Phi \in \Gamma_\Sigma^{\mathcal{G}}$, $\neg\neg\mathbf{A} \in \Phi$ and $\Phi * \mathbf{A} \notin \Gamma_\Sigma^{\mathcal{G}}$. Hence $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_{\beta} * \neg \mathbf{A} \downarrow_{\beta}$ and so $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_{\beta} * \neg\neg\neg \mathbf{A} \downarrow_{\beta}$ by admissibility of $\mathcal{G}(\neg)$. Since $\neg\neg\mathbf{A} \in \Phi$, we know $\neg \Phi \downarrow_{\beta}$ is equal to $\neg \Phi \downarrow_{\beta} * \neg\neg\neg \mathbf{A} \downarrow_{\beta}$. Hence $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_{\beta}$, contradicting $\Phi \in \Gamma_\Sigma^{\mathcal{G}}$. Thus ∇_{\neg} holds.

Suppose $\Phi \in \Gamma_\Sigma^{\mathcal{G}}$, $(\mathbf{A} \vee \mathbf{B}) \in \Phi$, $\Phi * \mathbf{A} \notin \Gamma_\Sigma^{\mathcal{G}}$ and $\Phi * \mathbf{B} \notin \Gamma_\Sigma^{\mathcal{G}}$. Hence $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_{\beta} * \neg \mathbf{A} \downarrow_{\beta}$ and $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_{\beta} * \neg \mathbf{B} \downarrow_{\beta}$. Applying $\mathcal{G}(\vee_-)$, we have $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_{\beta}$ since $\neg(\mathbf{A} \vee \mathbf{B}) \downarrow_{\beta} \in \neg \Phi \downarrow_{\beta}$, contradicting $\Phi \in \Gamma_\Sigma^{\mathcal{G}}$. Thus ∇_{\vee} holds.

By a similar argument, admissibility of $\mathcal{G}(\Pi^C)$ implies ∇_{\vee} .

Suppose $\Phi \in \Gamma_\Sigma^{\mathcal{G}}$, $\neg(\mathbf{A} \vee \mathbf{B}) \in \Phi$ and $\Phi * \neg\mathbf{A} * \neg\mathbf{B} \notin \Gamma_\Sigma^{\mathcal{G}}$. By Lemma 3.3, $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_{\beta} * \mathbf{A} \downarrow_{\beta} * \mathbf{B} \downarrow_{\beta}$. Applying $\mathcal{G}(\vee_+)$, we have $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_{\beta} * (\mathbf{A} \vee \mathbf{B}) \downarrow_{\beta}$. Applying $\mathcal{G}(\neg)$, we have $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_{\beta}$ since $\neg(\mathbf{A} \vee \mathbf{B}) \in \Phi$, contradicting $\Phi \in \Gamma_\Sigma^{\mathcal{G}}$. Thus ∇_{\wedge} holds.

By a similar argument, admissibility of $\mathcal{G}(\Pi^c)$, $\mathcal{G}(Inv^{\neg})$ and $\mathcal{G}(\neg)$ imply ∇_{\exists} .

Suppose $\Phi \in \Gamma_\Sigma^{\mathcal{G}}$, $\mathbf{A} \in \Phi$, $\mathbf{A} \equiv_{\beta} \mathbf{B}$ and $\Phi * \mathbf{B} \notin \Gamma_\Sigma^{\mathcal{G}}$. Hence $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_{\beta} * \neg \mathbf{B} \downarrow_{\beta}$, contradicting $\mathbf{A} \downarrow_{\beta} \in \Phi \downarrow_{\beta}$ and $\Phi \in \Gamma_\Sigma^{\mathcal{G}}$. Thus ∇_{β} holds. \square

Proof of Theorem 3.5:

Proof. Suppose $\mathcal{G}(cut)$ is admissible, $\Phi \in \Gamma_\Sigma^{\mathcal{G}}$, $\mathbf{A} \in cwoff_o(\Sigma)$, $\Phi * \mathbf{A} \notin \Gamma_\Sigma^{\mathcal{G}}$ and $\Phi * \neg\mathbf{A} \notin \Gamma_\Sigma^{\mathcal{G}}$. Hence $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_{\beta} * \neg \mathbf{A} \downarrow_{\beta}$ and $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_{\beta} * \neg\neg \mathbf{A} \downarrow_{\beta}$. Using $\mathcal{G}(cut)$, we have $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_{\beta}$, contradicting $\Phi \in \Gamma_\Sigma^{\mathcal{G}}$.

Suppose $\Gamma_\Sigma^{\mathcal{G}}$ is saturated, $\Vdash_{\mathcal{G}} \Delta * \mathbf{C}$ and $\Vdash_{\mathcal{G}} \Delta * \neg\mathbf{C}$ hold but $\Vdash_{\mathcal{G}} \Delta$ does not. Applying $\mathcal{G}(\neg)$ to every member of Δ and to \mathbf{C} we have $\Vdash_{\mathcal{G}} \neg\neg\Delta * \neg\neg\mathbf{C}$ and $\Vdash_{\mathcal{G}} \neg\neg\Delta * \neg\mathbf{C}$. By Lemma 3.3, we know $\neg\Delta \in \Gamma_\Sigma^{\mathcal{G}}$. By saturation, we must have $\neg\Delta * \mathbf{C} \in \Gamma_\Sigma^{\mathcal{G}}$ or $\neg\Delta * \neg\mathbf{C} \in \Gamma_\Sigma^{\mathcal{G}}$. The first case contradicts $\Vdash_{\mathcal{G}} \neg\neg\Delta * \neg\mathbf{C}$ while the second case contradicts $\Vdash_{\mathcal{G}} \neg\neg\Delta * \mathbf{C}$. \square

Proof of Lemma 3.8:

Proof. Suppose $\Gamma'_\Sigma \in \mathfrak{Acc}_*$ is a saturated extension of $\Gamma_\Sigma^{\mathcal{G}}$. Assume $\Vdash_{\mathcal{G}} \Delta * \mathbf{C}$ and $\Vdash_{\mathcal{G}} \Delta * \neg \mathbf{C}$ hold and $\Vdash_{\mathcal{G}} \Delta$ does not. By Lemma 3.3, we know $\neg \Delta \in \Gamma_\Sigma^{\mathcal{G}}$. Since $\neg \Delta$ is finite (hence sufficiently Σ -pure), $\neg \Delta \in \Gamma'_\Sigma$. By the model existence theorem for saturated abstract consistency classes (cf. Theorem [5](6.34)), there is a model $\mathcal{M} \in \mathfrak{M}_*$ such that $\mathcal{M} \models \neg \Delta$. By soundness of $\Gamma_\Sigma^{\mathcal{G}}$, we know both $\Delta * \mathbf{C}$ and $\Delta * \neg \mathbf{C}$ must be valid in \mathcal{M} . Since $\mathcal{M} \models \neg \Delta$, we must have $\mathcal{M} \models \mathbf{C}$ and $\mathcal{M} \models \neg \mathbf{C}$, a contradiction. \square

Proof of Lemma 3.10:

Proof. We can argue 0-admissibility of $\mathcal{G}(Inv^-)$ and $\mathcal{G}(weak)$ by induction on derivations. We use the notation $\Vdash_{\mathcal{G}_\beta}^n \Delta$ to indicate there is a derivation with size at most n of Δ . For negation inversion, we need to show $\Vdash_{\mathcal{G}_\beta}^n \Delta * \mathbf{A}$ whenever $\Vdash_{\mathcal{G}_\beta}^n \Delta * \neg \neg \mathbf{A}$. First assume $\neg \neg \mathbf{A}$ is a principal formula of the last rule applied. This is only possible if the last rule is $\mathcal{G}(\neg)$. Examining $\mathcal{G}(\neg)$, we have either $\Vdash_{\mathcal{G}_\beta}^{n-1} \Delta * \mathbf{A}$ or $\Vdash_{\mathcal{G}_\beta}^{n-1} \Delta * \neg \neg \mathbf{A} * \mathbf{A}$. In the first case, we are done. Otherwise, we apply the induction hypothesis to $\Vdash_{\mathcal{G}_\beta}^{n-1} \Delta * \neg \neg \mathbf{A} * \mathbf{A}$ and obtain $\Vdash_{\mathcal{G}_\beta}^{n-1} \Delta * \mathbf{A}$ as desired. Next assume $\neg \neg \mathbf{A}$ is not a principal formula of the last rule. In this case, the application of rule r concludes $\Vdash_{\mathcal{G}_\beta}^n (\Delta' * \neg \neg \mathbf{A}) \cup \Delta_0$ from $\Vdash_{\mathcal{G}_\beta}^{n_i} (\Delta' * \neg \neg \mathbf{A}) \cup \Delta_i$ (with $1 \leq i \leq m$) where Δ_0 contains the principal formulae of the rule application (a singleton unless the rule is $\mathcal{G}(init)$) and $n^1 + \dots + n^m \leq n - 1$. Applying the inductive hypothesis, we have $\Vdash_{\mathcal{G}_\beta}^{n_i} (\Delta' * \mathbf{A}) \cup \Delta_i$ for $1 \leq i \leq m$. Applying rule r we have $\Vdash_{\mathcal{G}_\beta}^n (\Delta' * \mathbf{A}) \cup \Delta_0$. (For the case where r is $\mathcal{G}(\Pi_+^c)$ we use the fact that the same parameters occur in \mathbf{A} and $\neg \neg \mathbf{A}$.)

To prove 0-admissibility of weakening, we generalize the statement to include a parameter renaming (to handle the $\mathcal{G}(\Pi_+^c)$ rule). A parameter renaming θ is a well-typed map from parameters to parameters extended to operate on arbitrary terms. Note that if \mathbf{A} is β -normal, then $\theta(\mathbf{A})$ is also β -normal. Also, if \mathbf{A} is atomic, then $\theta(\mathbf{A})$ is atomic. We prove for any n , Δ , Δ' and parameter renaming θ , if $\Vdash_{\mathcal{G}_\beta}^n \Delta$ and $\theta(\mathbf{A}) \in \Delta'$ for every $\mathbf{A} \in \Delta$, then $\Vdash_{\mathcal{G}_\beta}^n \Delta'$. Applying this with the identity parameter renaming θ , we have 0-admissibility of $\mathcal{G}(weak)$.

Suppose $\Vdash_{\mathcal{G}_\beta}^n \Delta$ and $\theta(\mathbf{A}) \in \Delta'$ for every $\mathbf{A} \in \Delta$. First, assume the last rule application is $\mathcal{G}(\Pi_+^c)$ with principal formula $(\Pi^\alpha \mathbf{G}) \in \Delta$. In this case we know $\Vdash_{\mathcal{G}_\beta}^{n-1} \Delta_0 * (\mathbf{G}c_\alpha) \downarrow_\beta$ where $\Delta_0 * (\Pi \mathbf{G})$ is Δ and c does not occur in any sentence in Δ . Choose a parameter d_α such that d does not occur in any sentence in Δ' . Let θ' be the parameter renaming given by $\theta'(c) := d$ and $\theta'(w) := \theta(w)$ for parameters w other than c . Let Δ'' be $\Delta' * (\theta(\mathbf{G})d) \downarrow_\beta$. For each $\mathbf{A} \in \Delta_0 \subseteq \Delta$, we know $\theta'(\mathbf{A}) \equiv \theta(\mathbf{A}) \in \Delta' \subseteq \Delta''$ (since c does not occur in any sentence in Δ). Also, since c does not occur in \mathbf{G} , $\theta'((\mathbf{G}c) \downarrow_\beta) \equiv (\theta(\mathbf{G})d) \downarrow_\beta \in \Delta''$. Hence we can apply the induction hypothesis with $n - 1$, $\Delta_0 * (\mathbf{G}c) \downarrow_\beta$, Δ'' and θ' to conclude $\Vdash_{\mathcal{G}_\beta}^{n-1} \Delta' * (\theta(\mathbf{G})d_\alpha) \downarrow_\beta$. Since d does not occur in Δ' and $\theta(\Pi \mathbf{G}) \in \Delta'$, we can apply $\mathcal{G}(\Pi_+^d)$ to conclude $\Vdash_{\mathcal{G}_\beta}^n \Delta'$.

Next, assume the last rule applied is $\mathcal{G}(\Pi^C)$. Hence $\Vdash_{\mathcal{G}_\beta}^{n-1} \Delta_0 * \neg (\mathbf{G}\mathbf{C}) \downarrow_\beta$ where $\Delta_0 * \neg(\Pi \mathbf{G})$ is Δ . We apply the induction hypothesis with $n - 1$, $\Delta_0 * (\mathbf{G}\mathbf{C}) \downarrow_\beta$, $\Delta' * \neg (\theta(\mathbf{G}\mathbf{C})) \downarrow_\beta$

and θ to conclude $\Vdash_{\mathcal{G}_\beta}^{n-1} \Delta' * \neg(\theta(\mathbf{GC})) \downarrow_\beta$. Applying the rule $\mathcal{G}(\Pi_-^{\theta(\mathbf{C})})$, we obtain $\Vdash_{\mathcal{G}_\beta}^{n-1} \Delta'$ as desired. (Note that $\theta(\neg\Pi\mathbf{G}) \in \Delta'$.)

Finally, assume the last rule application is not $\mathcal{G}(\Pi_+^c)$ and not $\mathcal{G}(\Pi_-^c)$. Let r be the last rule applied. The rule r concludes $\Vdash_{\mathcal{G}_\beta}^n \Delta$ from $\Vdash_{\mathcal{G}_\beta}^{n^i} \Delta_0 \cup \Delta_i$ where $\Delta_0 \subseteq \Delta$, $1 \leq i \leq m$ and $n^1 + \dots + n^m \leq n - 1$. For each i , we can apply the induction hypothesis with n^i , $\Delta_0 \cup \Delta_i$, $\Delta' \cup \{\theta(\mathbf{A}) \mid \mathbf{A} \in \Delta_i\}$ and θ to conclude $\Vdash_{\mathcal{G}_\beta}^{n^i} \Delta' \cup \{\theta(\mathbf{A}) \mid \mathbf{A} \in \Delta_i\}$. Applying the same rule r we conclude $\Vdash_{\mathcal{G}_\beta}^n \Delta'$. \square

Proof of Theorem 5.3:

Proof. Assume the rules $\mathcal{G}(\mathbf{f})$ and $\mathcal{G}(\Pi_+^c)$ are admissible. If $\neg(\mathbf{G} \doteq^{\alpha \rightarrow \beta} \mathbf{H}) \in \Phi$ and $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_\beta * (\mathbf{G}w \doteq^\beta \mathbf{H}w) \downarrow_\beta$ (with w_α new) holds, then we can show $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_\beta$ holds using $\mathcal{G}(\Pi_+^w)$ and $\mathcal{G}(\mathbf{f})$.

Assume the rule $\mathcal{G}(\mathbf{b})$ is admissible. Suppose $\Phi \in \Gamma_\Sigma^{\mathcal{G}}$, $\neg(\mathbf{A} \doteq^o \mathbf{B}) \in \Phi$, $\Phi * \mathbf{A} * \neg\mathbf{B} \notin \Gamma_\Sigma^{\mathcal{G}}$ and $\Phi * \neg\mathbf{A} * \mathbf{B} \notin \Gamma_\Sigma^{\mathcal{G}}$. By Lemma 3.3, $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_\beta * \neg \mathbf{A} \downarrow_\beta * \mathbf{B} \downarrow_\beta$ and $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_\beta * \mathbf{A} \downarrow_\beta * \neg \mathbf{B} \downarrow_\beta$. Applying $\mathcal{G}(\mathbf{b})$, $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_\beta * (\mathbf{A} \doteq^o \mathbf{B}) \downarrow_\beta$. Applying $\mathcal{G}(\neg)$, $\Vdash_{\mathcal{G}} \neg \Phi \downarrow_\beta$ since $\neg(\mathbf{A} \doteq^o \mathbf{B}) \in \Phi$, contradicting $\Phi \in \Gamma_\Sigma^{\mathcal{G}}$. Thus $\nabla_{\mathbf{b}}$ holds. \square